

LINEAR MOTION GUIDE

1 WON Linear Motion Guide

1. Characteristics

WON Linear Motion Guide is a straight-line motion bearing with the structure in which rolling elements such as balls or rollers softly circulate the inner part of the block and the block can make an infinite straight-line motion along the raceway surface of a rail.

2. Strengths

1) Able to make a precise positioning

Since there is less difference between static friction and kinetic friction as well as in speed-induced friction fluctuation, it excellently responds even to micro-migration, allowing precise positioning.

2) Able to maintain accuracy stably for a long time

Less friction coefficient and wear due to ideal rolling motion allows the stable maintenance of accuracy for a long time.

3) Able to eliminate clearance or increase rigidity by preloading

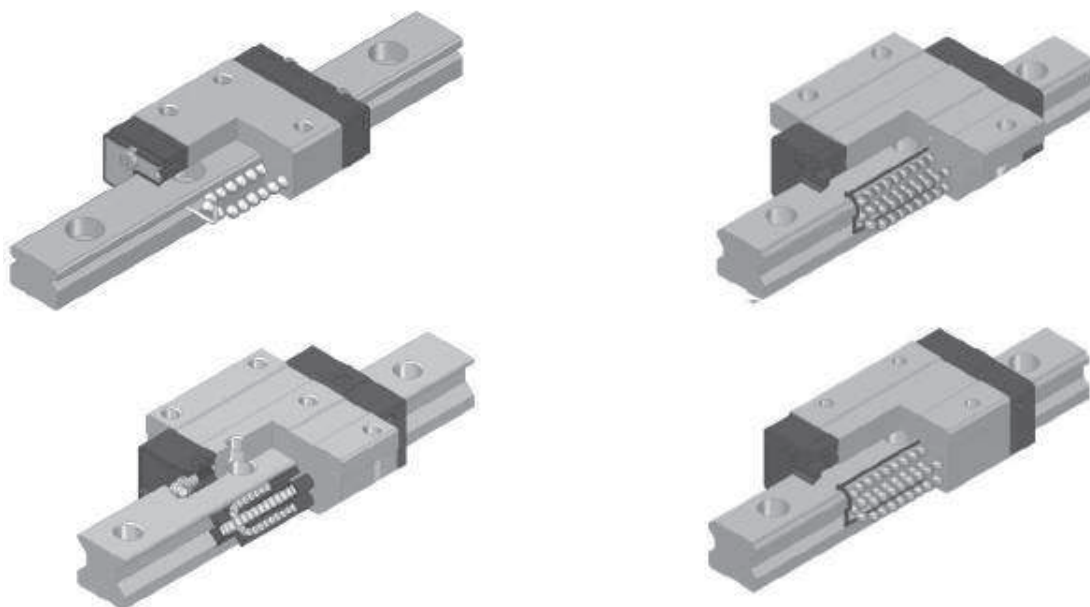
It is possible to eliminate clearance by using rolling elements such as a ball or a roller or increase rigidity of Linear Motion Guide by preloading.

4) Lubrication is simple.

Lubrication is simple but it uses grease or oil which makes it convenient to maintain.

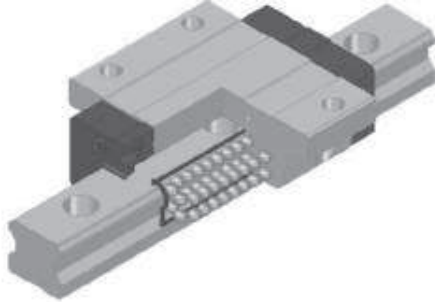
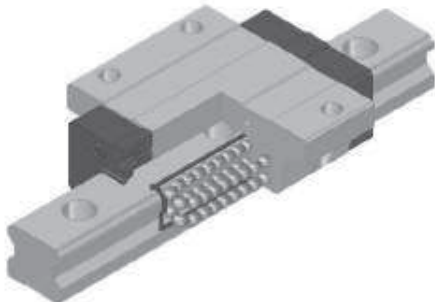
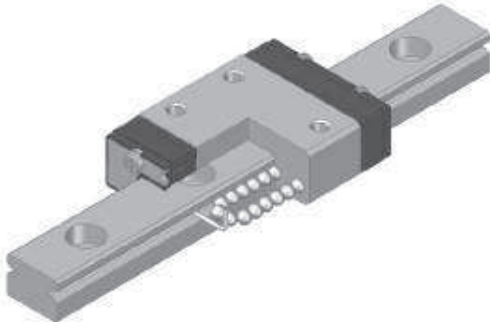
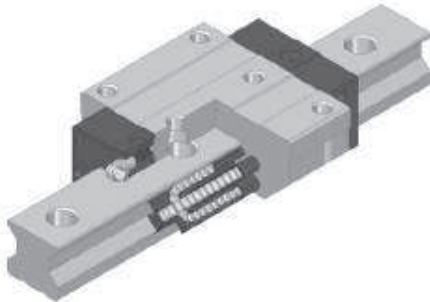
5) Able to compact equipment and save cost for operating electricity

It can be made into compact miniaturized equipment because friction is low despite highly-rigid high-loading, which saves manufacturing costs and energy.



3. Types

WON ST offers various types of Linear Motion guide from miniature types to general ball Linear Motion guide to low-sound linear motion guide to ultra high-rigid roller linear motion guide. Since each supports different shapes and sizes according to service conditions, you can select the optimal linear motion guide to each usage.












Linear Motion Guide		<ul style="list-style-type: none"> ·World standard ball Linear Motion guide ·4-direction equal load type with 40° contact angle ·Great error-absorbing ability with D/F combination ·High-rigid highly accurate straight-line motion through ideal rolling motion
Spacer Chain Linear Motion Guide		<ul style="list-style-type: none"> ·World standard ball Linear Motion guide ·4-direction equal load type with 45° contact angle ·Great error-absorbing ability with D/F combination ·Spacer-enabled retainer type with low noise low dust raise straight-line motion device
Miniature Linear Motion Guide		<ul style="list-style-type: none"> ·Miniature high-rigidity ·Various shapes and sizes ·Highly-durable and reliable compact straight-line motion device
Roller Linear Motion Guide		<ul style="list-style-type: none"> ·Roller-enabled ultra-rigid linear motion guide ·4-direction equal load type with 40° contact angle ·Able to run reliably for a long time through rolling motion having wide contact surface ·High-load, high-rigid, highly accurate straight-line motion

2 Selection of Linear Motion Guide

1. Overview

To select Linear Motion guide, most of all identify detailed requirements and prioritize the requirements to select the Linear Motion Guide suitable for the service conditions.

2. Procedure

1 Identify service conditions	 equipment, maintenance structure, installation space, assembly status, functional requirements, service conditions
2 Select the type of Linear Motion guide	 Select the appropriate type by considering motion condition, load level, rigidity, friction, and assembly
3 Select the model number of Linear Motion guide	 Determine the model number and the quantity of blocks by considering the space and load
4 Calculate load	 Calculate the load in vertical and horizontal directions and moment
5 Calculate equivalent load	 Calculate each load applied to the block by converting it into equivalent load
6 Calculate mean load	 Calculate each load applied to the block and variable load during deceleration by converting them into mean load
7 Calculate static safety factor	 Calculate the static safety factor identified by basic load rating and max. equivalent load and check if it fits for service conditions
8 Calculate life	 Check if it fits for service conditions by calculating load rating and life
9 Review preload & clearance	 Select the preload and clearance suitable for service conditions
10 Determine the class of precision	 Determine the class of precision required by Linear Motion guide while driving
11 Lubrication, dust proof, surface handling	 Select lubricant suitable for the environment using grease, oil, and special grease lubrication and select seal for dust proof / determine the method of surface handling for rust prevention and low dust raise
12 Complete selection	 Complete the decision of final specifications of Linear Motion guide

3 Life Calculation

1. Load rating and life

(1) Life

If external load is applied to Linear Motion guide while driving, fatigue fracture occurs by stress created as load is repeatedly applied to the raceway surface and rolling elements, and flaking -peeling off in scale-like flakes arises. A total driving distance until flaking occurs due to initial fatigue fracture is the life of a linear motion guide.

- Defects may occur in Linear Motion guide earlier than when flaking normally occurs due to wear or fatigue in the following cases:

- Excess load by the imprecise assembly following a difference in temperature or tolerance
- If Linear Motion guide is contaminated with foreign substance
- Driving with insufficient lubrication
- Reciprocating motion in a very short distance in the form of vibration or wave during the halt or drive
- Excessive load to Linear Motion guide
- Deformation of plastic end-plate

2) Rating fatigue life L

Generally Linear Motion guide does not always have same life even though the products are manufactured in the same way because of the difference in scattering of raw material's original fatigue. For this reason, the reference value of life is defined as the rating fatigue life which is a total driving distance that flaking does not occur in 90% of Linear Motion guides in a group when having them run under the same conditions by grouping multiple Linear Motion guides with same specifications into a group.

When using a ball

$$L = \left(\frac{f_H \cdot f_T \cdot f_C}{f_w} \cdot \frac{C}{P_c} \right)^3 \times 50$$

When using a roller

$$L = \left(\frac{f_H \cdot f_T \cdot f_C}{f_w} \cdot \frac{C}{P_c} \right)^{\frac{10}{3}} \times 100$$

(3) Basic dynamic load rating C

Basic dynamic load rating is Linear Motion guide's bearing of load which represents an applicable constant load in direction and magnitude when the rated life is 50KM. The reference value of WON Linear Motion Guide's basic dynamic load rating is 50KM (ball type) and 100KM (roller type). It is used for calculating Linear Motion guide's life while driving under constant load in magnitude from the center of a block to bottom.

Each value of basic dynamic load rating (C) is stated in the catalogue.

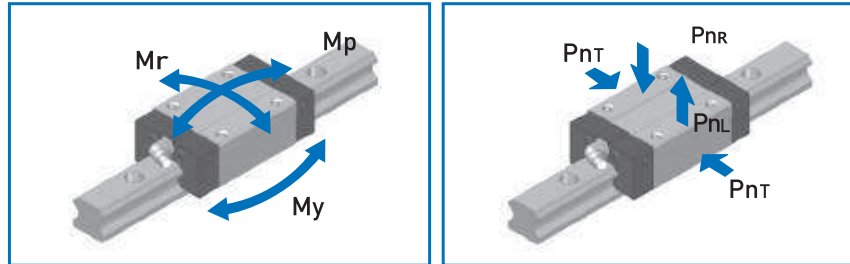
(4) Basic static load rating C₀

If Linear Motion guide is applied by excessive load or attached instantly by big impact load, a partially permanent deformation occurs between a rolling element and the raceway surface. If deformation reaches to a certain extent, it hinders a smooth driving. Basic static load rating is defined as the constant static load in direction and magnitude with the permanent deformation that occurs between a rolling element like a ball or a roller and the raceway surface of block and rail 0.0001 times bigger than the diameter of the rolling element. In Linear Motion guide, it is the load applied from top to bottom based on the center of the block. Each value of basic static load rating (C₀) is stated in the specification table.

(5) Static allowable moment M_0

Moment load can be applied to Linear Motion guide. Here, a ball or a roller both at the ends is most stressed due to the stress distribution of a ball or a roller which is the rolling element inside Linear Motion guide. Static allowable moment refers to the constant moment load in direction and magnitude when the permanent deformation between a ball or a roller applied with the biggest stress and the raceway surface of a block or a rail is less than 0.0001 of the diameter of the rolling element. Moment values of three directions (M_p , M_y , M_r) are stated in the specification sheet. Static allowable moment (M_0) and static moment load rating (M_p) can be reviewed by applying safety factor (f_s).

Directions of load and moment



$$f_s = \frac{M_p}{M_0}$$

2. Load Calculation

Linear Motion guide bears basic dynamic load rating (C) and basic static load rating (C_0). But compression load applied from top to down due to inertia force created by the center of gravity, positioning thrust, acceleration, cutting force, and deceleration as well as various loads including tensile load, horizontal load, and moment load can be applied to Linear Motion guide depending on the service conditions. In this case, load of Linear Motion guide changes. When selecting Linear Motion guide, it is required to review these conditions and calculate proper load.

3. Service Condition Setting

Service conditions necessary for calculating the load and life of Linear Motion guide :

- | | | | | |
|---|----------------------|--|-----------------|---------------------------------|
| ① Mass : | m (kg) | ⑥ Velocity diagram | Velocity : | V (mm/s) |
| ② Applicable load direction | | | Time constant : | t_n (s) |
| ③ Point of application :
(center of gravity) | l_2, l_3, h_1 (mm) | | Acceleration : | α_n (mm/s ²) |
| ④ Point of thrust : | l_4, h_2 (mm) | ⑦ No. of reciprocating motion/second : | | N_1 (min ⁻¹) |
| ⑤ Composition of Linear Motion guide :
(No. of block & rail) | l_0, l_1 (mm) | ⑧ Stroke : | | L_s (mm) |
| | | ⑨ Avg. velocity : | | V_m (m/s) |
| | | ⑩ Required life : | | L_h (h) |

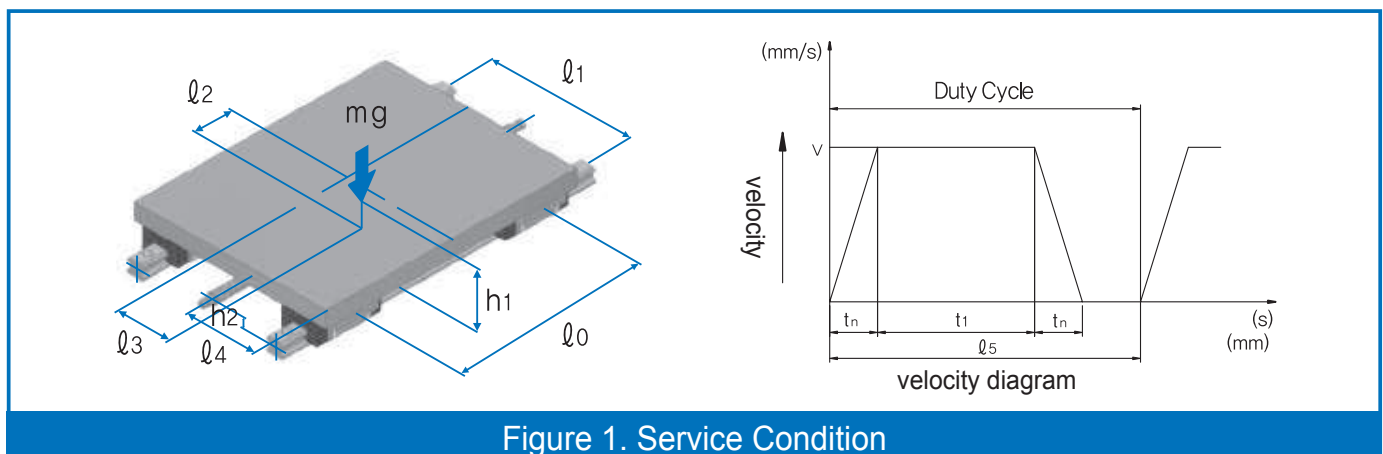


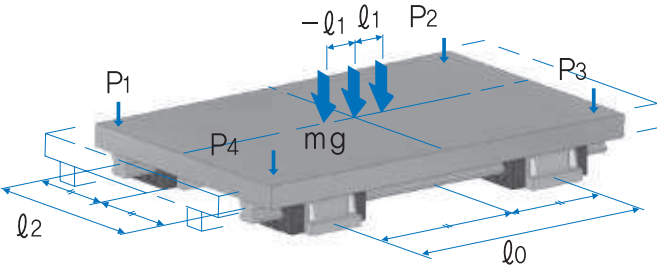
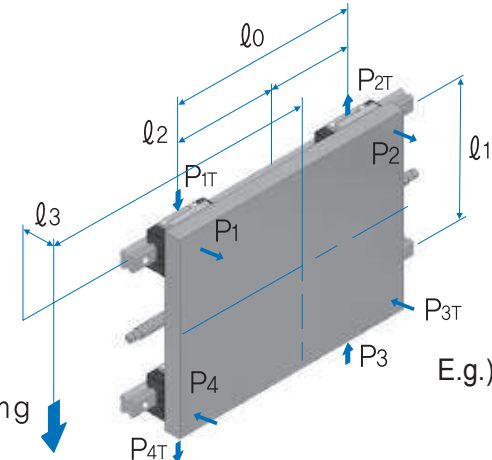
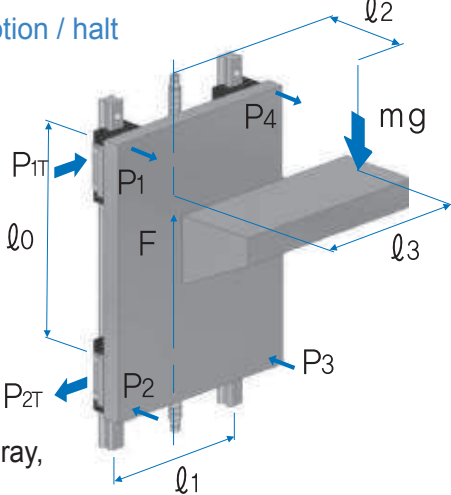
Figure 1. Service Condition

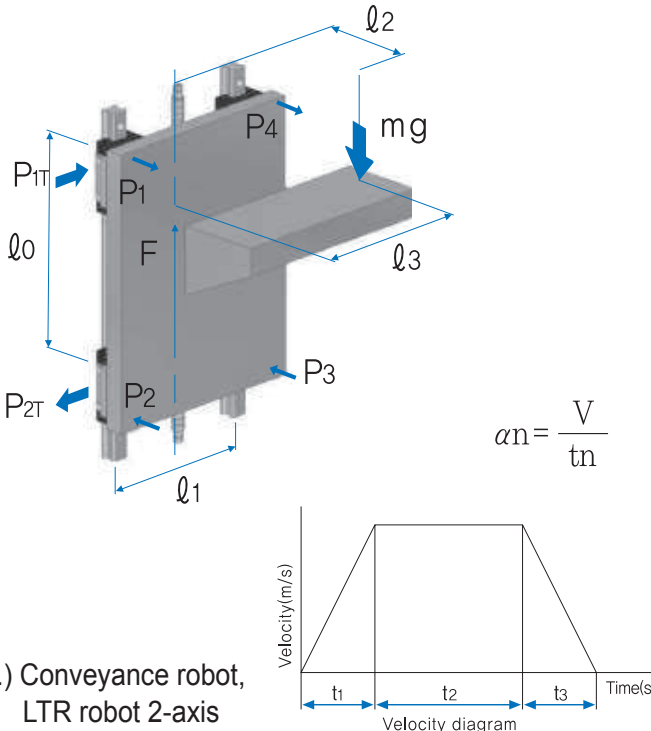
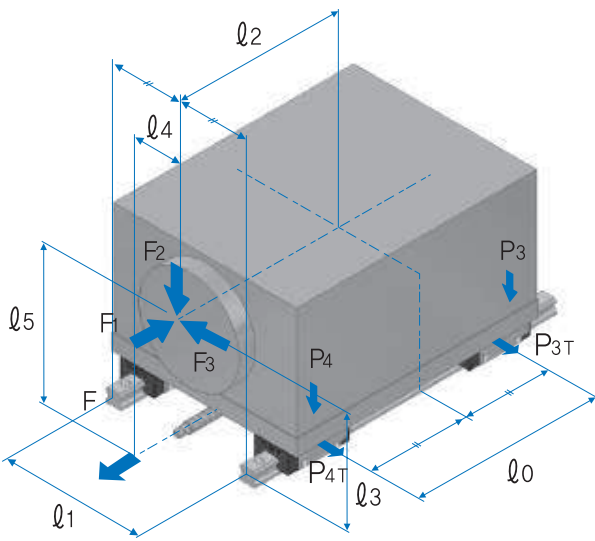
4. Load Calculation Formula

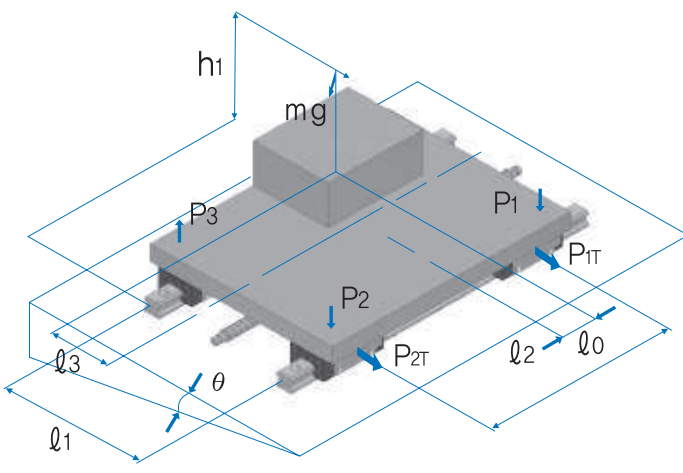
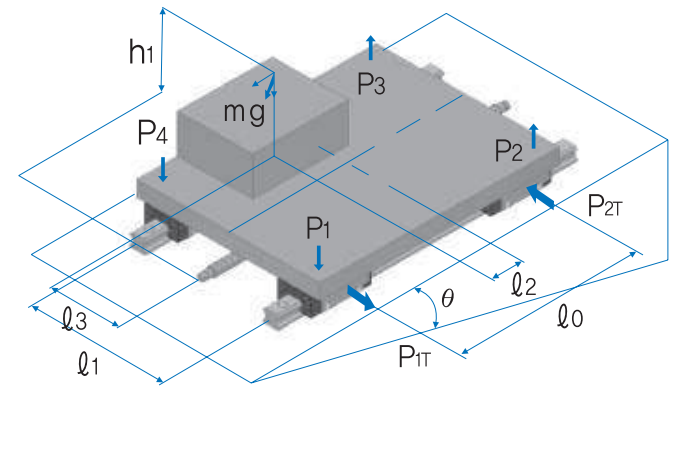
Load applied to Linear Motion guide changes due to external forces such as the center of gravity, position of thrust, acceleration, and cutting resistance. To select Linear Motion guide, you should calculate load applied to the block by fully considering the conditions below.

m : Mass	(kg)	g : Acceleration of gravity(g : 9.8m/s ²)	(m/s ²)
ℓ _n : Distance	(mm)	V : Velocity	(m/s)
F _n : Thrust	(N)	t _n : Time constant	(s)
P _n : Load (vertical, reverse-vertical)	(N)	a _n : Acceleration	(m/s ²)
P _{NT} : Load (horizontal)	(N)		

Case	Service Conditions	Load Calculation Formula
1	Block move Horizontal / uniform motion / halt 	$P_1 = \frac{mg}{4} + \frac{mg \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot l_3}{2 \cdot l_1}$ $P_2 = \frac{mg}{4} - \frac{mg \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot l_3}{2 \cdot l_1}$ $P_3 = \frac{mg}{4} - \frac{mg \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot l_3}{2 \cdot l_1}$ $P_4 = \frac{mg}{4} + \frac{mg \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot l_3}{2 \cdot l_1}$
2	Block move Overhang-horizontal / uniform motion / halt 	$P_1 = \frac{mg}{4} + \frac{mg \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot l_3}{2 \cdot l_1}$ $P_2 = \frac{mg}{4} - \frac{mg \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot l_3}{2 \cdot l_1}$ $P_3 = \frac{mg}{4} - \frac{mg \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot l_3}{2 \cdot l_1}$ $P_4 = \frac{mg}{4} + \frac{mg \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot l_3}{2 \cdot l_1}$

Case	Service Conditions	Load Calculation Formula
3	<p>Rail move Horizontal / uniform motion / halt</p>  <p>E.g.) X or Z axis Loader/unLoader</p>	$P_1 = \frac{mg \cdot \cos \theta}{4} + \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} + \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_1}$ $P_{1T} = \frac{mg \cdot \sin \theta}{4} + \frac{mg \cdot \sin \theta \cdot l_2}{2 \cdot l_0}$ $P_2 = \frac{mg \cdot \cos \theta}{4} - \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} + \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_1}$ $P_{2T} = \frac{mg \cdot \sin \theta}{4} - \frac{mg \cdot \sin \theta \cdot l_2}{2 \cdot l_0}$
4	<p>Block move Wall installation / uniform motion / halt</p>  <p>E.g.) Gantry-type device Y-axis drive</p>	$P_1 \sim P_4 = \frac{mg \cdot l_3}{2 \cdot l_1}$ $P_{1T} = P_{4T} = \frac{mg}{4} + \frac{mg \cdot l_2}{2 \cdot l_0}$ $P_{2T} = P_{3T} = \frac{mg}{4} - \frac{mg \cdot l_2}{2 \cdot l_0}$
5	<p>Block move Vertical / uniform motion / halt</p>  <p>E.g.) Industrial robot Z-axis Auto-painting spray, lifter</p>	$P_1 \sim P_4 = \frac{mg \cdot l_2}{2 \cdot l_0}$ $P_{1T} \sim P_{4T} = \frac{mg \cdot l_3}{2 \cdot l_0}$

Case	Service Conditions	Load Calculation Formula
6	<p>Block move Vertical/moment of inertia</p>  <p>E.g.) Conveyance robot, LTR robot 2-axis</p>	<p>Acceleration</p> $P_1=P_4 = -\frac{m(g-\alpha_1)l_2}{2 \cdot l_0}$ $P_2=P_3 = \frac{m(g-\alpha_1)l_2}{2 \cdot l_0}$ $P_{1T}=P_{4T} = \frac{m(g-\alpha_1)l_3}{2 \cdot l_0}$ $P_{2T}=P_{3T} = -\frac{m(g-\alpha_1)l_3}{2 \cdot l_0}$ <p>Uniform motion</p> $P_1=P_4 = -\frac{mg \cdot l_2}{2 \cdot l_0}$ $P_2=P_3 = \frac{mg \cdot l_2}{2 \cdot l_0}$ $P_{1T}=P_{4T} = \frac{mg \cdot l_3}{2 \cdot l_0}$ $P_{2T}=P_{3T} = -\frac{mg \cdot l_3}{2 \cdot l_0}$ <p>Deceleration</p> $P_1=P_4 = -\frac{m(g-\alpha_3)l_2}{2 \cdot l_0}$ $P_2=P_3 = \frac{m(g-\alpha_3)l_2}{2 \cdot l_0}$ $P_{1T}=P_{4T} = \frac{m(g-\alpha_3)l_3}{2 \cdot l_0}$ $P_{2T}=P_{3T} = -\frac{m(g-\alpha_3)l_3}{2 \cdot l_0}$
7	<p>Block move Cutting load / complex external load</p>  <p>E.g.) Machine tool, CNC shelf, machining center, NC milling machine</p>	<p>F1 application</p> $P_1=P_4 = -\frac{F_1 \cdot l_5}{2 \cdot l_0}$ $P_2=P_3 = \frac{F_1 \cdot l_5}{2 \cdot l_0}$ $P_{1T}=P_{4T} = \frac{F_1 \cdot l_4}{2 \cdot l_0}$ $P_{2T}=P_{3T} = -\frac{F_1 \cdot l_4}{2 \cdot l_0}$ <p>F2 application</p> $P_1=P_4 = \frac{F_2}{4^+} - \frac{F_2 \cdot l_2}{2 \cdot l_0}$ $P_2=P_3 = \frac{F_2}{4^-} + \frac{F_2 \cdot l_2}{2 \cdot l_0}$ <p>F3 application</p> $P_1=P_4 = -\frac{F_3 \cdot l_3}{2 \cdot l_1}$ $P_2=P_3 = \frac{F_3 \cdot l_3}{2 \cdot l_1}$ $P_{1T}=P_{4T} = \frac{F_3}{4^-} - \frac{F_3 \cdot l_2}{2 \cdot l_0}$ $P_{2T}=P_{3T} = \frac{F_2}{4^-} + \frac{F_3 \cdot l_2}{2 \cdot l_0}$

Case	Service Conditions	Load Calculation Formula
8	<p>Block move Moment load in case of application to side slope / cutting load</p>  <p>E.g.) CNC shelf, reciprocating carriage</p>	$P_1 = \frac{mg \cdot \cos \theta}{4} + \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} + \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_1}$ $P_{1T} = \frac{mg \cdot \sin \theta}{4} + \frac{mg \cdot \sin \theta \cdot l_2}{2 \cdot l_0}$ $P_2 = \frac{mg \cdot \cos \theta}{4} - \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} + \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_1}$ $P_{2T} = \frac{mg \cdot \sin \theta}{4} - \frac{mg \cdot \sin \theta \cdot l_2}{2 \cdot l_0}$ $P_3 = \frac{mg \cdot \cos \theta}{4} - \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} - \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_1}$ $P_{3T} = \frac{mg \cdot \sin \theta}{4} + \frac{mg \cdot \sin \theta \cdot l_2}{2 \cdot l_0}$ $P_4 = \frac{mg \cdot \cos \theta}{4} + \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} - \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_1}$ $P_{4T} = \frac{mg \cdot \sin \theta}{4} + \frac{mg \cdot \sin \theta \cdot l_2}{2 \cdot l_0}$
9	<p>Block move Moment load in case of application to front slope / cutting load</p>  <p>E.g.) CNC shelf, tool rest</p>	$P_1 = \frac{mg \cdot \cos \theta}{4} + \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} + \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_0}$ $P_{1T} = \frac{mg \cdot \sin \theta \cdot l_3}{2 \cdot l_0}$ $P_2 = \frac{mg \cdot \cos \theta}{4} - \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} - \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} - \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_0}$ $P_{2T} = -\frac{mg \cdot \sin \theta \cdot l_3}{2 \cdot l_0}$ $P_3 = \frac{mg \cdot \cos \theta}{4} - \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} - \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_0}$ $P_{3T} = -\frac{mg \cdot \sin \theta \cdot l_3}{2 \cdot l_0}$ $P_4 = \frac{mg \cdot \cos \theta}{4} + \frac{mg \cdot \cos \theta \cdot l_2}{2 \cdot l_0} + \frac{mg \cdot \cos \theta \cdot l_3}{2 \cdot l_1} + \frac{mg \cdot \sin \theta \cdot h_1}{2 \cdot l_0}$ $P_{4T} = \frac{mg \cdot \sin \theta \cdot l_3}{2 \cdot l_0}$

Case	Service Conditions	Load Calculation Formula
10	<p>Block move Horizontal application / inertia force application</p> <p>E.g.) Industrial robot carriage, LCD test device</p>	<p>Acceleration</p> $P_{1}=P_{4}=\frac{mg}{4}-\frac{m \cdot \alpha_{1} \cdot l_{2}}{2 \cdot l_{0}}$ $P_{2}=P_{3}=\frac{mg}{4}+\frac{m \cdot \alpha_{1} \cdot l_{2}}{2 \cdot l_{0}}$ $P_{1T} \sim P_{4T}=\frac{m \cdot \alpha_{1} \cdot l_{3}}{2 \cdot l_{0}}$ <p>Constant velocity</p> $P_{1} \sim P_{4}=\frac{mg}{4}$ <p>Deceleration</p> $P_{1}=P_{4}=\frac{mg}{4}+\frac{m \cdot \alpha_{3} \cdot l_{2}}{2 \cdot l_{0}}$ $P_{2}=P_{3}=\frac{mg}{4}-\frac{m \cdot \alpha_{3} \cdot l_{2}}{2 \cdot l_{0}}$ $P_{1T} \sim P_{4T}=\frac{m \cdot \alpha_{3} \cdot l_{3}}{2 \cdot l_{0}}$

5. Equivalent Load Calculation

There are diverse kinds of load applied to Linear Motion guide, such as compression load in vertical direction, tensile load, horizontal load, moment load, etc. There is also combined load of them and sometimes the magnitude and direction of load change. Since it is hard to calculate the variable load when calculating the life of Linear Motion guide, it is required to use equivalent load which is converted to compression load or tensile load in vertical direction in order to produce life or static safety factor.

6. Equivalent Load Calculation Formula

If Linear Motion guide bears vertical compression load or tensile load or horizontal load simultaneously, or the magnitude or direction of load changes, equivalent load is calculated using the following formula.

$$P_E(\text{equivalent load}) = P_n + P_{nT}$$

P_n : Compression load
 P_{nT} : Horizontal load

P_n : Compression load
 P_L : Tensile load
 P_{nT} : Horizontal load
 M_p : Pitching moment
 M_y : Yawing moment
 M_r : Rolling moment

Figure 2.

7. Static Safety Factor Calculation

Unexpected big load may be applied to Linear Motion guide due to inertia force caused by vibration impact or quick braking and moment load of mechanical structure. When selecting Linear Motion guide, static safety factor must be taken into account to be ready for such load. Static safety factor (f_s) is shown in value obtained by dividing basic static load rating by the calculated load. To see the baseline of static safety factor by service condition, please refer to Table 1-1. and Table 1-2.

Table 1-1. Baseline of static safety factor(f_s)

Type of rolling element	Service condition	Static safety factor (f_s)
Ball	There is no vibration and impact.	1.0 ~ 1.5
	Great travel performance is needed.	1.5 ~ 2.0
	There are moment load, violation, and impact.	2.5 ~ 7.0
Roller	There is no vibration and impact.	2.0 ~ 3.0
	Great travel performance is needed.	3.0 ~ 5.0
	There are moment load, violation, and impact.	4.0 ~ 7.0

Table 1-2.

If compression load is big	$\frac{f_H \cdot f_T \cdot f_C \cdot C_0}{P_n} \geq f_s$
If tensile load is big	$\frac{f_H \cdot f_T \cdot f_C \cdot C_{0L}}{P_L} \geq f_s$
If horizontal load is big	$\frac{f_H \cdot f_T \cdot f_C \cdot C_{0T}}{P_{nT}} \geq f_s$

f_s : Static safety factor

C_0 : Basic static load rating(vertical)

C_{0L} : Basic static load rating(reverse-vertical)

C_{0T} : Basic static load rating(horizontal)

P_n : Calculated load(vertical)

P_L : Calculated load (reverse-vertical) (N)

P_{nT} : Calculated load (horizontal) (N)

f_H : Hardness factor

f_T : Temperature factor

f_C : Contact factor

8. Mean Load Calculation

Load applied to the block of Linear Motion guide is not constant, but differs according to service conditions. Here the load that becomes equal to life under variable load is used. This is called mean load. If the load applied to block is changed due to external condition, it is required to calculate life as mean load that includes various conditions as below. If load applied to block varies with different conditions, life should be calculated by including this variable load condition. Mean load (Pm) refers to constant load that becomes equal to life under this variable load when the load applied to block changes with various conditions while traveling.

$$P_m = \sqrt[i]{\frac{1}{L} \cdot \sum_{n=1}^n (P_n^i \cdot L_n)}$$

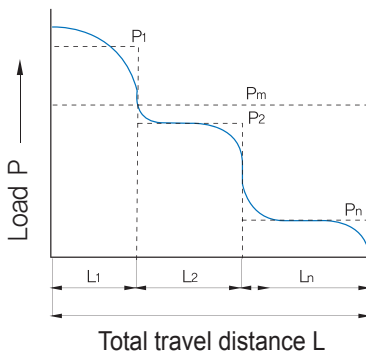
- Pm : Mean load (N)
- Pn : Variable load (N)
- L : Total travel distance (mm)
- Ln : Travel distance by loading Pn (mm)
- i : Ball - 3, Roller - 10/3

Note) the formula above or formula (1) below is applied to a ball.

1) Change in phase

$$P_m = \sqrt[i]{\frac{1}{L} (P_1^i \cdot L_1 + P_2^i \cdot L_2 + \dots + P_n^i \cdot L_n)} \dots (1)$$

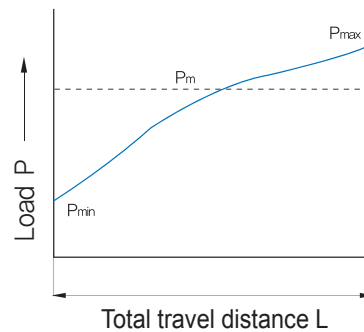
- Pm : Mean load (N)
- Pn : Variable load (N)
- L : Total travel distance (mm)
- Ln : Travel distance by loading Pn (mm)



2) Change monotonously

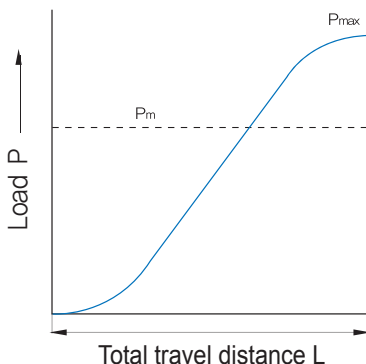
$$P_m \doteq \frac{1}{3} (P_{min} + 2 \cdot P_{max}) \dots (2)$$

- Pmin : Minimum load (N)
- Pmax : Maximum load (N)

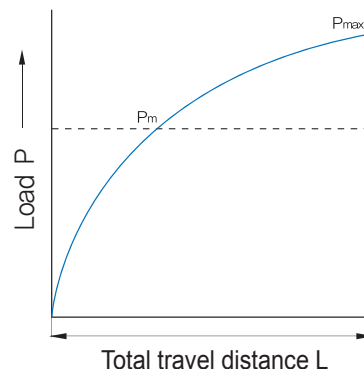


3) Change in a sine curve

a) $P_m \doteq 0.65 \max \dots (3)$



b) $P_m \doteq 0.75 \max \dots (4)$



9. Rating Life Calculation

Rating life needs to be calculated because Linear Motion guide's life differs even under same working conditions. Rating life of Linear Motion guide is the total travel distance that a Linear Motion guide system composed of a certain number of units can drive until flaking does not occur in 90% of the raceway surface or rolling elements after being run under same working conditions. If a ball or a roller is used as a rolling element, rating life can be calculated using the following formula.

▶ Calculation formula of the rating life of ball-enabled Linear Motion guide

$$L = \left(\frac{f_H \cdot f_T \cdot f_C}{f_w} \cdot \frac{C}{P_c} \right)^3 \times 50$$

L	: Rating life	(km)
C	: Basic dynamic load rating	(N)
P _c	: Calculated load	(N)
f _H	: Hardness factor	See Fig. 3
f _T	: Temperature factor	See Fig. 4
f _C	: Contact factor	See Table 2
f _w	: Load factor	See Table 3

▶ Calculation formula of the rating life of roller-enabled Linear Motion guide

$$L = \left(\frac{f_H \cdot f_T \cdot f_C}{f_w} \cdot \frac{C}{P_c} \right)^{\frac{10}{3}} \times 100$$

L	: Rating life	(km)
C	: Basic dynamic load rating	(N)
P _c	: Calculated load	(N)
f _H	: Hardness factor	See Fig. 3
f _T	: Temperature factor	See Fig. 4
f _C	: Contact factor	See Table 2
f _w	: Load factor	See Table 3

▶ If the length of stroke and the number of reciprocating motion are constant, life time can be calculated using rating life (L) by the formula below.

$$L_h = \frac{L \times 10^6}{2 \times l_s \times n_1 \times 60}$$

L _h	: Life time	(N)
l _s	: Length of stroke	(mm)
n ₁	: No. of reciprocating motion per minute	(mm ⁻¹)

1) Hardness factor (f_H)

To realize the best performance of Linear Motion guide, the proper hardness and depth should be maintained between the block contacting a rolling element (ball or roller) and the raceway surface of rail.

WON Linear Motion guide has HRC58-64 surface hardness, so there is no need to consider hardness factor. But if the hardness is lowered than baseline, Linear Motion guide's load capacity decreases so hardness factor needs to be reflected in calculating life.

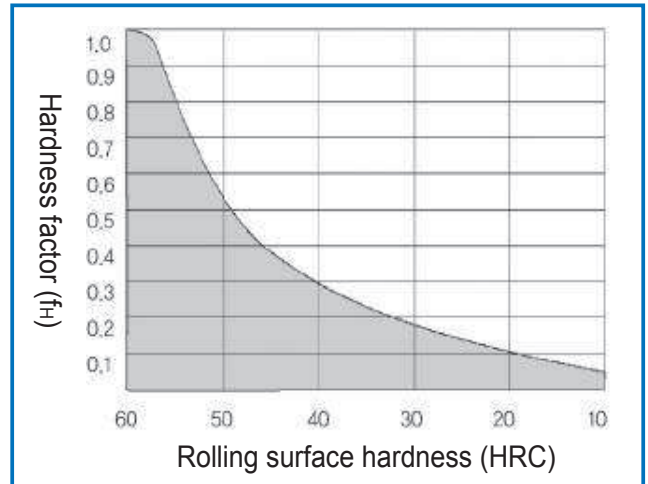


Figure 3. Hardness factor (f_H)

2) Temperature factor (f_T)

If high temperature over 100°C is applied to Linear Motion guide, temperature factor (f_T) needs to be taken into account when selecting Linear Motion guide. WON Linear Motion guide must be used at less than 80°C. But you have to use it at over 80°C, please use a high-temp Linear Motion guide - WON ST's specially customized product.

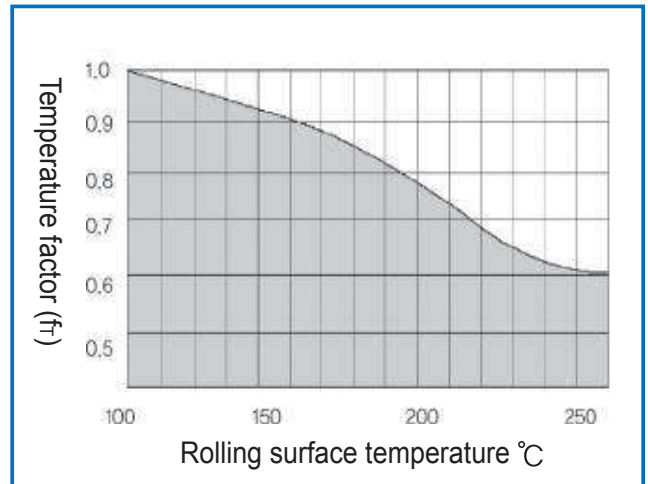


Figure 4. Temperature factor (f_T)

Note) In ambient temperature of over 80°C, materials for seal, end plate, and support plate should be changed to the specifications for high temperature.

3) Contact factor (f_c)

If over two blocks of Linear Motion guide are closely assembled, since uniform load may not be applied to blocks due to difference among mounting surfaces, you have to multiply basic static load rating (C) and basic dynamic load rating (C_0) by contact factor shown in Table 2.

Table 2.

No. of blocks contacted	Contact factor (f_c)
2	0.81
3	0.72
4	0.66
5	0.61
Over 6	0.6
Common use	1.0

4) Load factor (f_w)

Generally the static load applied to the block of Linear Motion guide can be calculated by formula. But the load applied to the block while running the machine tends to come from vibration or impact. Therefore, you have to consider load factor (f_w) shown in Table 3 for the vibration or impact load during the speedy running of the machine. It can be calculated by dividing the basic dynamic load rating of Linear Motion guide by load factor (f_w).

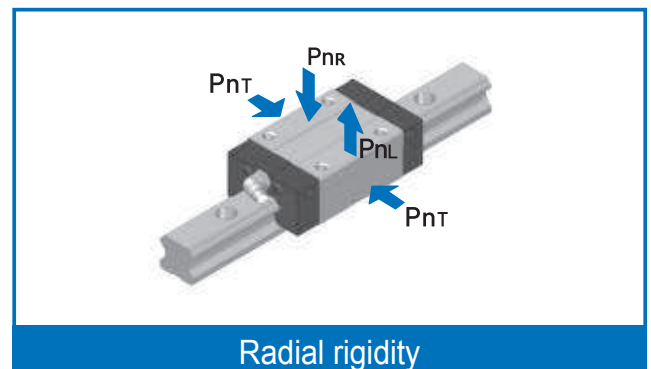
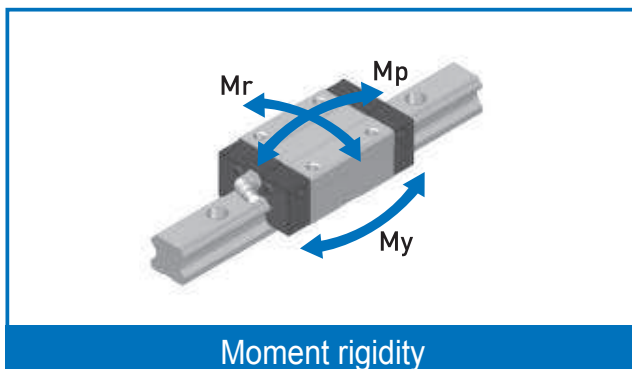
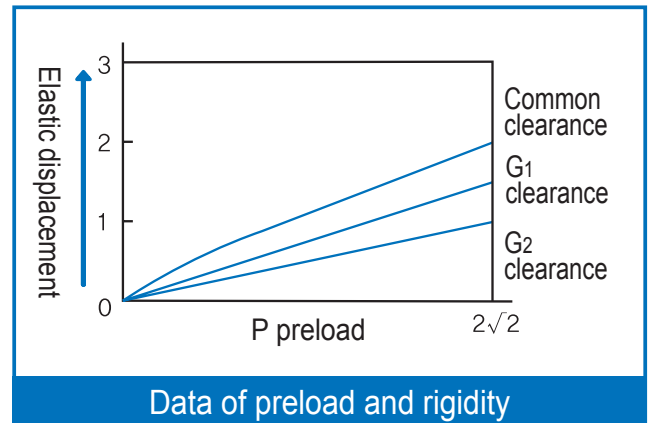
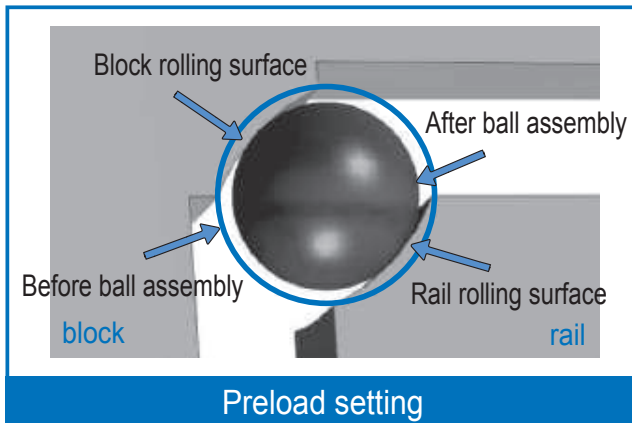
Table 3.

External condition	Service conditions	Load factor (f_w)
Low	There is no external vibration or impact due to the smooth running of machine at mild speed.	1.0 ~ 1.3
Moderate	There is moderate external vibration or impact due to the running of machine at low speed.	1.2 ~ 1.5
Big	There is strong vibration or impact due to the running of machine at fast speed.	1.5 ~ 2.0
Very big	There is strong vibration or impact due to the running of machine at very fast speed.	2.0 ~ 4.0

4 Rigidity & Preload

1. Preload

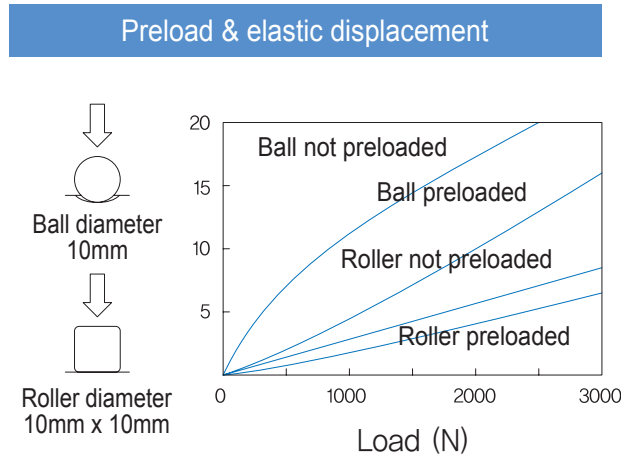
Linear Motion guide is preloaded in a way that improves mechanical precision by eliminating clearance using the rolling element (ball or roller) inserted into the space between rail and the block or in a way that applies load to the rolling element in advance by inserting the rolling element larger in size than the clearance of raceway between rail and the block. This process will enhance the rigidity of Linear Motion guide and lessen the displacement level caused by external load.



2. Radial Clearance

Radial clearance refers to the total travel distance in a radial direction from the center of the block of Linear Motion guide when mild load is applied to the block up and down from the center part of the rail length after the block is assembled in the rail which is then fixed to base.

Radial clearance is usually classified into common clearance (no symbol), G₁ clearance (light preload), G₂ clearance (heavy load), and G_s clearance (special preload), and are optional depending on usage. The values are standardized by form.



	Preload type	Preload symbol	Preload
H	Moderate	No symbol	0 ~ 0.03 x C
	Light	G ₁	0.04 ~ 0.08 x C
	Heavy	G ₂	0.09 ~ 0.13 x C
S	Moderate	No symbol	0 ~ 0.03 x C
	Light	G ₁	0.03 ~ 0.05 x C
	Heavy	G ₂	0.06 ~ 0.08 x C

Table 4. Service condition for radial clearance (preload)

Type	Preload status	Symbol	Service Conditions	Use
1. Moderate	Plus-minus clearance	No (1)	<ul style="list-style-type: none"> ·Load is applied in uniform direction and smooth running is needed. ·There is almost no vibration or impact and precise running is required. 	Welding machine, textile machinery, packaging machinery, various conveyors, medical equipment, woodworking machine, glass cutting machine, take-out robots, ATC, winding machine
2. Light	Minus clearance in small amount	G ₁ (2)	<ul style="list-style-type: none"> ·There is a little vibration or impact and moment load. ·Light load is applied, yet high precision is required. 	Various industrial robots, measuring equipment, inspection equipment, 3D processor, laser processor, PCB drilling machine, various assembling machine, electric spark machine, punching press
3. Heavy	Minus clearance in large amount	G ₂ (3)	<ul style="list-style-type: none"> ·There is mild impact load or overhang load and moment load. Rigidity and high precision are required. 	CNC shelf, machining center, milling machine, grinding machine, tapping center, drilling machine, hobbing machine, various special equipment
4. Special	Minus clearance in small or large amount	G _s (4)	<ul style="list-style-type: none"> ·With smaller clearance than that of G₁ preload, light and precise operation is required. 	No preload, ultra-light preload, larger-than-moderate preload, special preload customized to user's conditions, special processing machine for heavy-duty cutting

- Note (1) No clearance or very small clearance.
 (2) Very small minus clearance.
 (3) Quiet large minus clearance to enhance rigidity
 (4) Preload below G₁ or over G₂ to meet service conditions

Table 5. Radial clearance of H & S Series

Unit : μm

Model No.		Symbol		
		Moderate	Light preload	Heavy preload
		No symbol	G ₁	G ₂
H15	S15	-4 ~ +2	-12 ~ -4	-
H20	S20	-5 ~ +2	-14 ~ -5	-23 ~ -14
H25	S25	-6 ~ +3	-16 ~ -6	-26 ~ -16
H30	-	-7 ~ +4	-19 ~ -7	-31 ~ -19
H35	-	-8 ~ +4	-22 ~ -8	-35 ~ -22
H45	-	-10 ~ +5	-25 ~ -10	-40 ~ -25
H55	-	-12 ~ +5	-29 ~ 12	-46 ~ -29

Table 6. Radial clearance of M & MB Series

Unit : μm

Model No.		Symbol	
		Moderate	Light preload
		No symbol	G ₁
M5	MB5	0 ~ +1.5	-1 ~ 0
M7	MB7	-2 ~ +2	-3 ~ 0
M9	MB9	-2 ~ +2	-4 ~ 0
M12	MB12	-3 ~ +3	-6 ~ 0
M15	MB15	-5 ~ +5	-10 ~ 0
M20	-	-7 ~ +7	-14 ~ 0

Table 7. Radial clearance of R Series

Unit : μm

Model No.		Symbol		
		Moderate	Light preload	Heavy preload
		No symbol	G ₁	G ₂
R35		-2 ~ -1	-3 ~ -2	-5 ~ -3
R45		-2 ~ -1	-3 ~ -2	-5 ~ -3
R55		-2 ~ -1	-4 ~ -2	-6 ~ -4

5 Friction

1. Friction

Linear Motion guide's friction resistance occurs to the level of 1/20~1/40 compared to existing sliding guide since the rolling element (ball or roller) is assembled between the rail and the block which is the raceway surface. Also starting torque is low because the difference between static friction and kinetic friction is very small. Its low power loss and temperature rise in the part of linear motion are of advantage to speedy operation. Its high conformability and response realize the highly precise positioning.

2. Friction Coefficient

Friction resistance of Linear Motion guide relies on the load applied to Linear Motion guide, speed, lubrication or form. In case of light load or high-speedy motion, lubrication or seal is the main cause of friction resistance. In case of heavy load or slow motion, the magnitude of load affects friction resistance.

$$F = \mu P$$

F : Friction resistance (N)
 μ : Kinetic friction factor
 P : Load (N)

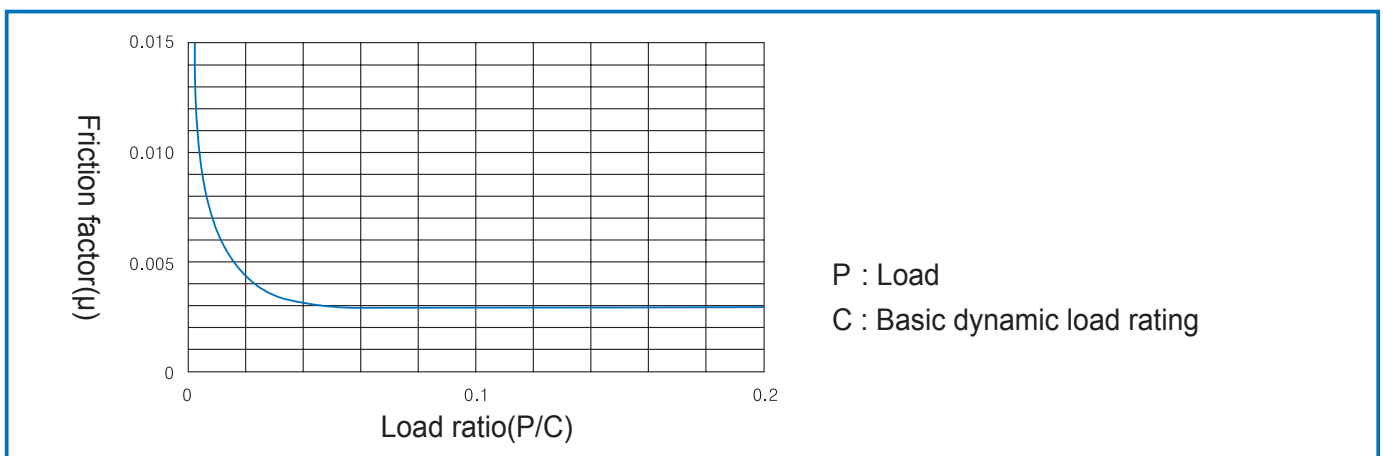


Figure 5. Relation between load ratio and friction factor

Common friction factors of various operating systems are shown in a table below and applied in case of proper lubrication or assembly and normal load.

Type of operating system	Major model number	Friction factor μ
Linear Motion Guide	H, H-S, S, S-S, M, MB	0.002 ~ 0.003
	R	0.001 ~ 0.002
Ball Spline	WLS, WSP	0.002 ~ 0.003
Super Ball Bushing / Linear Ball Bushing	SB, SBE, LM, LME	0.001 ~ 0.003
Cross Roller Guideway	WRG	0.001 ~ 0.0025

6 Precision

1. Precision Specification

The degree of travel of Linear Motion guide is measured as below. (See Figure 6.)

- Tighten rail to the mounting surface of the bed using a bolt at the prescribed torque.
- Draw a measuring jig right up against the datum plane of the block as shown in Figure.
- Measure it by having the block and measuring jig travel the whole section from the starting point to the end point of the rail.
- The value measured by the measuring jig is the error in the parallelism of motion of the block.

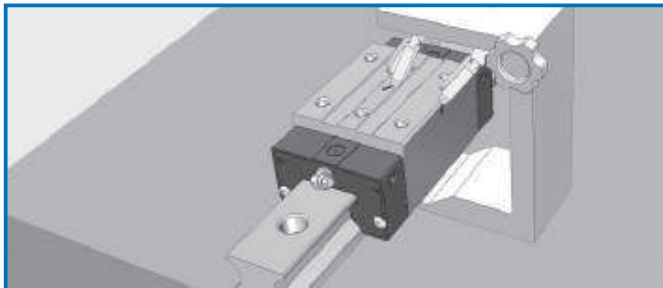


Figure 6. Parallelism of motion

Measuring the error in the degree of parallelization between the datum plane of block and that of rail

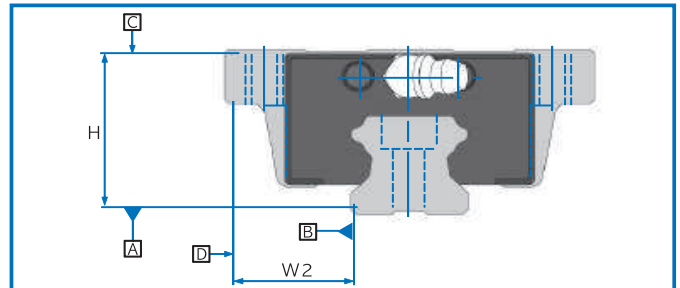


Figure 7. Difference of block

Difference between the maximum difference and minimum difference of blocks in each height and dimension installed to surface

2. Precision Design

Table 8. Classification of precision

Dimension	Terms
Dimension tolerance of height H	Distance from the base side of rail A to the top side of block C
Difference in height H	Difference in the height of blocks combined from each rail on the same plane
Dimension tolerance of width W_2	Distance between the datum plane of rail B and the reference side of block D
Difference in width W_2	Difference of the reference axis of rail B and the reference side of block D of blocks combined to the rail
Parallelism of motion of C against A	Change in the top side of block C based on the base side of rail A during the motion of block combined to the rail
Parallelism of motion of D against B	Change in the reference side of block D based on the reference side of rail B during the motion of block combined to the rail

3. Dimension Tolerance and Difference

Table 9. Specifications for precision of Linear Motion guide (H, H-S, S, S-S)

Unit : mm

Dimension	Terms	High	Precision	Super precision	Ultra precision
	No symbol	H P6	P P5	SP P4	UP P3
Dimension tolerance of height H	± 0.080	± 0.042	± 0.020	± 0.010	± 0.008
Difference in height H	0.025	0.015	0.007	0.005	0.003
Dimension tolerance of width W_2	± 0.100	± 0.050	± 0.025	± 0.015	± 0.010
Difference in width W_2	0.030	0.020	0.010	0.007	0.003
Parallelism of motion of C against A	See Table 10				
Parallelism motion of D against B	See Table 10				

Table 10. Length of rail and parallelism of motion of Linear Motion guide (H, H-S, S, S-S)

Unit : μm

Length of rail		Terms				
Above	Below	Moderate	High	Precision	Super precision	Ultra precision
		No symbol	P6	P5	P4	P3
–	50	5	3	2	1.5	1
50	80	5	3	2	1.5	1
80	125	5	3	2	1.5	1
125	200	5	3.5	2	1.5	1
200	250	6	4	2.5	1.5	1
250	315	7	4.5	3	1.5	1
315	400	8	5	3.5	2	1.5
400	500	9	6	4.5	2.5	1.5
500	630	11	7	5	3	2
630	800	12	8.5	6	3.5	2
800	1000	13	9	6.5	4	2.5
1000	1250	15	11	7.5	4.5	3
1250	1600	16	12	8	5	4
1600	2000	18	13	8.5	5.5	4.5
2000	2500	20	14	9.5	6	5
2500	3150	21	16	11	6.5	5.5
3150	4000	23	17	12	7.5	6

Table 11. Specifications for precision of Linear Motion guide (M, MB)

Unit : mm

Model No.	Dimension	Moderate	High	recision
		No symbol	P6	P5
5	Dimension tolerance of height H	± 0.030	–	± 0.015
	Difference in height H	0.015	–	0.005
	Dimension tolerance of width W_2	± 0.030	–	± 0.015
	Difference in width W_2	0.015	–	0.005
	Parallelism of motion of C against A	See Table 12		
	Parallelism of motion of D against B	See Table 12		
7 9 12 15 20	Dimension tolerance of height H	± 0.040	± 0.020	± 0.010
	Difference in height H	0.030	0.015	0.007
	Dimension tolerance of width W_2	± 0.040	± 0.025	± 0.015
	Difference in width W_2	0.030	0.020	0.010
	Parallelism of motion of C against A	See Table 12		
	Parallelism of motion of D against B	See Table 12		

Table 12. Length of rail and parallelism of motion of miniature Linear Motion guide (M, MB Series)

Unit : μm

Length of rail		Parallelism of motion			Length of rail		Parallelism of motion		
Above	Below	Moderate	High	Precision	Above	Below	Moderate	High	Precision
		No Symbol	H P6	P P5			No Symbol	H P6	P P5
-	40	8	4	1	820	850	24	14	5
40	70	10	4	1	850	880	24	14	5
70	100	11	4	2	880	910	24	14	5
100	130	12	5	2	910	940	24	14	5
130	160	13	6	2	940	970	24	14	5
160	190	14	7	2	970	1000	25	14	5
190	220	15	7	3	1000	1030	25	16	5
220	250	16	8	3	1030	1060	25	16	5
250	280	17	8	3	1060	1090	25	16	6
280	310	17	9	3	1090	1120	25	16	6
310	340	18	9	3	1120	1150	25	16	6
340	370	18	10	3	1150	1180	25	17	6
370	400	19	10	3	1180	1210	26	17	6
400	430	20	11	4	1210	1240	26	17	6
430	460	20	12	4	1240	1270	26	17	6
460	490	21	12	4	1270	1300	26	17	6
490	520	21	12	4	1300	1330	26	17	6
520	550	22	12	4	1330	1360	27	17	6
550	580	22	13	4	1360	1390	27	18	6
580	610	22	13	4	1390	1420	27	18	6
610	640	22	13	4	1420	1450	27	18	7
640	670	23	13	4	1450	1480	27	18	7
670	700	23	13	5	1480	1510	27	18	7
700	730	23	14	5	1510	1540	28	19	7
730	780	23	14	5	1540	1570	28	19	7
760	790	23	14	5	1570	1800	28	19	7
790	820	23	14	5					

Table 13. Specifications for precision of Linear Motion guide (R)

Unit : mm

Dimension	High	Precision	Super Precision	Ultra Precision
	H	P	SP	UP
	P6	P5	P4	P3
Dimension tolerance of height H	±0.042	±0.020	±0.010	±0.008
Difference in height H	0.015	0.007	0.005	0.003
Dimension tolerance of width W ₂	±0.050	±0.025	±0.015	±0.010
Difference in width W ₂	0.020	0.010	0.007	0.003
Parallelism of motion of C against A	See Table 14			
Parallelism of motion of D against B	See Table 14			

Table 14. Length of rail and parallelism of motion of Linear Motion guide (R)

Unit : μm

Length of rail		Parallelism of motion			
Above	Below	High	Precision	Super Precision	Ultra Precision
		P6	P5	P4	P3
–	50	3	2	1.5	1
50	80	3	2	1.5	1
80	125	3	2	1.5	1
125	200	3.5	2	1.5	1
200	250	4	2.5	1.5	1
250	315	4.5	3	1.5	1
315	400	5	3.5	2	1.5
400	500	6	4.5	2.5	1.5
500	630	7	5	3	2
630	800	8.5	6	3.5	2
800	1000	9	6.5	4	2.5
1000	1250	11	7.5	4.5	3
1250	1600	12	8	5	4
1600	2000	13	8.5	5.5	4.5
2000	2500	14	9.5	6	5
2500	3150	16	11	6.5	5.5
3150	4000	17	12	7.5	6

4. Selection of Precision Class

Table 15. For the selection of precision class of Linear Motion guide by unit, please refer to the table below.

Application	Unit	Precision class					Preload		
		Moderate	High	Precision	Super precision	Ultra precision	Moderate	Light preload	Heavy preload
		No sigh	H P6	P P5	SP P4	UP P3	No symbol	G ₁	G ₂
Machine Tool	CNC shelf		•	•	•				•
	Machining center		•	•	•				•
	NC milling machine		•	•	•				•
	CNC tapping machine		•	•	•				•
	NC boring machine		•	•	•				•
	NC drilling machine		•	•	•				•
	3D engraving machine		•	•	•				•
	Jig boring machine		•	•	•				•
	EDM electric spark machine			•	•	•		•	•
	Grinding machine			•	•	•			•
Semiconductor equipment	Prober equipment					•		•	•
	Wire bonder				•	•		•	•
	Sliding machine				•	•		•	
	Dicing saw machine				•	•		•	
	IC test handler			•	•			•	
	PCB laser via-hole driller				•			•	
	PCB inspection equipment			•	•			•	
	Laser marker			•				•	
	Chip mounter			•	•			•	
FPD	Mac/Mic inspection equipment				•	•		•	
	Pattern test system				•	•		•	
	Exposure				•	•		•	
	Laser repair			•	•	•		•	
	Lighting test equipment		•	•				•	
	Coder equipment			•	•			•	
	Chip bonding equipment		•	•				•	
	Dispenser equipment		•	•				•	

Application	Unit	Precision class					Preload		
		Moderate	High	Precision	Super precision	Ultra precision	Moderate	Light preload	Heavy preload
		No sigh	H P6	P P5	SP P4	UP P3	No symbol	G ₁	G ₂
FPD	Scriber		•	•				•	
	Glass edge grinding machine		•	•				•	
	FPD measuring/test equipment			•	•			•	
	Laminating equipment		•	•				•	
	Indentation test equipment								
	Prober equipment								
Industrial machine	Punching press		•					•	
	Tire molder	•						•	
	Tire vulcanizer	•						•	
	Auto-shearing machine	•						•	
	Auto-welding machine	•					•	•	
	Conveyor	•					•		
	Textile machine	•					•		
	Injection molding machine	•					•	•	
Industrial robot	Cartesian coordinated robot	•	•	•				•	
	Gantry robot	•	•					•	
	LTR robot		•	•				•	
	Take-out robot	•						•	
	Cylindrical coordinated robot		•					•	
	Vacuum robot		•	•				•	
	Robot carriage	•						•	
	Linear actuator		•	•	•		•	•	
Others	Office machine	•					•		
	FA transport system	•					•		
	Medical equipment	•					•	•	
	Welding machine	•					•		
	Painting machine	•					•		
	Precision XY table		•	•	•			•	
	UVW stage		•	•				•	
	3D measuring machine			•	•	•		•	

7 Lubrication

1. Purpose

The purpose of lubricating Linear Motion guide is to create an oil film between rail, the raceway surface of block and a rolling element to avoid the direct contact of metals and reduce friction and wear, preventing the raceway surface and the rolling element from being overheated and melted to be adhered to each other.

Moreover, the oil film created between the raceway surface and a ball decreases load-induced contact stress to improve the rolling contact fatigue life and prevent rust.

Linear Motion guide is equipped with seal but grease inside the block is leaking little by little during the operation. Therefore it is required to lubricate it at a time and interval appropriate to each service condition.

2. Selection of lubricant

To achieve the best performance of Linear Motion guide, you have to select the lubricant suitable for service conditions.

Lubricants used for Linear Motion guide include grease and oil. You can select the lubricant and lubrication method that fit your service conditions, load, operating speed, assembly type, etc.

3. Grease lubrication

Grease is a semisolid lubricant consisting of base oil, thickener, and additives.

In case of using grease for Linear Motion guide, lithium soap grease is commonly used, but grease mixed with extreme-pressure additive is used under high load or according to use. If you want to use Linear Motion guide in a high-vacuum environment or a clean room, it's desirable to choose grease with excellent performance in low evaporation and low dust raise.

1) Refilling of grease

To refill grease to Linear Motion guide, supply a sufficient amount of grease through the nipple until remaining grease is discharged. It is appropriate to fill grease up to 50% of the volume of the block. To reduce rolling resistance which may increase after grease is filled, it is better to take a test run about 20 times prior to the operation.

2) Refill interval

If Linear Motion guide's travel exceeds a certain time, its lubricating performance declines. So it is required to refill an appropriate amount of grease at a proper time depending on service conditions and environment. Usually grease is to be filled when the travel distance reaches 100KM.

$$T = \frac{100 \times 6000}{V_e \times 60} \text{ hr}$$

T : Oil refilling cycle (time)
V_e : Velocity (m/min)

4. Oil lubrication

In case of using oil for Linear Motion guide, it is recommended to use oil lubricant with high viscosity (68mm²/sec) under higher load while oil lubricant with low-viscosity (13mm²/sec) at high velocity.

It is appropriate to refill 0.3cm³ of oil per hour for each one block.

Table 16. Inspection and refilling time of lubricant

Type	Inspection item	Inspection period	Refiling time
Grease	<ul style="list-style-type: none"> Status of mixing with cutting chip, dust, foreign substance Status of contamination by other substances 	3~6 months	<ul style="list-style-type: none"> Generally 1-2 times per year Usually more than once per year if travel exceeds 100km/year Refill depending on the situation after checking the status of grease
Oil	Lubricant quantity, contamination, foreign substance	3~6 months	<ul style="list-style-type: none"> Refill depending on the results of inspection, and determine the optimal amount to refill depending on the capacity of oil tank
	Check oil level (supply oil mist)	Before every operation	<ul style="list-style-type: none"> Refill an appropriate amount after identifying the consumption Standardize the optimal amount after identifying the consumption

※ Please do not use oil that may affect synthetic resin which is the material of Linear Motion guide units.

Table 17. Lubricants used for Linear Motion guide

Application	Main use	Product name	Manufacturer	Temp. in use (°C)	Base oil	Type of thickener
Common use (extreme-pressure additive incl.)	Industrial machine, machine tool	BW EP NO.2	BWC	-20 ~ +105	Mineral oil	Lithium
Common use	Machine tool, electric spark machine, industrial robots, etc.	GADUS S2 V220	SHELL	-25 ~ +120	Mineral oil	Lithium
Clean & low dust raise	Semiconductor, FPD equipment	SNG 5050 DEMNUM	NTG DAIKIN	-40 ~ +1200 -50 ~ +300	Synthetic oil	Urea
Eco-friendly	Semiconductor AMOLED process equipment, driving gear in vacuum chamber	FOMBLIN Krytox High vacuum grease	AUSIMONT DuPont Dow Corning	-20 ~ +250	Synthetic oil	Ethylene fluorinated
Machine tool	Excellent in preventing rust and oil film strength Suitable for machine tools because it is hardly emulsified to clearance	VACTRA No.2 SLC DTE Oil	Exxon Mobil	-20 ~ +100	Oil	Way oil Turbine oil
Specialuse	Corrosion proofing	6459 Grease	SHELL	-20 ~ +100	Mineral oil	Polyurethane

8 Surface Treatment

1. Surface Treatment

WON ST uses the following methods for the optimal treatment of surfaces of Linear Motion guide in order to prevent rust and enhance appearance.

2. Types of Surface Treatment

1) Electrolytic rust-preventive black coating (black Cr plating)

This is an industrial black chrome coating which is used to improve the corrosion resistance at low cost. It can achieve better corrosion resistance than martensite stainless steel and be used to enhance appearance and prevent the reflection of light.

2) Industrial hard Cr plating

The film's hardness is over 850HV so its wear resistance is excellent and the corrosion resistance is comparable with that of martensite stainless steel.

WON ST offers surface treatments such as alkakine coloring or color alumite treatment if a customer requests. If you want use Linear Motion Guide by treating its surface, you have to set the safety factor high.

3) Fluoride low-temperature Cr plating

It is also called "Raydent." This is a combined surface treatment of black Cr coating with special fluoride resin coating which is used in where corrosion resistance or low dust raise is needed - for instance clean room.

9 Dust Proof

1. Dust Proof

To make use of the characteristics and performance of Linear Motion guide, it is important to protect the unit from external foreign substances which are likely to cause abnormal wear or shorten life. If dust or foreign substance is expected to be mixed in, it is required to use the effective sealing or dust-proofing system.

2. Types of Dust Proof

WON Linear Motion guide is basically equipped with seal but if a customer request, a metal scraper can be additionally mounted on the unit before shipment.

1) Exclusive seal

The block is equipped with end seals, side seals and inner seals to protect the bearing from foreign substances.

2) Metal scraper

A metal scraper is installed outside the end seals and effective in preventing foreign substances such as hot spatter or slag created during a welding process from entering into the unit.

10 Measure to Use in Special Environment

WON Linear Motion guide is useful in various special applications if being used in accordance with service conditions including material, surface treatment, dust proof, grease, etc.

Table 18.

Application	Conditions of use	Countermeasure	
Clean (clean room) - Semiconductor, FPD, medical equipment -	• If used in a clean environment, dust or particles generated in Linear Motion guide should be minimized.	Lubricant	<ul style="list-style-type: none"> • For use in a clean environment • Use low dust raise grease
		Rust prevention	<ul style="list-style-type: none"> • Black Cr coating • Fluoride low-temperature colorimetric Cr plating (Raydent treatment) • Use high-corrosion resistant stainless steel as material
Vacuum - Semiconductor, FPD deposition equipment -	<ul style="list-style-type: none"> • If used in a vacuum environment, out gas discharged from Linear Motion guide should be tightly controlled to maintain the vacuum status. • Great rust prevention is required since rust-prone parts cannot be used in this environment. 	Lubricant	<ul style="list-style-type: none"> • Use grease for a vacuum environment
		Rust prevention (Out Gas)	<ul style="list-style-type: none"> • Use high-corrosion resistant stainless steel as material • Use a self oiling agent using special coatings such as fluoroplastic coating • Use ceramic as material
High-temperature environment	• If used in higher temperature than general environment, the material's heat resistance is important and plastic synthetic resin used for parts should be replaced with metal.	Lubricant	<ul style="list-style-type: none"> • Use grease for high-temperature environments
		Material	<ul style="list-style-type: none"> • Use an end seal, side seal + double seal • Use a double seal • Use a special seal for high temperature
Dust	• If used in an environment filled with cutting chips, wood dust, and dust, it is required to develop a measure to protect the block from foreign substances.	seal	<ul style="list-style-type: none"> • Use a plastic synthetic resin cap • Use a metal cap • Use a metal scraper
		Cap	<ul style="list-style-type: none"> • Use a plastic synthetic resin cap • Use a metal cap • Use a seal plate
		Holding door	<ul style="list-style-type: none"> • Use an exclusive holding door • Use an sealing all-in-one holding oor
Spatter	• If exposed to a spot welding or arc welding environment, hot spatters may be fixed onto the	Spatter	<ul style="list-style-type: none"> • Fluoride black Cr coating
		seal	<ul style="list-style-type: none"> • Use a metal scraper
		Dust proof	<ul style="list-style-type: none"> • Use a metal cap • Use a seal plate

11 Placement and Installation

1. Placement and Structure

To place Linear Motion guide in the equipment, first identify the overall structure of the equipment, then check the size of the base and a transfer table and consider load applied according to mounting directions such as placing vertically, in slope, or in the back as well as required life to make sure Linear Motion guide is optimally installed.

Placement of Linear Motion guide (example)

(1) Assembly of the top side of block, block transfer



(2) Assembly of the back side of block, rail transfer



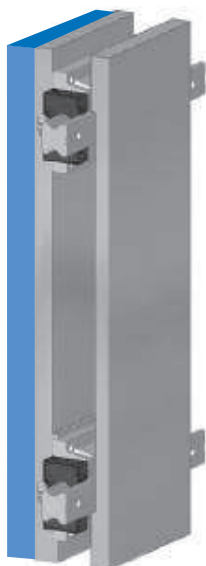
(3) Assembly of the flank of block, block transfer



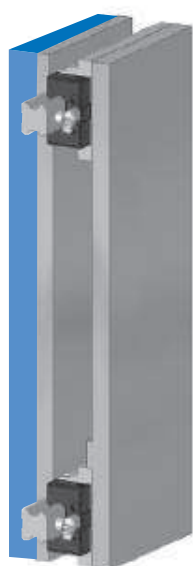
(4) Assembly of the flank of block, rail transfer



(5) Assembly of the wall side of block, rail transfer



(6) Assembly of the wall side of block, block transfer



(7) Symmetrical assembly of the top and bottom of block, rail transfer



(8) Symmetrical assembly of the top and bottom of block, block transfer



2. Mounting and Fixation

In the structure that vibration or impact is applied or where combined load or moment load is applied, Linear Motion guide should be fixed in a different way from a general method.

As a widely used method, push a pressure plate from the flank after slightly protruding the block and rail of LM unit.

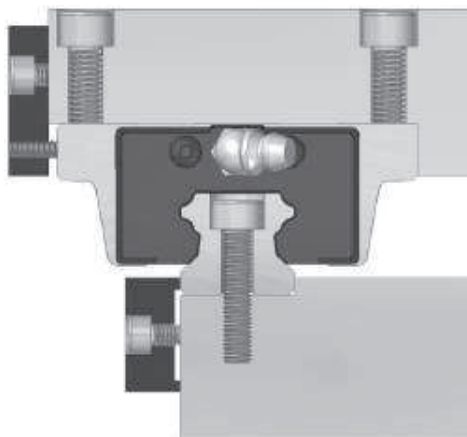


Figure 8. Pushing a pressure plate from the flank

Fasten a tapered fixture with a bolt. Even slight bolting up generates big force in a horizontal direction. If it is bolted up too much, deformation may occur in rail, for instance, which needs to be taken a caution.

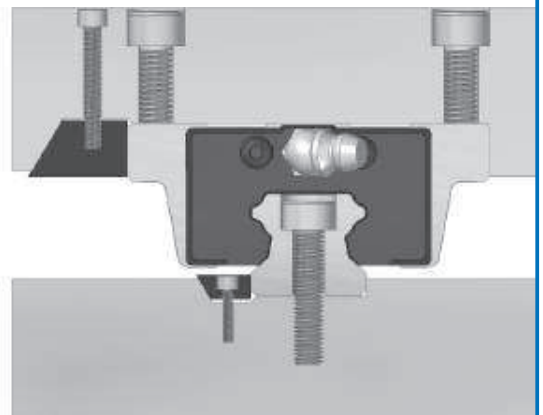


Figure 9. Pushing a tapered plate

Need to use miniature bolts due to space constraint when pushing the rail and useful if having many bolts for pushing.

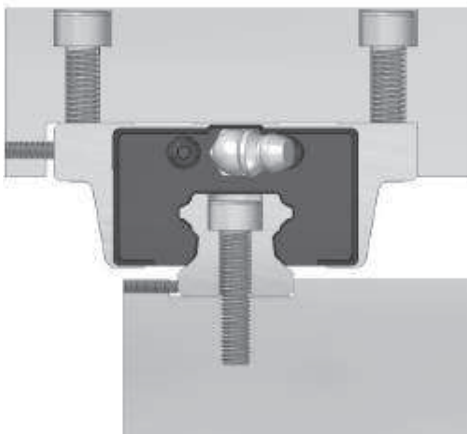


Figure 10. Pushing a bolt from the flank

Push a needle roller with the head of a counter-sunk screw using a roller of the bed. You must be careful to push it to fit the screw.

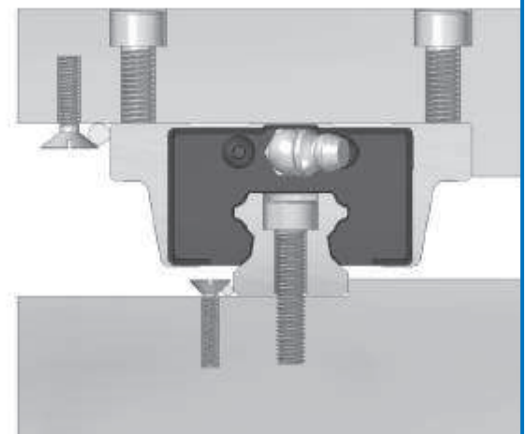


Figure 11. Pushing a roller

3. Design of mounting surface during installation

Design and management of mounting surface

The precision of mounting surface of Linear Motion guide and the error in installation generate unexpected load and stress to the unit, therefore it is required to take caution to prevent the harmful effects on the unit's travel and life.

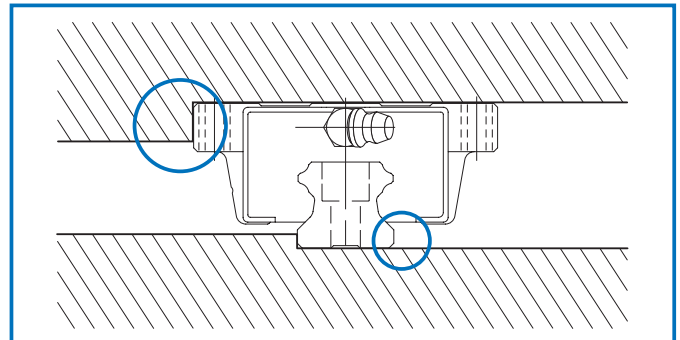


Figure 12. Shape of edges

Management of vertical angle of datum plane for installation

If the vertical angle of the installation surface and of a rail or a block is inaccurate, it cannot be assembled precisely. So you need to review the vertical angle and error during design.

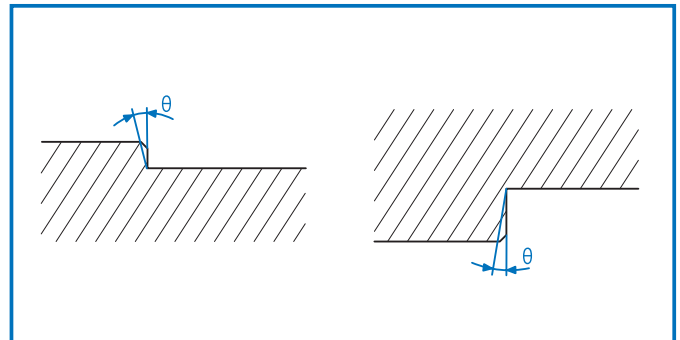


Figure 13.

Management of datum plane for assembly

It is important to manage the height and thickness of datum plane during design.

If the height is too high or low, a rail or a block cannot be assembled precisely due to its surface attachment. Or the application of eccentric load, horizontal load and moment load may loosen the strength of joint and result in faulty assembly which will be unable to meet the precision requirements. So attention must be paid

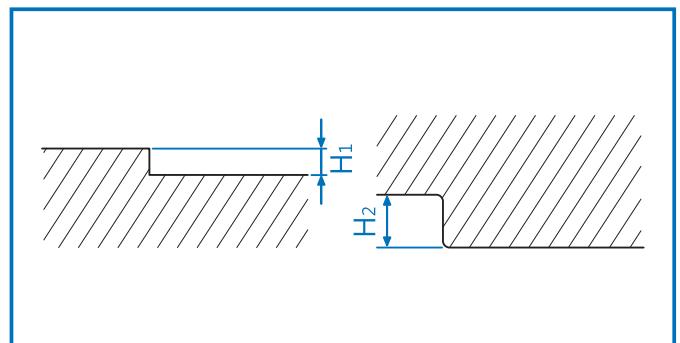


Figure 14. Vertical angle of contact datum plane

Management of the shape of contact corner

If the right-angled corner of a rail or a block installed to the mounting surface of Linear Motion guide is processed in R-shape and R value is bigger than the dimension of the surface of the rail or the block, it may not be assembled precisely to the datum plane. So attention must be paid.

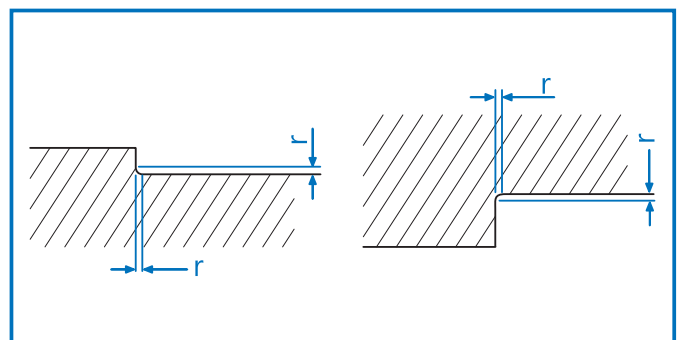


Figure 15. Dimension of contact datum plane

Management of dimensional tolerance between datum plane and bolt during design

If the dimensional tolerance from the contact datum plane to the mounting hole of a rail or a block of Linear Motion guide is too big, precise assembly is impossible so attention must be paid.

Generally the dimensional tolerance is $\pm 0.1\text{mm}$.

If the distance tolerance from the assembly datum plane to the assembly bolt roll of a rail and a block is too wide or narrow, precise assembly is impossible. So the tolerance must be $W3 \pm 0.1\text{mm}$ during design.

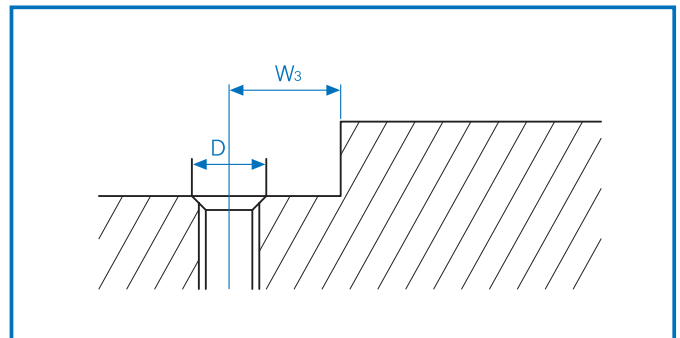


Figure 16. Dimensional tolerance between contact datum plane and mounting hole

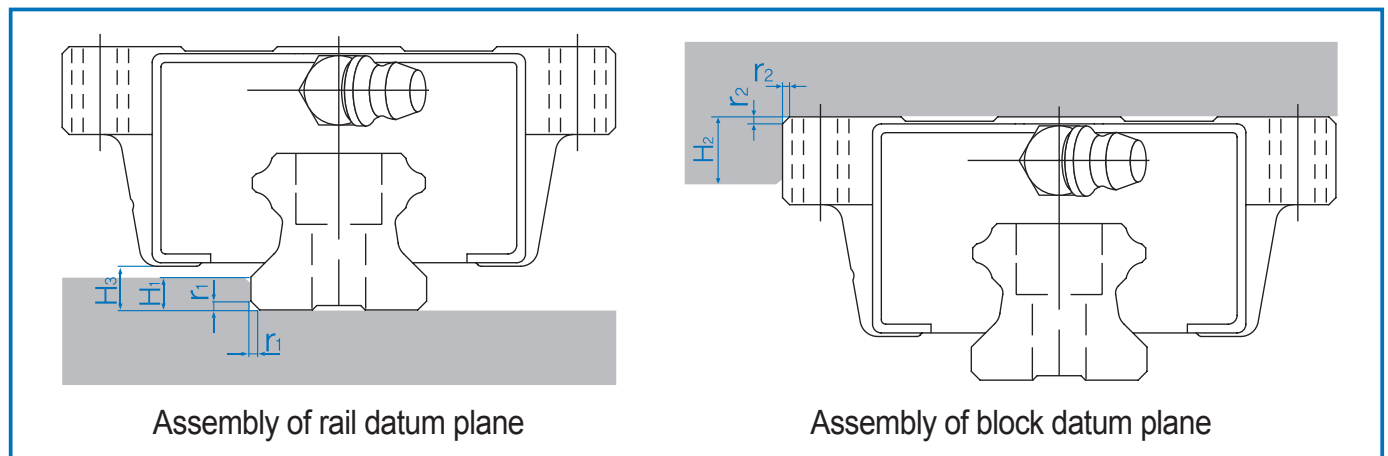


Figure 17. Height of the raised spot of mounting surface and radius of corner R

- Make a datum plane which can contact the flank in order to secure convenience in assembly of and precision positioning of a rail and a block during the installation of Linear Motion guide.
- The height of the raised spot of contact datum plane or the radius of corner may vary depending on the specifications of Linear Motion guide so please see the table below.
- To prevent deformation of the raised spot by pressing force from above or pushing force from side, sufficient thickness must be secured during design.

H Series, H-S Series

Unit : mm

Model No.	Radius of corner of the installation to rail $r_1(\text{max.})$	Radius of corner of the installation to block $r_2(\text{max.})$	Height of raised spot of the installation to rail H_1	Height of raised spot of the installation to block H_2	H_3
15	0.5	0.5	3	4	4.7
20	0.5	0.5	3.5	5	6
25	1	1	5	5	7
30	1	1	5	5	7.5
35	1	1	6	6	9
45	1	1	8	8	10
55	1.5	1.5	10	10	13

S Series, S-S Series

Unit : mm

Model No.	Radius of corner of the installation to rail r_1 (max.)	Radius of corner of the installation to block r_2 (max.)	Height of raised spot of the installation to rail H_1	Height of raised spot of the installation to block H_2	H_3
15	0.5	0.1	2.5	4.0	4.5
20	0.5	1.0	4.0	5.0	6.0
25	1.0	1.0	5.0	5.0	7.0

M Series, MB Series

Unit : mm

Model No.	Radius of corner of the installation to rail r_1 (max.)	Radius of corner of the installation to block r_2 (max.)	Height of raised spot of the installation to rail H_1	Height of raised spot of the installation to block H_2	H_3
5	0.2	0.2	0.8	2	1
7	0.2	0.2	1.2	2.5	1.5
9	0.2	0.2	1.5	3	2
12	0.2	0.2	2.5	4	3
15	0.2	0.2	3	4.5	4
20	0.2	0.2	4	5	5

R Series

Unit : mm

Model No.	Radius of corner of the installation to rail r_1 (max.)	Radius of corner of the installation to block r_2 (max.)	Height of raised spot of the installation to rail H_1	Height of raised spot of the installation to block H_2	H_3
35	1	1	5	6	6.5
45	1.5	1.5	6	8	8
55	1.5	1.5	8	10	10

4. Error tolerance of mounting surface during installation

1) Auto-adjusting and error-absorbing abilities

Linear Motion guide has an excellent auto-adjusting ability so that even though the structure to be assembled to a rail is slightly deformed or processing error may occur, the straightness or parallelism of a table after assembly will be better than the precision in processing before assembly and the quite straight-line running is available.

2) Error tolerance of the degree of parallelization when using 2-axis assembly (P_1)

The error in the degree of parallelization when using a 2-axis assembly is as shown below.

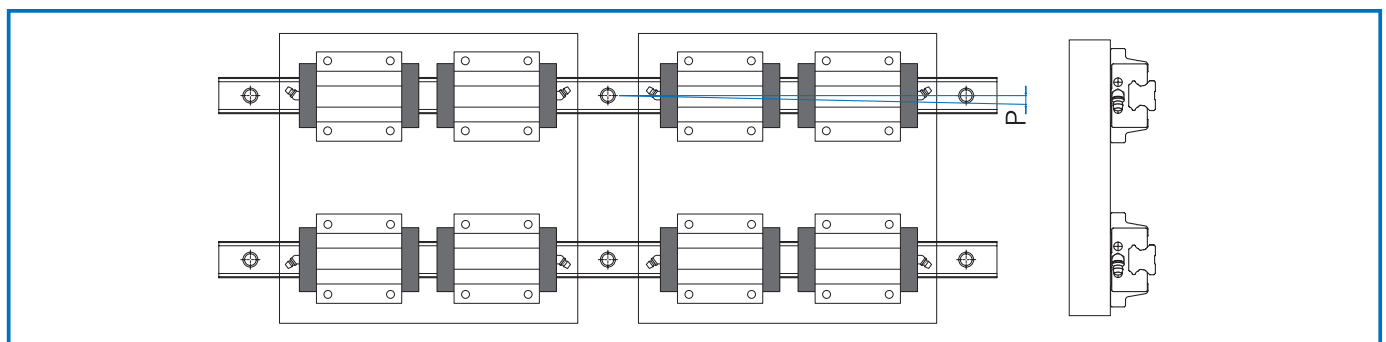


Figure 18. Error tolerance of the degree of parallelization (P)

H Series, H-S Series

Unit : μm

Model No.	Common clearance	G ₁ clearance	G ₂ clearance
15	25	18	-
20	25	20	18
25	30	22	20
30	40	30	27
35	50	35	30
45	60	40	35
55	70	50	45

S Series, S-S Series

Unit : μm

Model No.	Common clearance	G ₁ clearance	G ₂ clearance
15	25	18	-
20	25	20	18
25	30	22	20

M Series, MB Series

Unit : μm

Model No.	Common clearance	G ₁ clearance
5	2	-
7	3	-
9	4	3
12	9	5
15	10	6
20	13	8

R Series

Unit : μm

Model No.	Common clearance	G ₁ clearance	G ₂ clearance
35	14	10	7
45	17	13	9
55	21	14	11

3) Error tolerance of height during 2-axis assembly (P_2)

If the error in height is too big, the block may be distorted and its rigidity may be affected as the raceway groove of the block and the contact angle of a ball or a roller which is the rolling element are altered.

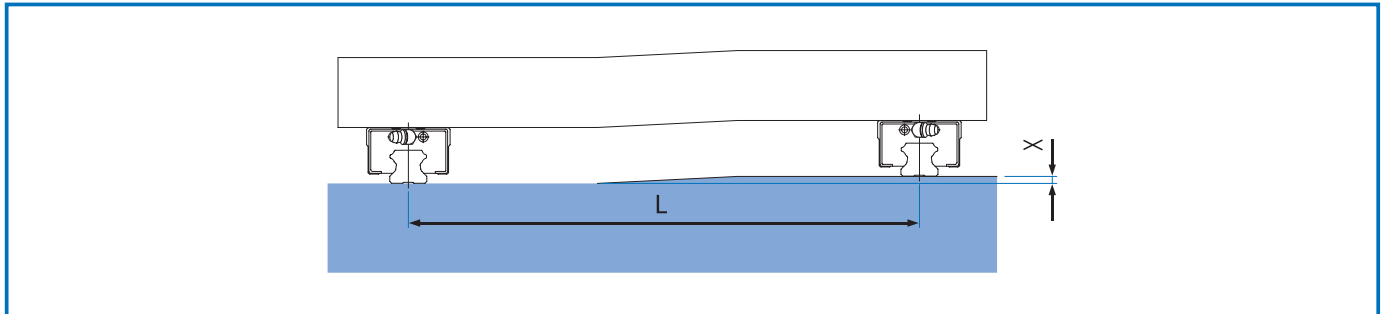


Figure 19. Error tolerance of height level in 2-axis (X)

H Series, H-S Series, S Series, S-S Series

Unit : μm

Model No.	Common clearance	G ₁ clearance	G ₂ clearance
15	0.26L	0.17L	-
20	0.26L	0.17L	0.10L
25	0.26L	0.17L	0.14L
30	0.34L	0.22L	0.18L
35	0.42L	0.30L	0.24L
45	0.50L	0.34L	0.28L
55	0.60L	0.42L	0.34L

M Series, MB Series

Unit : μm

Model No.	Common clearance	G ₁ clearance
5	0.04L	-
7	0.05L	-
9	0.07L	0.01L
12	0.10L	0.02L
15	0.12L	0.04L
20	0.14L	0.06L

R Series

Unit : μm

Model No.	Common clearance	G ₁ clearance	G ₂ clearance
35, 45, 55	0.22L	0.17L	0.12L

The error tolerance of height level in using 2-axis Linear Motion guides is as follows.

5. Marking of datum plane during installation

The datum plane of WON ST's Linear Motion guide is the ground surface on the opposite side of WON mark shown in the block.

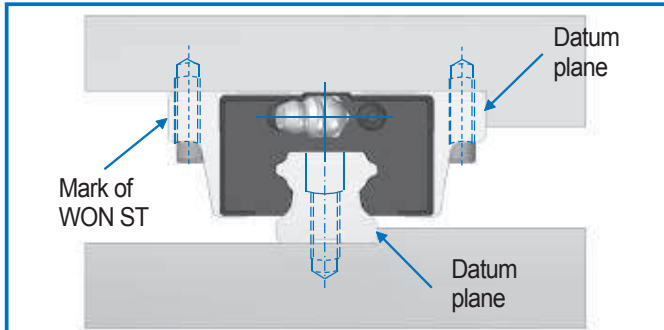


Figure 20. Linear Motion guide on the reference axis

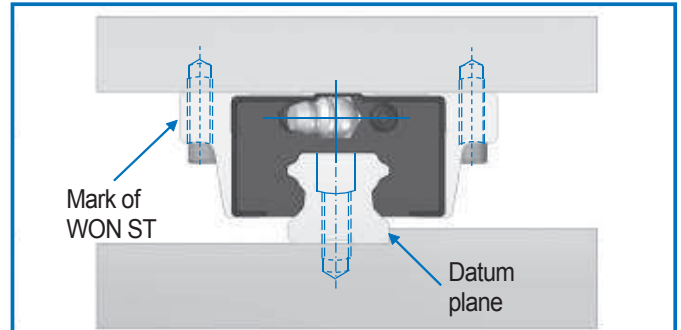


Figure 21. Linear Motion guide on the driven shaft

6. Connection of rails

If you need a longer rail than the one supplied, you can connect rails for the purpose of use. The mark on the rail indicates the point where rails should be linked.

If the block passes through the connecting points simultaneously, they may affect the unit's travel and cause a delicate hitch. To solve this problem, it is recommended to make sure the connecting points intercrossed

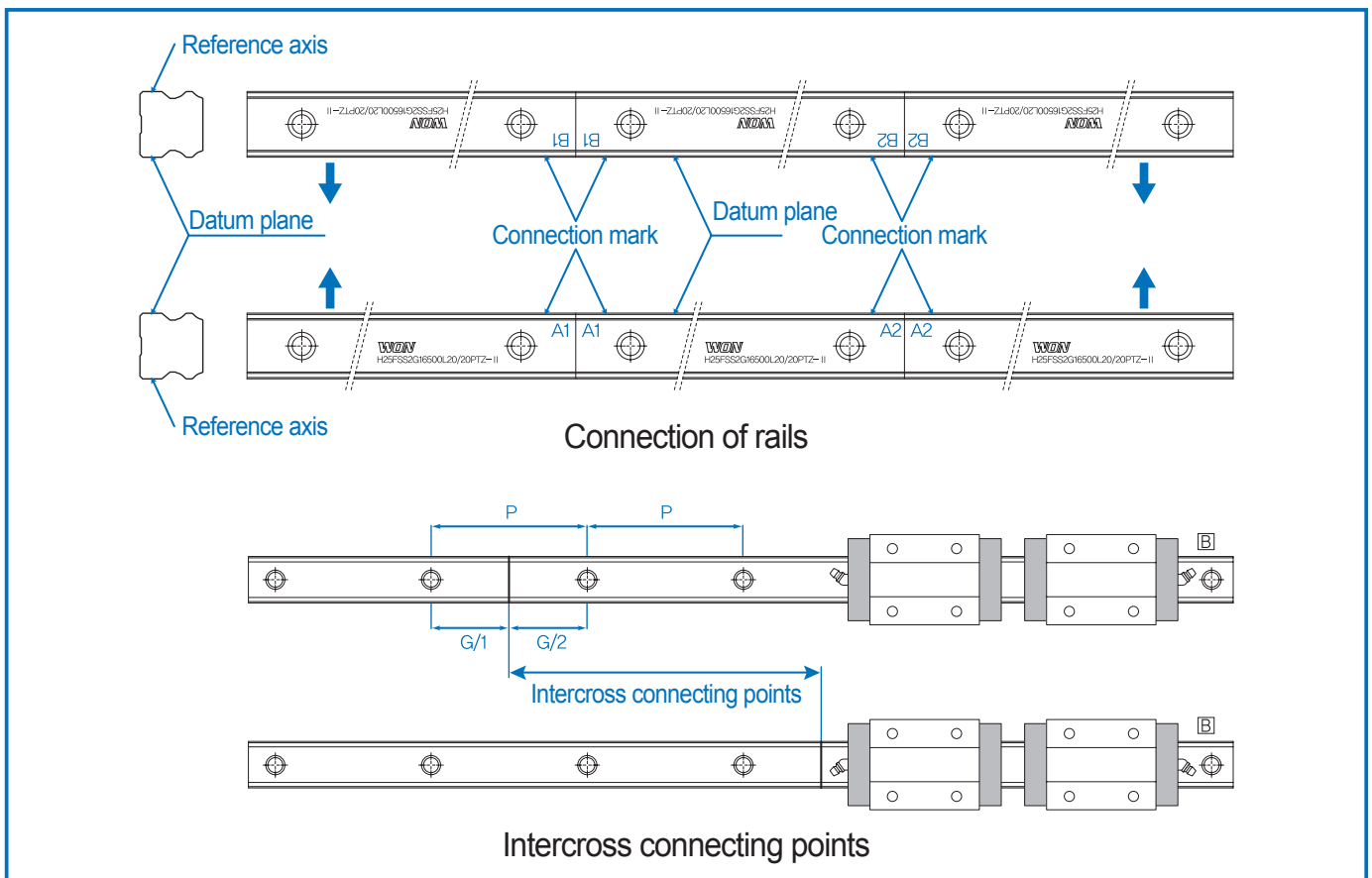
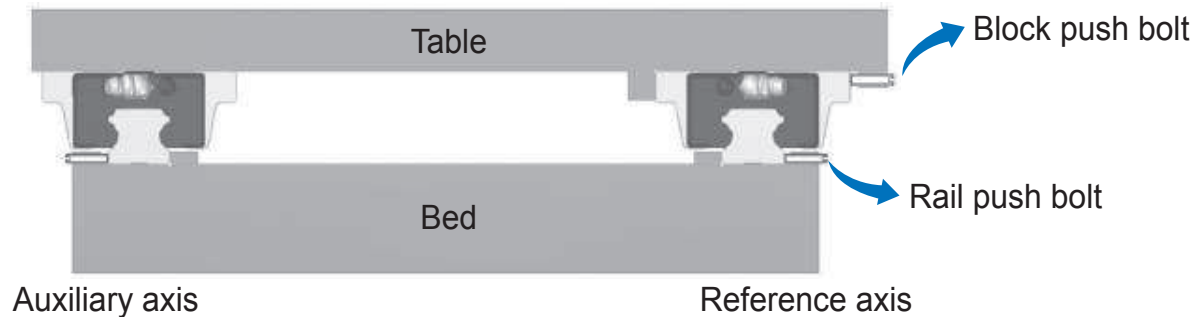


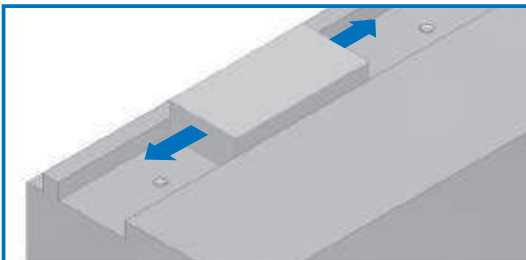
Figure 22. Connection of rails

7. Installation of Linear Motion Guide

1. Installation of Linear Motion guide in the equipment exposed to vibration and impact

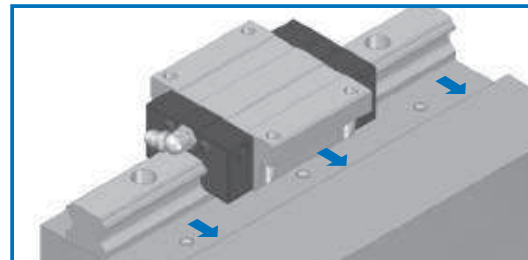


1) Install a rail



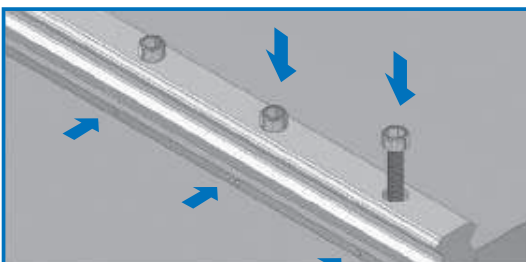
Step 1: Check the surface to be installed with a rail

Prior to installation, thoroughly remove burr, dust, rust preventive oil, etc.



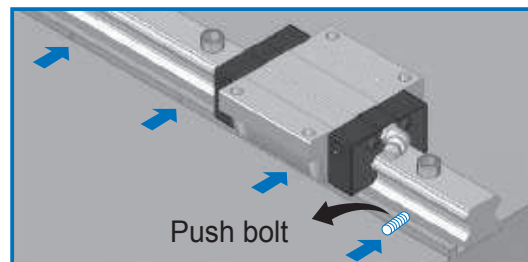
Step 2: Draw a rail tightly to the datum plane

Gently place Linear Motion guide on the bed and push it in the opposite direction of the bed's datum plane



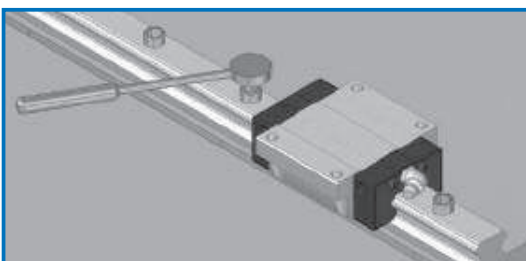
Step 3: Fasten bolts temporarily

Check the status of bolts and fasten every bolt temporarily



Step 4: Fasten push bolts

Fix push bolts to make sure that the rail is parallel with the datum plane of the bed.

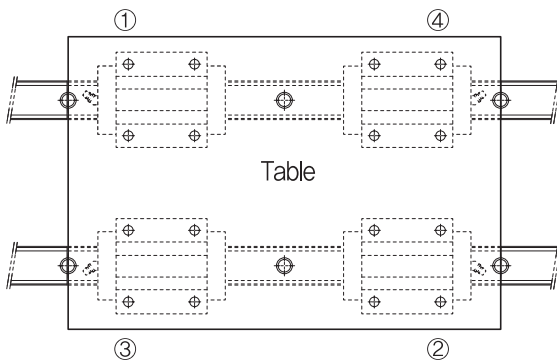


Step 5: Fix and fasten assembly bolts using a torque wrench

- Step 5 :
Fasten all bolts using the recommended torque. Fasten the bolt in the center first and then continue fastening each bolt toward both ends in order to maintain the precision of rail during assembly.

- Step 6 : Assemble an auxiliary axis
Repeat the procedure above for the installation of an auxiliary axis.

2) Install a block



-Step 1: Assembly bolts temporarily

Place a table on the block and fasten all bolts temporarily

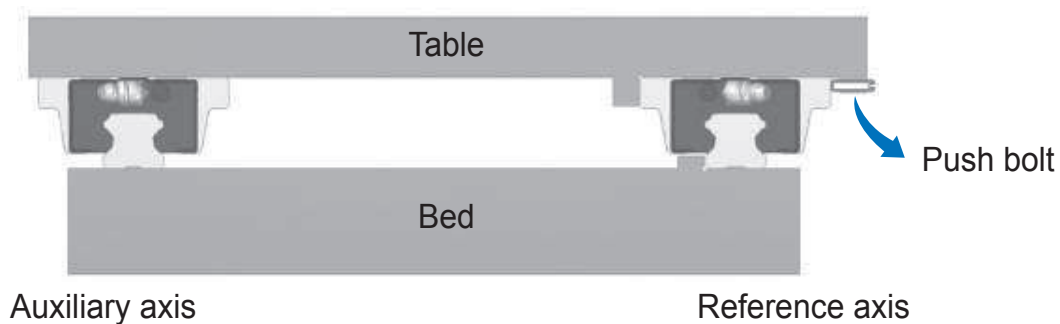
- Step 2: Fasten bolts tightly

Fix the main rail block to the opposite side of the table's datum plane using a push bolt and adjust the position of the table.

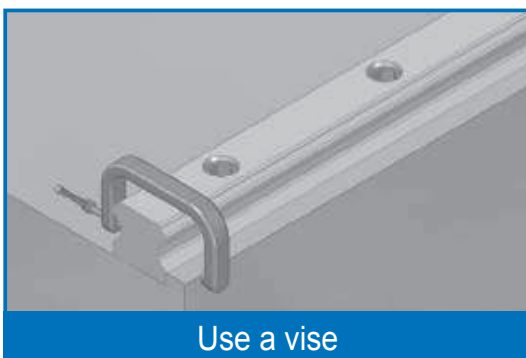
- Step 3: Fix and fasten assembly bolts

Completely fasten all bolts on the datum plane and subsidiary side in the order of 1 to 2.

2. Installation of Linear Motion guide without a push bolt



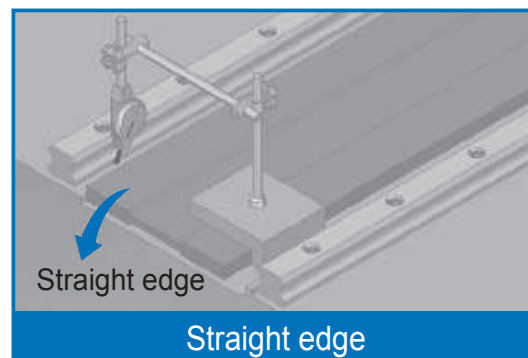
1) Install a master rail



Use a vise

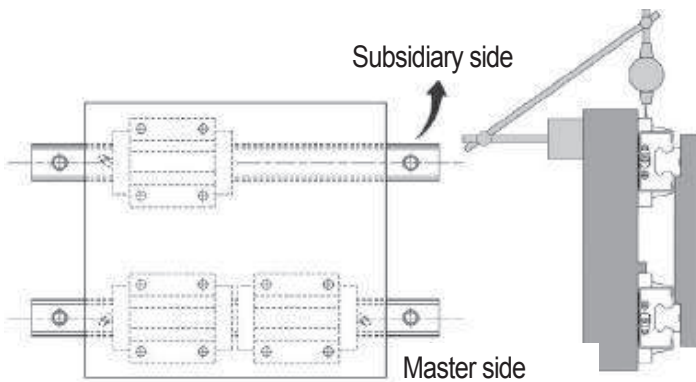
Fasten bolts temporarily and push a master rail toward the datum plane using a C-vise. Fasten the bolts according to the prescribed torque and order.

2) Install an auxiliary rail



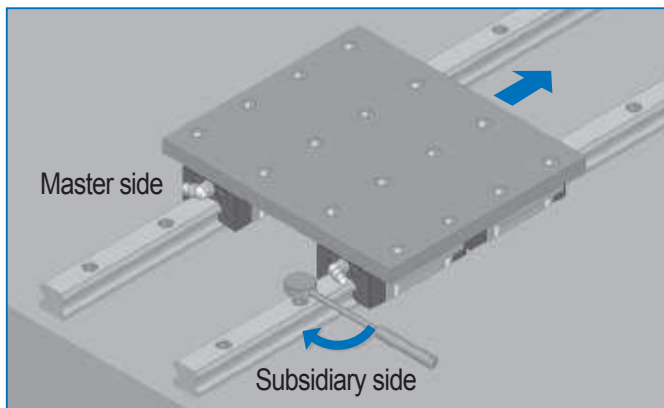
Straight edge

Place a straight edge between two rails and make sure it is parallel with the master rail that is fixed temporarily. Check the degree of parallelism with the dial gauge and adjust the rail if needed. Then, fasten bolts in order.



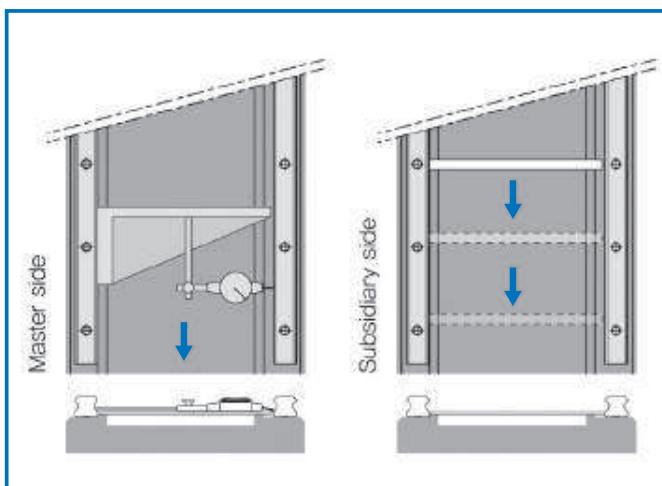
- Assembly using a table

1. Fix two blocks on the datum plane and one block on the subsidiary side to a table.
2. Fix another auxiliary block and rail to the table and bed temporarily.
3. Place a dial gauge on the table and make sure a prober of the gauge contact the subsidiary side of the block.
4. Separate the table from the end of the rail and check the degree of parallelization of the block with the auxiliary rail.
5. Fasten bolts in order.



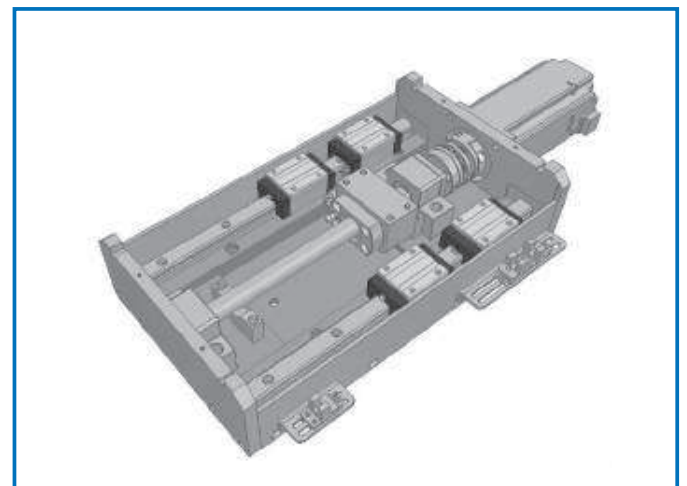
- Assembly using a rail on the datum plane

1. Fix two blocks on the datum plane and one block on the subsidiary side to a table.
2. Fix another auxiliary block and rail to the table and bed temporarily.
3. Separate the table from one rail and make an adjustment by considering the rolling resistance during the movement and checking the degree of parallelization of the auxiliary rail.
4. Fasten bolts in order.



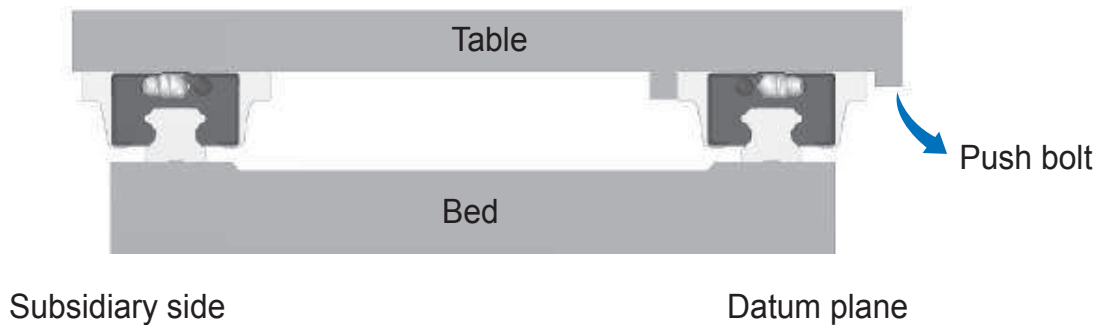
Assembly using a jig

Move the position of a block in every bolt pitch at the end of the rail in consecutive order and fasten bolts in order by adjusting the degree of parallelism between the datum plane of a reference rail and that of an auxiliary rail using a special jig.

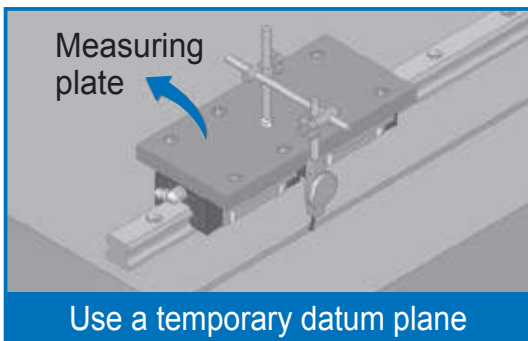


Installation completion of Linear Motion guide

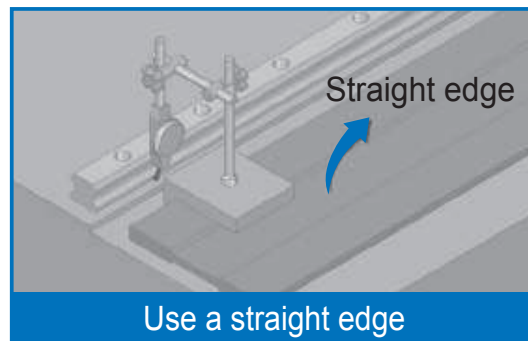
3. Installation of Linear Motion guide without the datum plane for a reference rail



1) Install a reference rail



Fix two blocks together onto the measuring plate and install the temporary datum plane near the surface where a rail is to be installed on the bed. Then check and adjust the degree of parallelism of the rail and fasten bolts in order.



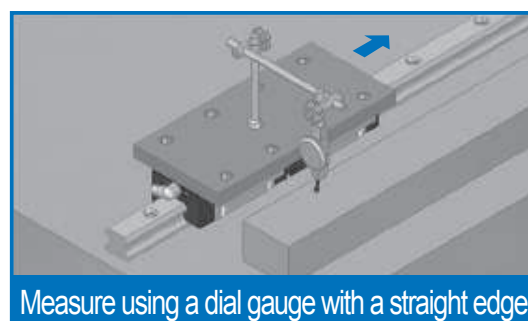
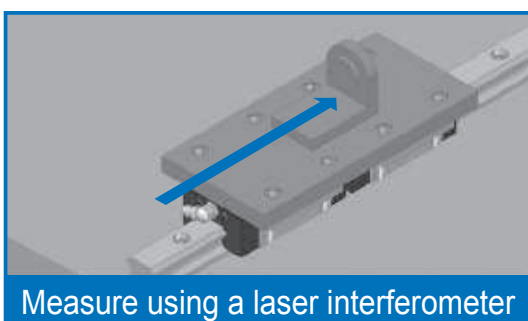
Fix a rail to the bed temporarily and adjust it to be straight using a dial gauge and then fasten bolts in order.

2) Apply the same method when installing the auxiliary block and rail

4. Measure precision after installation

You can check the precision of travel by fixing two blocks onto the measuring plate. Use a dial gauge with a straight edge or a laser interferometer to measure the precision.

In case of using a dial gauge, you have to place the straight edge as close to the block as possible in order to accurately measure it.



8. Torque used to fasten bolts during the assembly of Linear Motion guide

1) Select the optimal torque for bolts

For the assembly of the rail of Linear Motion guide, the optimal clamping torque must be used depending on the materials of mounting surface or bolts. Inaccurate clamping torque may affect the mounting precision of the rail so please use a torque wrench.

2) Recommended torques by the material of mounting base of Linear Motion guide

Unit : N·m

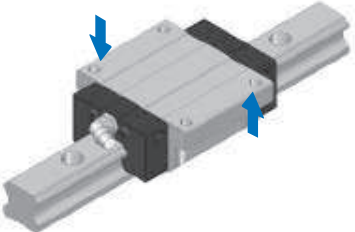
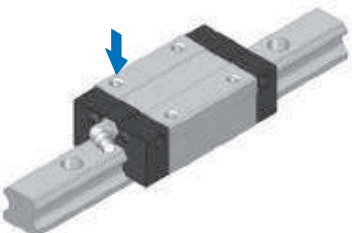
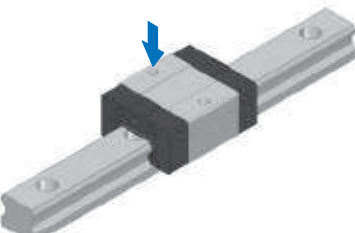
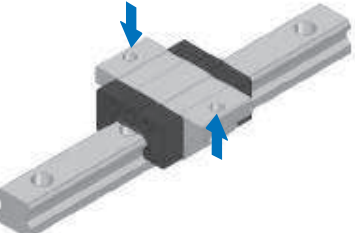
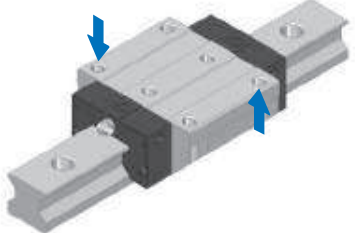
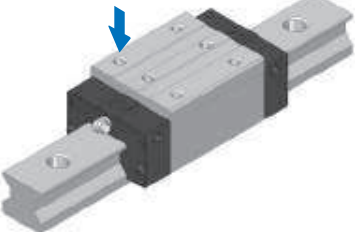
Bolt specification	Torque value (Unit : N·m)		
	Steel	Casting	Aluminum
M3	2	1.3	1
M4	4	2.7	2
M5	8.8	5.9	4.4
M6	13.7	9.2	6.8
M8	30	20	15
M10	68	45	33
M12	120	78	58
M14	157	105	78
M16	196	131	98
M20	382	255	191

3) Recommended torques by the material of bolts

Unit : N·m

Bolt specification	Clamping torque		Bolt specification	Clamping torque	
	Carbon steel bolt	SCM steel bolt		Carbon steel bolt	SCM steel bolt
M2.3	-	0.4	M12	108	76
M2.5	-	0.6	M14	172	122
M3	1.7	1.1	M16	263	196
M4	4.0	2.5	M18	-	265
M5	7.9	5.1	M20	512	-
M6	13.3	8.6	M22	-	520
M8	32.0	22.0	M24	882	-
M10	62.7	43.0	M30	1750	-

9. Directions of bolt fastening by Linear Motion guide type

	<p style="text-align: center;">H-F, H-FL, H-SF, H-SFL</p> <p>Since the flange of a block is tapped and the counter bore is processed in the bottom, bolts can be assembled both from bottom to top and from top to bottom as indicated by arrows. But, if bolts are fastened from bottom to top, it is recommended to use one size smaller bolts.</p>
	<p style="text-align: center;">H-R, H-RL, H-SR, H-SRL</p> <p>Since tap is processed in the square body of the block, it is used when bolts are fastened from top to bottom as indicated by arrows.</p>
	<p style="text-align: center;">S-C, S-R, S-SC, S-SR</p> <p>Since tap is processed in the rectangular body of the block, it is used when bolts are fastened from top to bottom as indicated by arrows.</p>
	<p style="text-align: center;">S-CF, S-F, S-SCF, S-SF</p> <p>Since the flange of a block is tapped and the counter bore is processed in the bottom, bolts can be assembled both from bottom to top and from top to bottom as indicated by arrows. But, if bolts are fastened from bottom to top, it is recommended to use one size smaller bolts.</p>
	<p style="text-align: center;">R-F, R-FL</p> <p>Since the flange of a block is tapped and the counter bore is processed in the bottom, bolts can be assembled both from bottom to top and from top to bottom as indicated by arrows. But, if bolts are fastened from bottom to top, it is recommended to use one size smaller bolts.</p>
	<p style="text-align: center;">R-R, R-RL</p> <p>Since the rectangular body of a block is tapped, it is used when bolts are fastened from top to bottom as indicated by arrows.</p>

12 Types of Linear Motion Guide

1. Linear Motion Guide H Series

1) Structure of H Series

WON Linear Motion Guide H Series has a four-row circular arc-groove structure in the raceway groove of a rail or a block and is a 4-direction equal load type which can bear equal load rating for vertical compression load, tensile load, and horizontal load as the rolling element is combined with balls at 45 degree, which reduces friction resistance to ensure smooth motion and long life.

Also if the ball is preloaded, it can enhance the rigidity of Linear Motion guide and minimize Linear Motion guide's displacement for external load.

2) Features of H Series

- a. High quality and very effective in realizing high precision and elimination of labor
- b. High rigidity and high precision which can realize the stable travel for a longtime
- c. Great wear resistance and friction resistance which ensures a long life
- d. Great auto-adjusting and error-absorbing abilities with the face-to-face duplex structure same to D/F combination of ball bearing
- e. Various specifications for easy design
- f. Easy to use due to great compatibility between a rail and a block

2. Spacer Chain Guide H-S Series

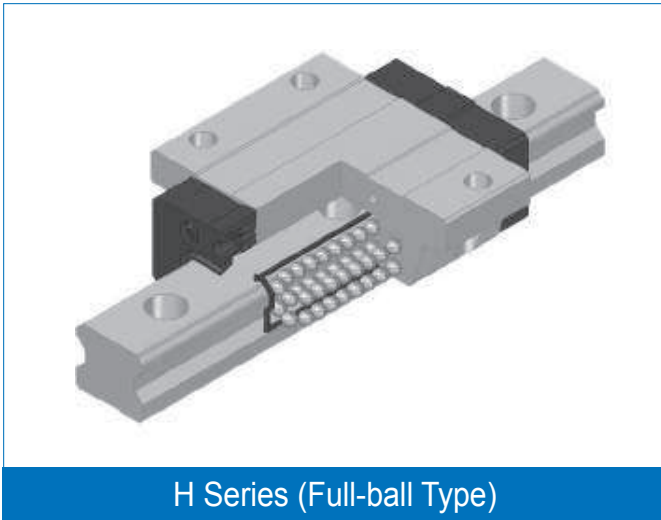
1) Structure of H-S Series

Linear Motion Guide H-S Series has a 4-direction equal load type which is identical to H Series and has an auto-adjusting face-to-face D/F structure. It uses balls as a rolling element and combines a spacer between balls to prevent them from colliding each other during the rolling motion. Therefore it makes less noise and more stable circulating motion than a full-ball type to realize quiet running and the spacer act as the pocket of lubricant to obtain longer life than H Series.

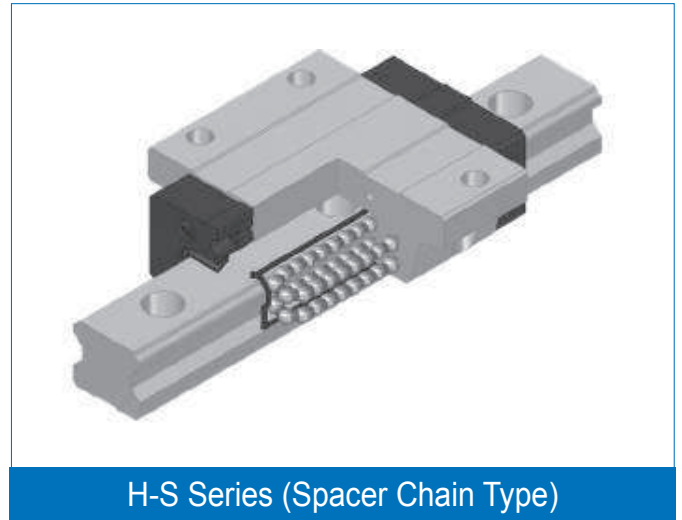
2) Features of H-S Series

- a. As a spacer-incorporated type which improves frictional properties and prevents the collision of balls, it not only allows stable circulating motion and smooth running but also reduces noise. If special lubricating seal is attached to lengthen life, maintenance-free operations can be achieved.
- b. Collision between balls and the loss of oil film are prevented by applying a resin spacer to improve life and generate less particles and dust.
- c. High quality in realizing high precision and high velocity so it could create large effect on elimination of power loss.
- d. High rigidity and high precision which can realize the stable travel for a long time
- e. Great wear resistance and friction resistance which ensures a long life
- f. Great auto-adjusting and error-absorbing abilities with the face-to-face duplex structure same to D/F combination of ball bearing
- g. Various specifications for easy design
- h. Easy to use due to great compatibility between a rail and a block

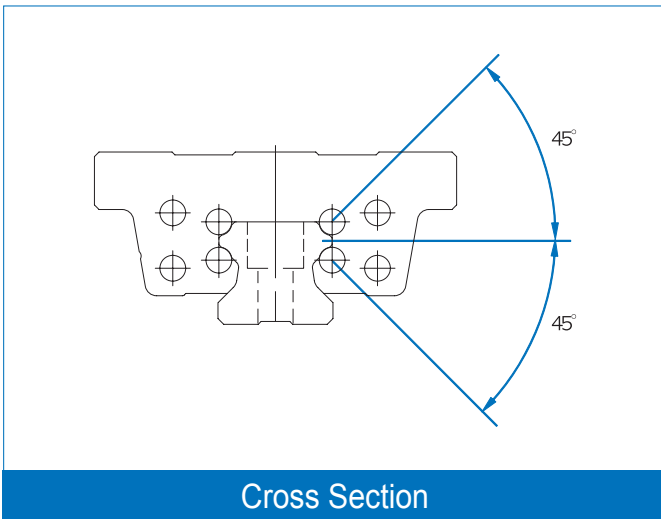
Linear Motion Guide



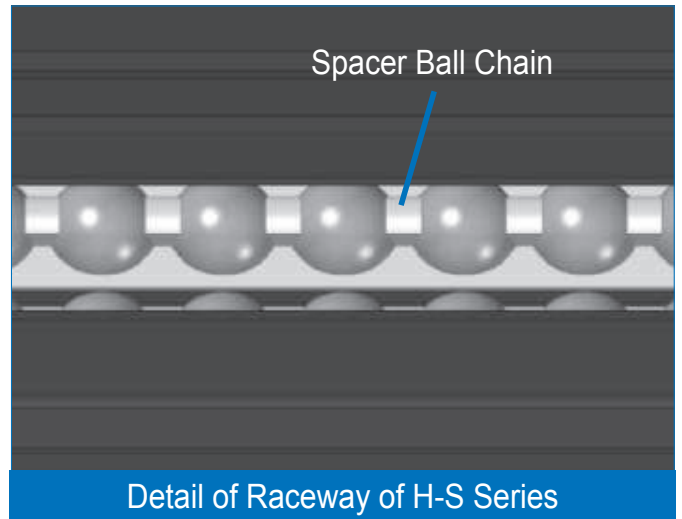
H Series (Full-ball Type)



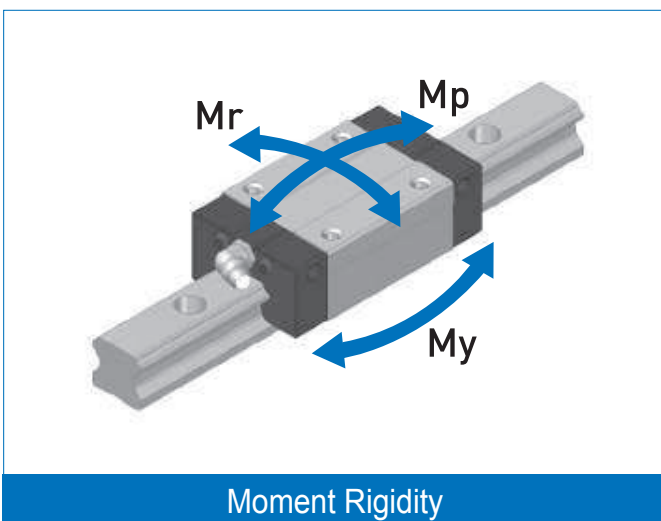
H-S Series (Spacer Chain Type)



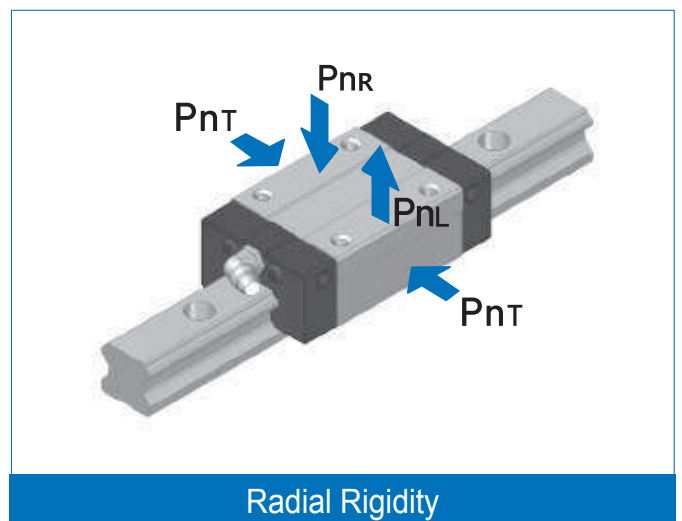
Cross Section



Detail of Raceway of H-S Series

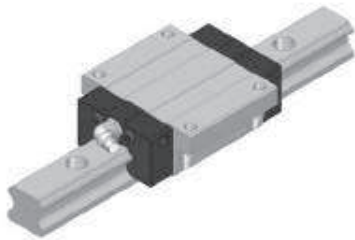
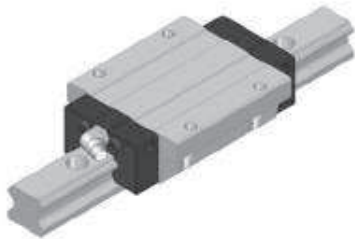
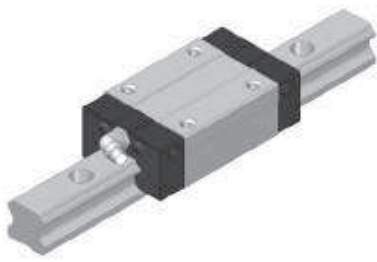



Moment Rigidity

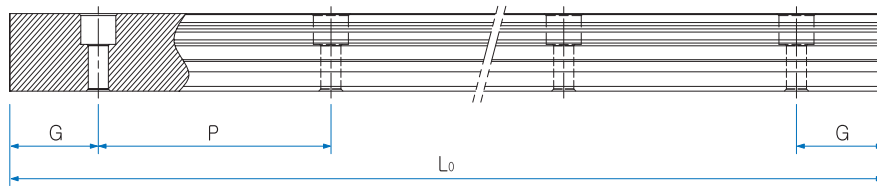


Radial Rigidity

Types and Features

Category	Type	Shape & Features		
Flange type	H-F H-SF		<ul style="list-style-type: none"> - With the tapped flange of a block, a general type which can be assembled both from bottom to top and from top to bottom - A 4-direction equal load type with high rigidity and high load <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer retainer is applied.</p>	Machine tool X, Y, Z axis, CNC machining center, CNC shelf, CNC tapping center, Electric injection machine, 3D engraving machine, laser processor, milling machine, welder for exclusive use, EDM electric spark machine, automation device, Various transport system, FPD inspection equipment, Industrial robots, ATC, Precision X-Y table, Various industrial machine
	H-FL H-SFL		<ul style="list-style-type: none"> - Having the cross section identical to that of H-F Series, it increased load rating by extending the whole length (L1) of Linear Motion guide block - A 4-direction equal load type with high rigidity and high load <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer retainer is applied.</p>	
Compact type	H-R H-SR		<ul style="list-style-type: none"> - With the tapped top side of a block, a compact type that the width of Linear Motion guide block is minimized - A 4-direction equal load type with high rigidity and high load <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer retainer is applied.</p>	Industrial robots, ATC, Precision X-Y table, Various industrial machine
	H-RL H-SRL		<ul style="list-style-type: none"> - Having the cross section identical to that of H-R Series, it increased load rating by extending the whole length (L1) of Linear Motion guide block - A 4-direction equal load type with high rigidity and high load <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer retainer is applied.</p>	

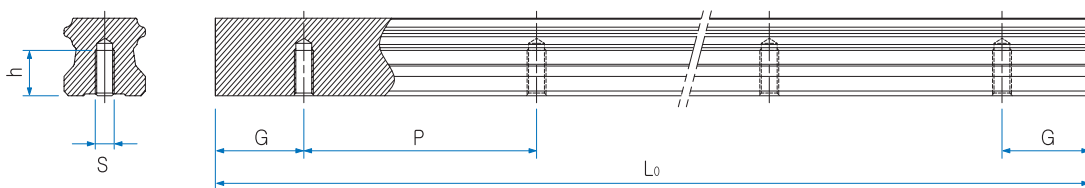
Standard and maximum length of a rail



Unit : mm

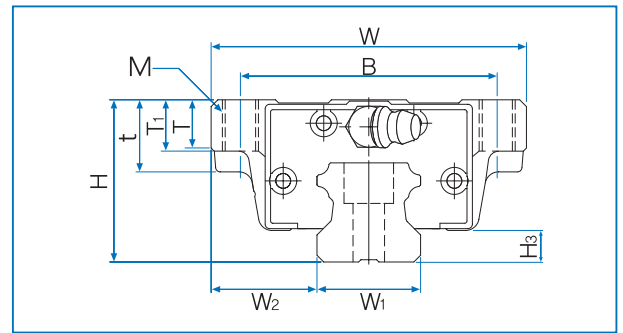
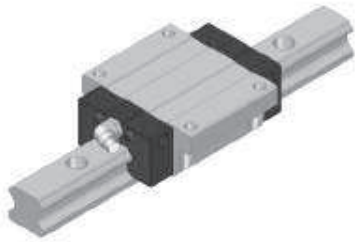
Model No.	H15	H20	H25	H30	H35	H45	H55
Standard length	160	160	220	280	440	570	780
	220	220	280	360	520	675	900
	280	280	340	440	600	780	1020
	⋮	340	400	520	680	885	⋮
	1360	⋮	460	600	760	⋮	2820
	1480	1960	⋮	⋮	⋮	2880	2940
	1600	2080	2200	2520	2680	2985	3060
		2200	2320	2680	2840	3090	
			2440	2840	3000		
Standard pitch P	60	60	60	80	80	105	120
G	20	20	20	20	20	22.5	30
Max. length	4000						

Standard tap hole type of a rail



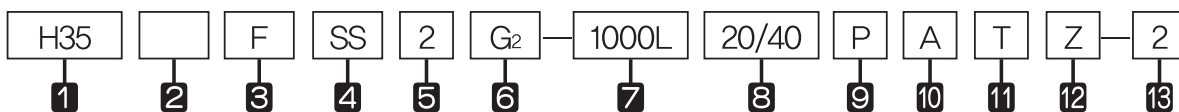
Model No.	S	h(mm)
H15	M5	8
H20	M6	10
H25	M6	12
H30	M8	15
H35	M8	17
H45	M12	24
H55	M14	24

H-F Series, H-FL Series

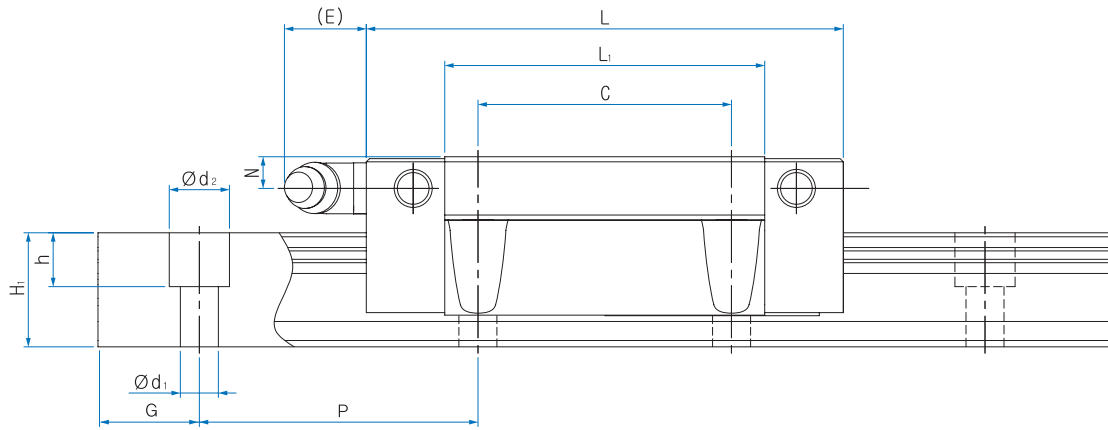


Model No.	External dimensions			Dimensions of block										Grease nipple	H ₃
	Height H	Width W	Length L	B	C	M	L ₁	t	T	T ₁	N	E			
H 15F	24	47	57	38	30	M5	40.8	–	7	11	6	6	A-M4	4.7	
H 15FL	24	47	65.3	38	30	M5	49.1	–	7	11	6	6	A-M4	4.7	
H 20F	30	63	72.7	53	40	M6	53.1	–	9.2	10	7.5	12	B-M6F	6	
H 20FL	30	63	88.6	53	40	M6	69	–	9.2	10	7.5	12	B-M6F	6	
H 25F	36	70	83	57	45	M8	58.3	–	11.5	16	9	12	B-M6F	7	
H 25FL	36	70	102.9	57	45	M8	78.2	–	11.5	16	9	12	B-M6F	7	
H 30F	42	90	97.8	72	52	M10	70.8	–	9.5	18	7.3	12	B-M6F	7.5	
H 30FL	42	90	120	72	52	M10	93	–	9.5	18	7.3	12	B-M6F	7.5	
H 35F	48	100	110	82	62	M10	80.8	–	12.5	21	8	12	B-M6F	9	
H 35FL	48	100	135.4	82	62	M10	106.2	–	12.5	21	8	12	B-M6F	9	
H 45F	60	120	139	100	80	M12	101.9	25	13	15	10	16	B-PT1/8	10	
H 45FL	60	120	170.8	100	80	M12	133.7	25	13	15	10	16	B-PT1/8	10	
H 55F	70	140	163	116	95	M14	117.5	29	19	17	11	16	B-PT1/8	13	
H 55FL	70	140	201.1	116	95	M14	155.6	29	19	17	11	16	B-PT1/8	13	

Composition of Model No.



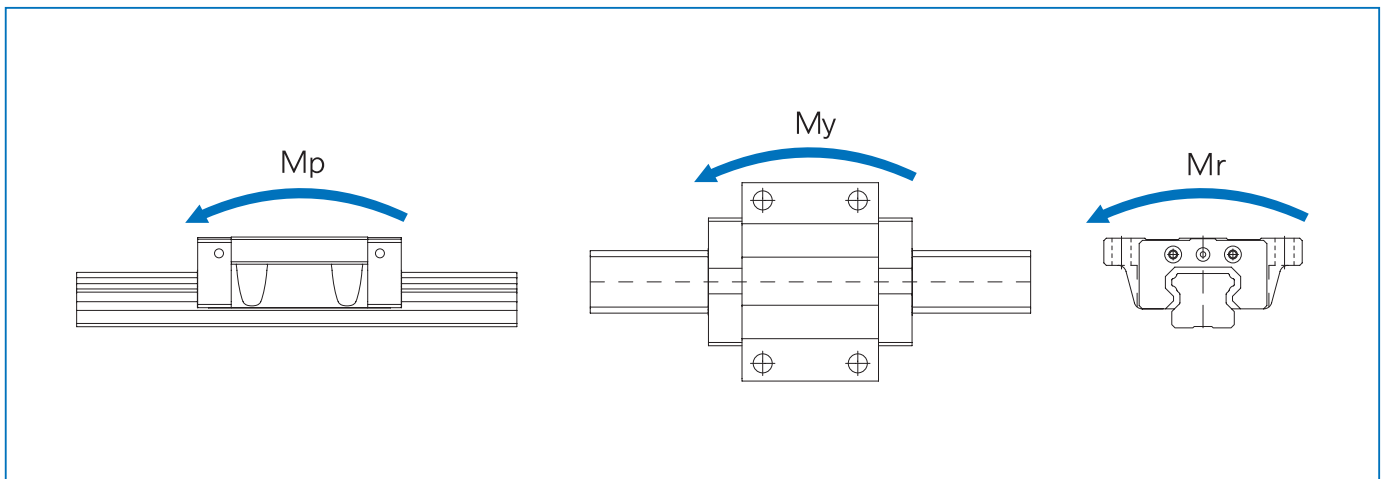
- 1 Model No. of Linear Motion Guide
 - 2 Type of block : No symbol–Full-ball type / S–Spacer Chain type
 - 3 Form of block : R–Rectangular standard type / RL–Rectangular long type / F–Flange standard type / FL–Flange long type
 - 4 Type of seal : UU–End seal / SS–End seal + Inside seal / ZZ–End seal + Inside seal + metal scraper
UULF–End seal + LF seal / SSLF– End seal + Inside seal + LF seal / ZZLF - End seal + Inside seal + metal scraper + LF seal (*1)
 - 5 Number of blocks combined in 1 rail
 - 6 Symbol of clearance : No symbol–Normal preload / G₁–Light preload / G₂–Heavy preload / G_s–Special preload (*2)
 - 7 Length of rail
 - 8 Size of G value : standard G value has no symbol.
 - 9 Symbol of precision : No symbol–Moderate precision / H–High precision / P–Precision / SP–Super Precision / UP–Ultra Precision (*3)
 - 10 No symbol–Rail counter bore type (A topside assembly) / A– Rail tap hole type (an underside assembly) (*4)
 - 11 Connection symbol
 - 12 Special symbol
 - 13 Number of axis used on the same surface
- (*1) See P89 Symbol List of Optional Parts (*2) See P17 Radial Clearance
(*3) See P24 Selection of Precision Class (*4) See P47 Standard tap hole type of a rail



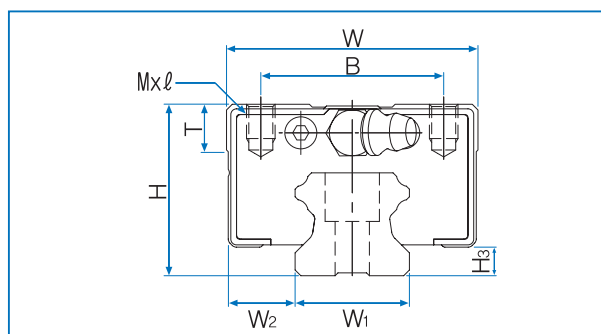
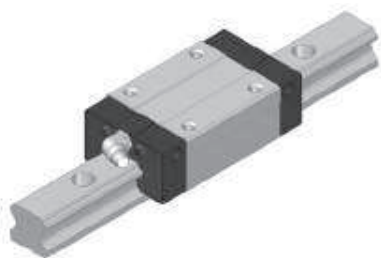
Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN·m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C ₀ kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(contact)	1	2(contact)	1		
15	16	13	20	60	4.5X7.5X5.3	9.9	16.2	0.115	0.552	0.115	0.552	0.129	0.19	1.3
15	16	13	20	60	4.5X7.5X5.3	11.2	19.3	0.165	0.769	0.165	0.769	0.154	0.24	1.3
20	21.5	16.5	20	60	6X9.5X8.5	14.9	23.9	0.221	1.049	0.221	1.049	0.251	0.41	2.2
20	21.5	16.5	20	60	6X9.5X8.5	17.8	30.7	0.370	1.692	0.370	1.692	0.322	0.54	2.2
23	23.5	20	20	60	7X11X9	22.1	33.1	0.337	1.636	0.337	1.636	0.398	0.61	3.0
23	23.5	20	20	60	7X11X9	26.8	43.6	0.596	2.760	0.596	2.760	0.525	0.82	3.0
28	31	26	20	80	9X14X12	38.4	57.1	0.711	3.384	0.711	3.384	0.828	1.1	4.85
28	31	26	20	80	9X14X12	45.9	73.6	1.203	5.506	1.203	5.506	1.067	1.3	4.85
34	33	29	20	80	9X14X12	51.1	74.6	1.062	5.012	1.062	5.012	1.298	1.6	6.58
34	33	29	20	80	9X14X12	61.0	96.2	1.797	8.172	1.797	8.172	1.674	2.01	6.58
45	37.5	38	22.5	105	14X20X17	82.1	116.4	2.860	9.912	2.860	9.912	2.275	2.83	11.03
45	37.5	38	22.5	105	14X20X17	98.2	150.1	4.533	16.161	4.533	16.161	2.935	3.70	11.03
53	43.5	44	30	120	16X23X20	118.1	161.5	4.654	16.016	4.654	16.016	3.779	4.36	15.26
53	43.5	44	30	120	16X23X20	142.0	210.1	7.468	26.493	7.468	26.493	4.916	5.76	15.26

1N≒0.102kgf

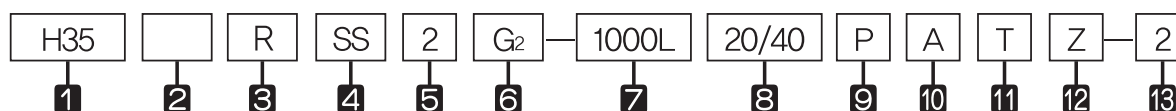


H-R Series, H-RL Series

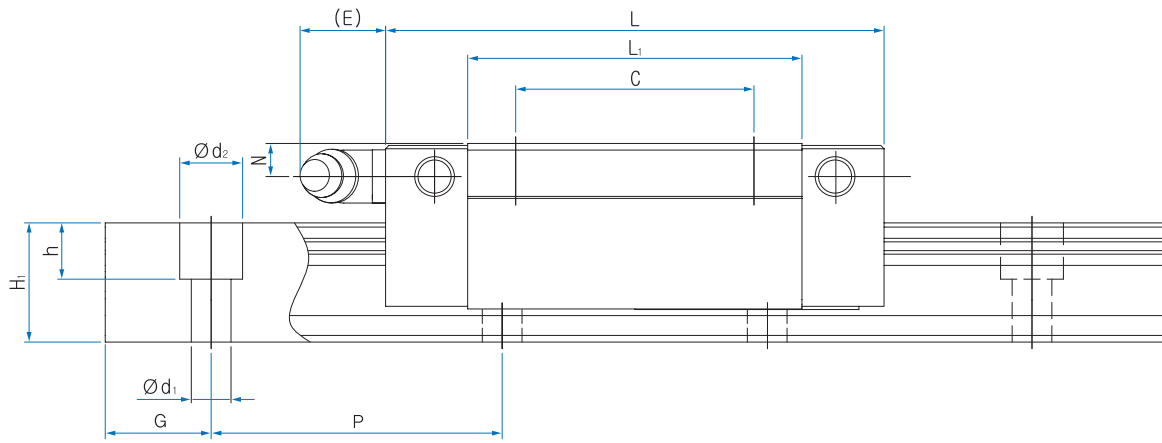


Model No.	External dimensions			Dimensions of block								H ₃
	Height H	Width W	Length L	B	C	M x l	L ₁	T	N	E	Grease nipple	
H 15R	28	34	57	26	26	M4 x 5	40.8	6	10	6	A-M4	4.7
H 15RL	28	34	65.3	26	26	M4 x 5	49.1	6	10	6	A-M4	4.7
H 20R	30	44	72.7	32	36	M5 x 6	53.1	8	7.5	12	B-M6F	6
H 20RL	30	44	88.6	32	50	M5 x 6	69	8	7.5	12	B-M6F	6
H 25R	40	48	83	35	35	M6 x 8	58.3	8	13	12	B-M6F	7
H 25RL	40	48	102.9	35	50	M6 x 8	78.2	8	13	12	B-M6F	7
H 30R	45	60	97.8	40	40	M8 x 10	70.8	8	10.3	12	B-M6F	7.5
H 30RL	45	60	120	40	60	M8 x 10	93	8	10.3	12	B-M6F	7.5
H 35R	55	70	110	50	50	M8 x 12	80.8	10	15	12	B-M6F	9
H 35RL	55	70	135.4	50	72	M8 x 12	106.2	10	15	12	B-M6F	9
H 45R	70	86	139	60	60	M10 x 17	101.9	15	20	16	B-PT1/8	10
H 45RL	70	86	170.8	60	80	M10 x 17	133.7	15	20	16	B-PT1/8	10
H 55R	80	100	163	75	75	M12 x 18	117.5	18	21	16	B-PT1/8	13
H 55RL	80	100	201.1	75	95	M12 x 18	155.6	18	21	16	B-PT1/8	13

Composition of Model No.



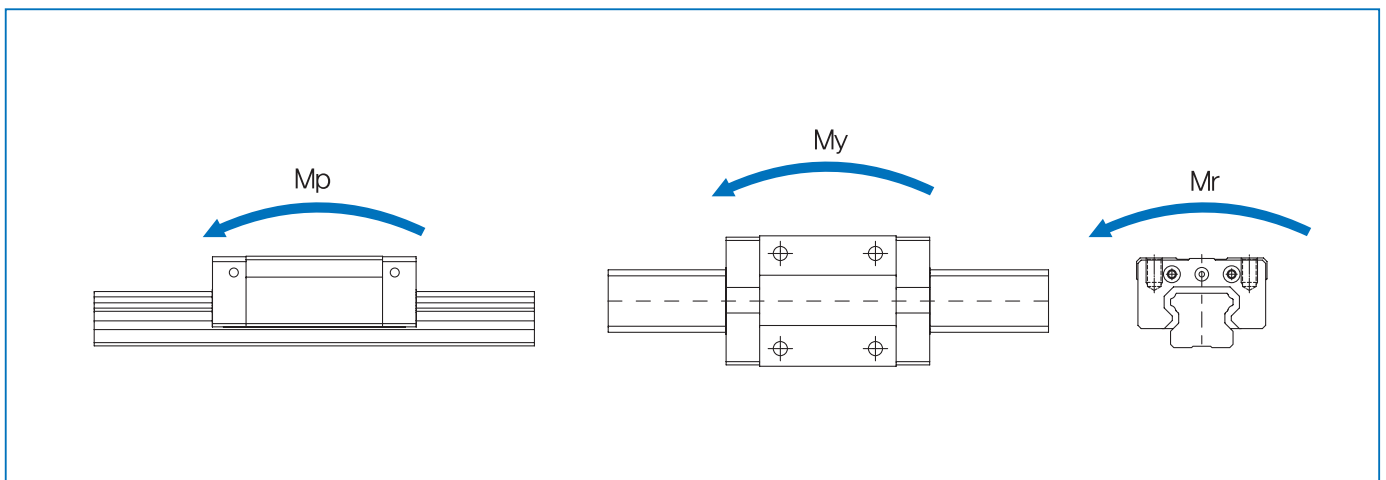
- 1 Model No. of Linear Motion Guide
 - 2 Type of block : No symbol—Full-ball type / S—Spacer Chain type
 - 3 Form of block : R—Rectangular standard type / RL—Rectangular long type / F—Flange standard type / FL—Flange long type
 - 4 Type of seal : UU—End seal / SS—End seal + Inside seal / ZZ—End seal + Inside seal + metal scraper
UULF—End seal + LF seal / SSLF—End seal + Inside seal + LF seal / ZZLF—End seal + Inside seal + metal scraper + LF seal (*1)
 - 5 Number of blocks combined in 1 rail
 - 6 Symbol of clearance : No symbol—Normal preload / G₁—Light preload / G₂—Heavy preload / G_s—Special preload (*2)
 - 7 Length of rail
 - 8 Size of G value : standard G value has no symbol.
 - 9 Symbol of precision : No symbol—Moderate precision / H—High precision / P—Precision / SP—Super Precision / UP—Ultra Precision (*3)
 - 10 No symbol—Rail counter bore type (A topside assembly) / A—Rail tap hole type (an underside assembly) (*4)
 - 11 Connection symbol
 - 12 Special symbol
 - 13 Number of axis used on the same surface
- (*1) See P89 Symbol List of Optional Parts (*2) See P17 Radial Clearance
(*3) See P24 Selection of Precision Class (*4) See P47 Standard tap hole type of a rail



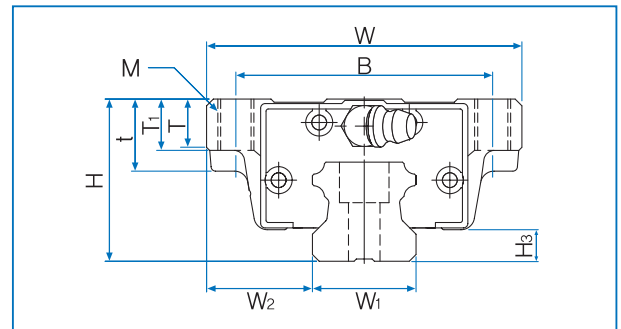
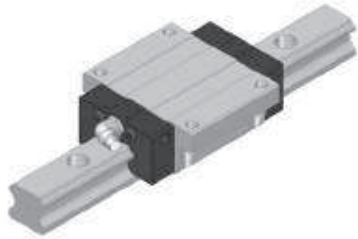
Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN·m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C ₀ kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(contact)	1	2(contact)	1		
15	9.5	13	20	60	4.5x7.5x5.3	9.9	16.2	0.115	0.552	0.115	0.552	0.129	0.18	1.3
15	9.5	13	20	60	4.5x7.5x5.3	11.2	19.3	0.165	0.769	0.165	0.769	0.154	0.23	1.3
20	12	16.5	20	60	6x9.5x8.5	14.9	23.9	0.221	1.049	0.221	1.049	0.251	0.31	2.2
20	12	16.5	20	60	6x9.5x8.5	17.8	30.7	0.370	1.692	0.370	1.692	0.322	0.41	2.2
23	12.5	20	20	60	7x11x9	22.1	33.1	0.337	1.636	0.337	1.636	0.398	0.53	3.0
23	12.5	20	20	60	7x11x9	26.8	43.6	0.596	2.760	0.596	2.760	0.525	0.71	3.0
28	16	26	20	80	9x14x12	38.4	57.1	0.711	3.384	0.711	3.384	0.828	0.9	4.85
28	16	26	20	80	9x14x12	45.9	73.6	1.203	5.506	1.203	5.506	1.067	1.1	4.85
34	18	29	20	80	9x14x12	51.1	74.6	1.062	5.012	1.062	5.012	1.298	1.5	6.58
34	18	29	20	80	9x14x12	61.0	96.2	1.797	8.172	1.797	8.172	1.674	2.01	6.58
45	20.5	38	22.5	105	14x20x17	82.1	116.4	2.860	9.912	2.860	9.912	2.275	2.89	11.03
45	20.5	38	22.5	105	14x20x17	98.2	150.1	4.533	16.161	4.533	16.161	2.935	3.74	11.03
53	23.5	44	30	120	16x23x20	118.1	161.5	4.654	16.016	4.654	16.016	3.779	4.28	15.26
53	23.5	44	30	120	16x23x20	142.0	210.1	7.468	26.493	7.468	26.493	4.916	5.59	15.26

1N=0.102kgf

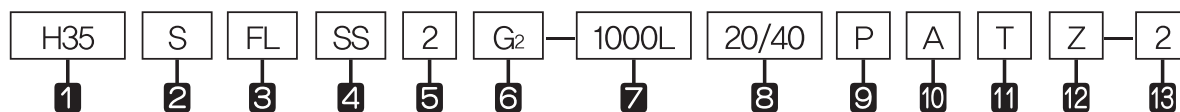


H-SF Series, H-SFL Series

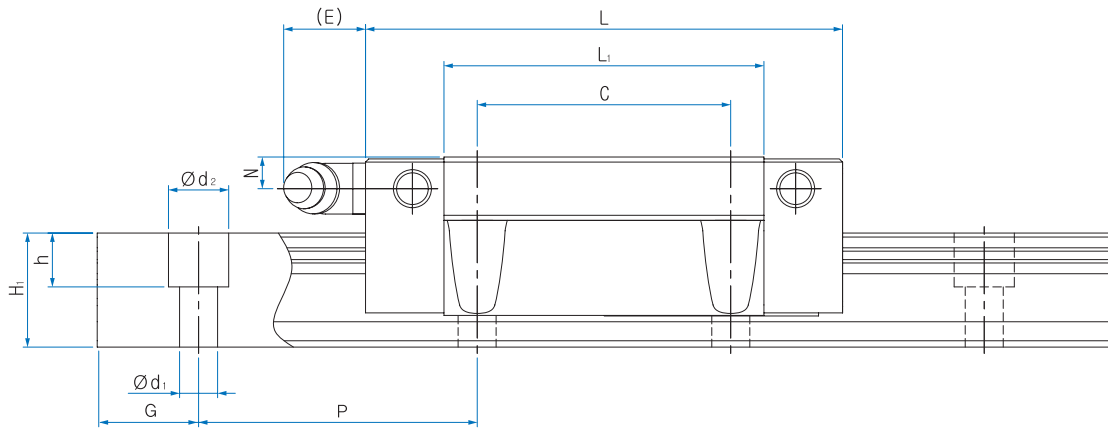


Model No.	External dimensions			Dimensions of block										H ₃
	Height H	Width W	Length L	B	C	M	L ₁	t	T	T ₁	N	E	Grease nipple	
H 15SF	24	47	56.9	38	30	M5	40.7	-	7	11	6	6	A-M4	4.7
H 15SFL	24	47	65.3	38	30	M5	49.1	-	7	11	6	6	A-M4	4.7
H 20SF	30	63	72.7	53	40	M6	53.1	-	9.2	10	7.5	12	B-M6F	6
H 20SFL	30	63	88.6	53	40	M6	69	-	9.2	10	7.5	12	B-M6F	6
H 25SF	36	70	83	57	45	M8	58.3	-	11.5	16	9	12	B-M6F	7
H 25SFL	36	70	102.9	57	45	M8	78.2	-	11.5	16	9	12	B-M6F	7
H 30SF	42	90	97.8	72	52	M10	70.8	-	9.5	18	7.3	12	B-M6F	7.5
H 30SFL	42	90	120	72	52	M10	93	-	9.5	18	7.3	12	B-M6F	7.5
H 35SF	48	100	110	82	62	M10	80.8	-	12.5	21	8	12	B-M6F	9
H 35SFL	48	100	135.4	82	62	M10	106.2	-	12.5	21	8	12	B-M6F	9

Composition of Model No.



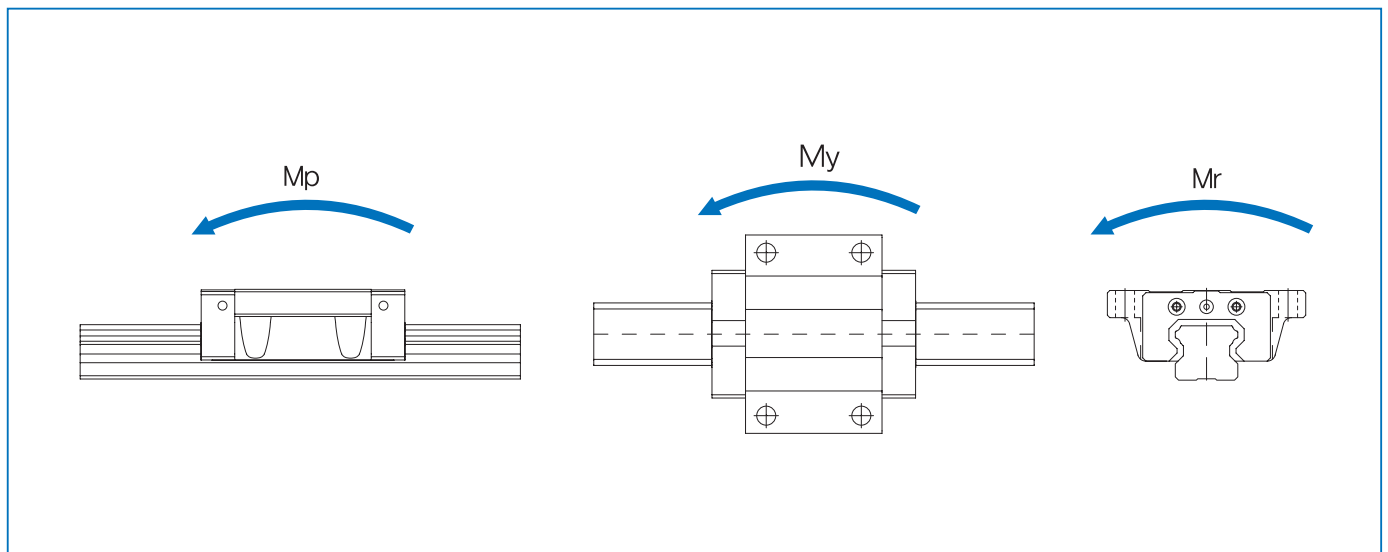
- 1 Model No. of Linear Motion Guide
 - 2 Type of block : **No symbol**–Full-ball type / **S**–Spacer Chain type
 - 3 Form of block : **R**–Rectangular standard type / **RL**–Rectangular long type / **F**–Flange standard type / **FL**–Flange long type
 - 4 Type of seal : **UU**–End seal / **SS**–End seal + Inside seal / **ZZ**–End seal + Inside seal + metal scraper
UULF–End seal + LF seal / **SSLF**–End seal + Inside seal + LF seal / **ZZLF**–End seal + Inside seal + metal scraper + LF seal (*1)
 - 5 Number of blocks combined in 1 rail
 - 6 Symbol of clearance : **No symbol**–Normal preload / **G₁**–Light preload / **G₂**–Heavy preload / **G_s**–Special preload (*2)
 - 7 Length of rail
 - 8 Size of G value : standard G value has no symbol.
 - 9 Symbol of precision : **No symbol**–Moderate precision / **H**–High precision / **P**–Precision / **SP**–Super Precision / **UP**–Ultra Precision (*3)
 - 10 **No symbol**–Rail counter bore type (A topside assembly) / **A**– Rail tap hole type (an underside assembly) (*4)
 - 11 Connection symbol
 - 12 Special symbol
 - 13 Number of axis used on the same surface
- (*1) See P89 Symbol List of Optional Parts (*2) See P17 Radial Clearance
(*3) See P24 Selection of Precision Class (*4) See P47 Standard tap hole type of a rail



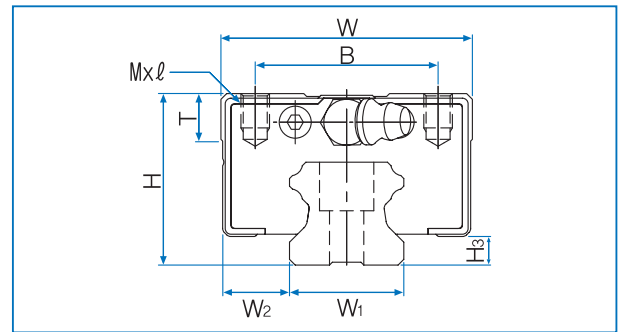
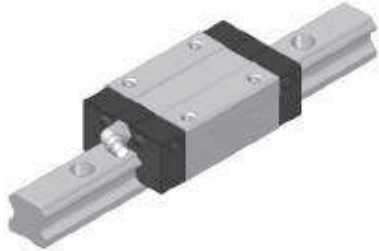
Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN · m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C ₀ kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(Contact)	1	2(Contact)	1		
15	16	13	20	60	4.5X7.5X5.3	12.1	16.2	0.115	0.552	0.115	0.552	0.129	0.19	1.3
15	16	13	20	60	4.5X7.5X5.3	13.7	19.3	0.165	0.769	0.165	0.769	0.154	0.24	1.3
20	21.5	16.5	20	60	6X9.5X8.5	17.6	23.9	0.221	1.049	0.221	1.049	0.251	0.41	2.2
20	21.5	16.5	20	60	6X9.5X8.5	21.1	30.7	0.370	1.692	0.370	1.692	0.322	0.54	2.2
23	23.5	20	20	60	7X11X9	25.8	33.1	0.337	1.636	0.337	1.636	0.398	0.61	3.0
23	23.5	20	20	60	7X11X9	31.7	43.6	0.596	2.760	0.596	2.760	0.525	0.82	3.0
28	31	26	20	80	9x14x12	48	57.1	0.711	3.384	0.711	3.384	0.828	1.1	4.85
28	31	26	20	80	9x14x12	58	73.6	1.203	5.506	1.203	5.506	1.067	1.3	4.85
34	33	29	20	80	9x14x12	63.7	74.6	1.062	5.012	1.062	5.012	1.298	1.6	6.58
34	33	29	20	80	9x14x12	77.1	96.2	1.797	8.172	1.797	8.172	1.674	2.01	6.58

1N≒0.102kgf

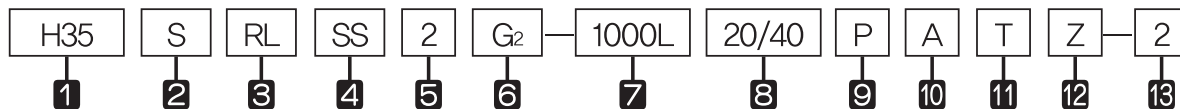


H-SR Series, H-SRL Series



Model No.	External dimensions			Dimensions of block								H ₃
	Height H	Width W	Length L	B	C	M X l	L ₁	T	N	E	Grease nipple	
H 15SR	28	34	56.9	26	26	M4 x 5	40.7	6	10	6	A-M4	4.7
H 15SRL	28	34	65.3	26	26	M4 x 5	49.1	6	10	6	A-M4	4.7
H 20SR	30	44	72.7	32	36	M5 x 6	53.1	8	7.5	12	B-M6F	6
H 20SRL	30	44	88.6	32	50	M5 x 6	69	8	7.5	12	B-M6F	6
H 25SR	40	48	83	35	35	M6 x 8	58.3	8	13	12	B-M6F	7
H 25SRL	40	48	102.9	35	50	M6 x 8	78.2	8	13	12	B-M6F	7
H 30SR	45	60	97.8	40	40	M8x10	70.8	8	10.3	12	B-M6F	7.5
H 30SRL	45	60	120	40	60	M8x10	93	8	10.3	12	B-M6F	7.5
H 35SR	55	70	110	50	50	M8x12	80.8	10	15	12	B-M6F	9
H 35SRL	55	70	135.4	50	72	M8x12	106.2	10	15	12	B-M6F	9

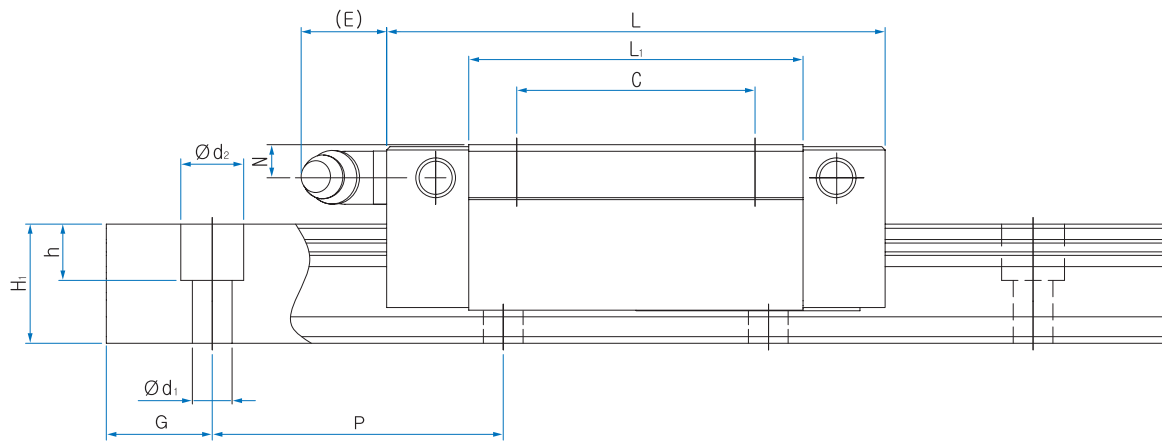
Composition of Model No.



- 1 Model No. of Linear Motion Guide
- 2 Type of block : No symbol–Full-ball type / S–Spacer Chain type
- 3 Form of block : R–Rectangular standard type / RL–Rectangular long type / F–Flange standard type / FL–Flange long type
- 4 Type of seal : UU–End seal / SS–End seal + Inside seal / ZZ–End seal + Inside seal + metal scraper
UULF–End seal + LF seal / SSLF–End seal + Inside seal + LF seal / ZZLF – End seal + Inside seal + metal scraper + LF seal (*1)
- 5 Number of blocks combined in 1 rail
- 6 Symbol of clearance : No symbol–Normal preload / G₁–Light preload / G₂–Heavy preload / G_s–Special preload (*2)
- 7 Length of rail
- 8 Size of G value : standard G value has no symbol.
- 9 Symbol of precision : No symbol–Moderate precision / H–High precision / P–Precision / SP–Super Precision / UP–Ultra Precision (*3)
- 10 No symbol–Rail counter bore type (A topside assembly) / A– Rail tap hole type (an underside assembly) (*4)
- 11 Connection symbol
- 12 Special symbol
- 13 Number of axis used on the same surface

(*1) See P89 Symbol List of Optional Parts (*2) See P17 Radial Clearance

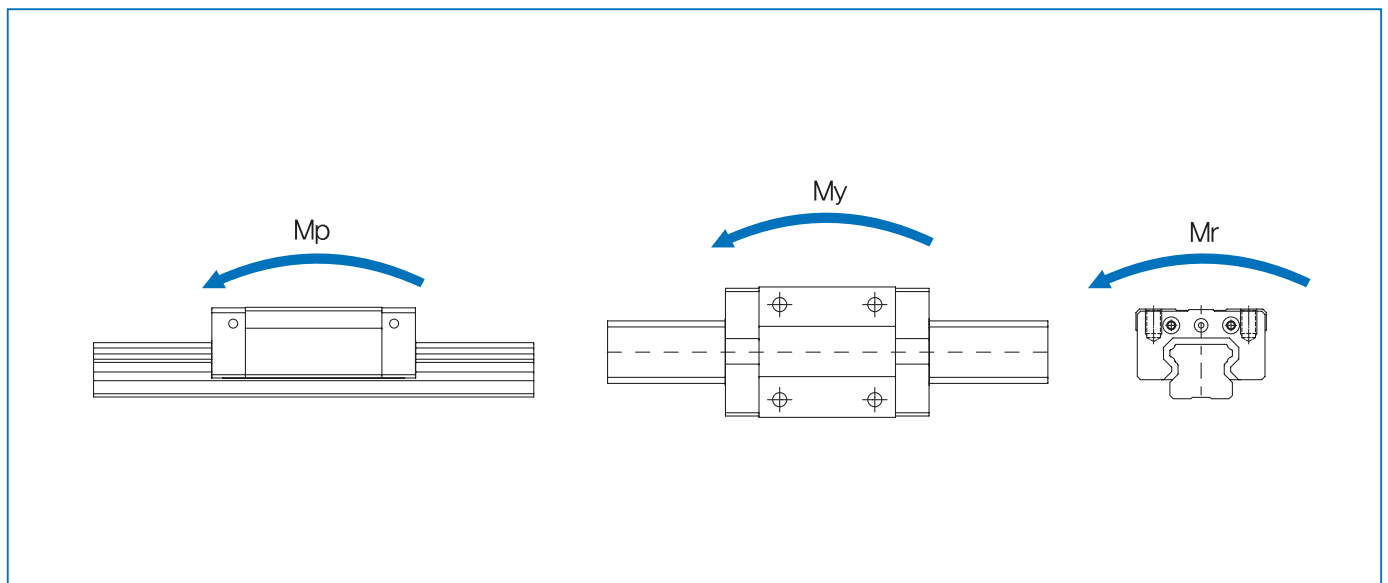
(*3) See P24 Selection of Precision Class (*4) See P47 Standard tap hole type of a rail



Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN · m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C ₀ kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(Contact)	1	2(Contact)	1		
15	9.5	13	20	60	4.5X7.5X5.3	12.1	16.2	0.115	0.552	0.115	0.552	0.129	0.18	1.3
15	9.5	13	20	60	4.5X7.5X5.3	13.7	19.3	0.165	0.769	0.165	0.769	0.154	0.23	1.3
20	12	16.5	20	60	6X9.5X8.5	17.6	23.9	0.221	1.049	0.221	1.049	0.251	0.31	2.2
20	12	16.5	20	60	6X9.5X8.5	21.1	30.7	0.370	1.692	0.370	1.692	0.322	0.41	2.2
23	12.5	20	20	60	7X11X9	25.8	33.1	0.337	1.636	0.337	1.636	0.398	0.53	3.0
23	12.5	20	20	60	7X11X9	31.7	43.6	0.596	2.760	0.596	2.760	0.525	0.71	3.0
28	16	26	20	80	9x14x12	48	57.1	0.711	3.384	0.711	3.384	0.828	0.9	4.85
28	16	26	20	80	9x14x12	58	73.6	1.203	5.506	1.203	5.506	1.067	1.1	4.85
34	18	29	20	80	9x14x12	63.7	74.6	1.062	5.012	1.062	5.012	1.298	1.5	6.58
34	18	29	20	80	9x14x12	77.1	96.2	1.797	8.172	1.797	8.172	1.674	2.01	6.58

1N≒0.102kgf



3. Slim Linear Motion Guide S Series

1) Structure of S Series

Linear Motion Guide S Series has a four-row circular arc-groove structure and is a 4-direction equal load type. It also has an auto-adjusting face-to-face D/F structure. It uses balls as a rolling element and is a slim-type guide with a low sectional height as well as high rigidity and less noise.

2) Features of S Series

- a. High quality and very effective in realizing high precision and elimination of labor
- b. High rigidity and high precision which can realize the stable travel for a long time
- c. Great wear resistance and friction resistance which ensures a long life
- d. Great auto-adjusting and error-absorbing abilities with the face-to-face duplex structure same to D/F combination of ball bearing
- e. Various specifications for easy design
- f. Easy to use due to great compatibility between a rail and a block
- g. 4-direction equal load and high-rigidity structure
- h. Slim shape suitable for horizontal motion to ensure stable running

4. Slim Spacer Chain Linear Motion Guide S-S Series

1) Structure of S Series

Linear Motion Guide S-S Series has a 4-direction equal load type which is identical to S Series and has an auto-adjusting face-to-face D/F structure.

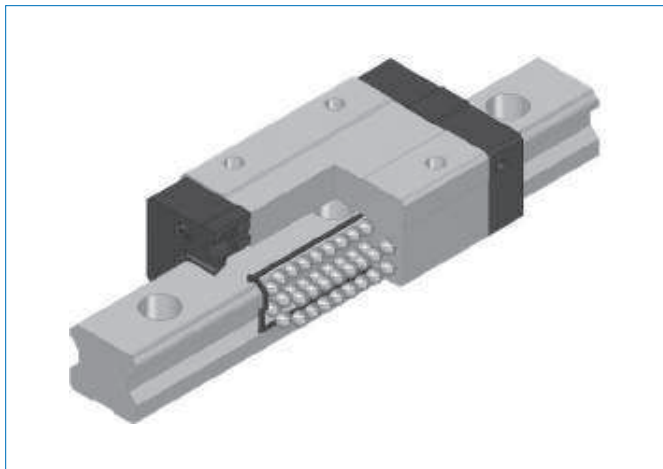
It uses balls as a rolling element and combines a spacer between balls to prevent them from colliding each other during the rolling motion.

Therefore it makes less noise and more stable circulating motion than a full-ball type to realize quiet running even in high velocity movement and the spacer act as the pocket of lubricant to obtain longer life than H Series.

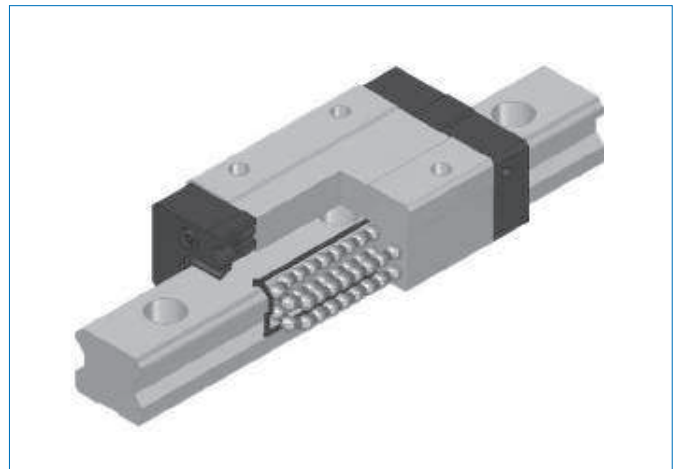
2) Features of S-S Series

- a. As a spacer-incorporated type which improves frictional properties and prevents the collision of balls, it not only allows stable circulating motion and smooth running but also reduces noise. If special lubricating seal is attached to lengthen life, maintenance-free operations can be achieved.
- b. Collision between balls and the loss of oil film are prevented by applying a resin spacer to improve life and generate less particles and dust.
- c. High quality in realizing high precision and high velocity so it could create large effect on elimination of power loss.
- d. High rigidity and high precision which can realize the stable travel for a long time
- e. Great wear resistance and friction resistance which ensures a long life
- f. Great auto-adjusting and error-absorbing abilities with the face-to-face duplex structure same to D/F combination of ball bearing
- g. Various specifications for easy design
- h. Easy to use due to great compatibility between a rail and a block

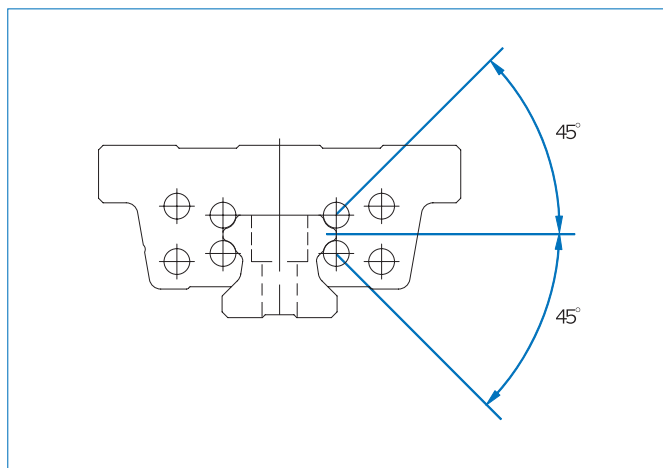
Slim Linear Motion Guide S, S-S Series



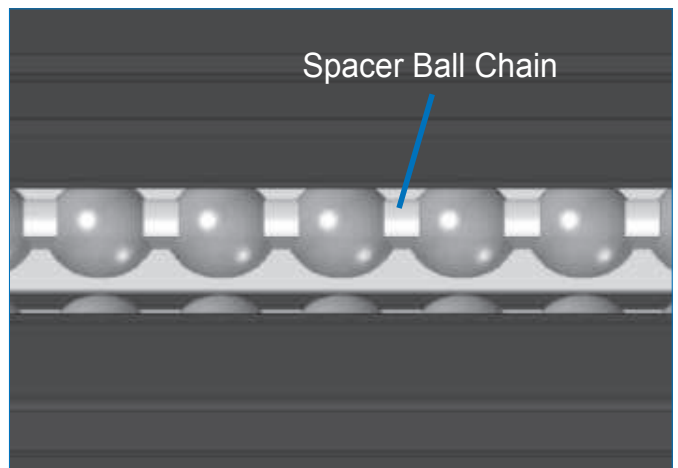
S Series (Full-ball Type)



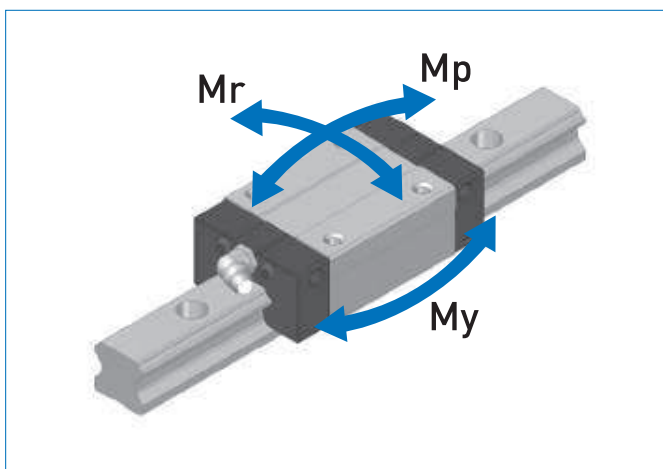
S-S Series (Spacer Chain Type)



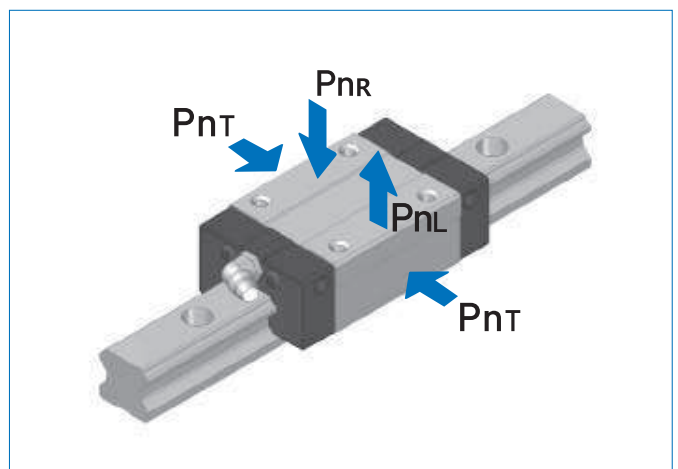
Cross Section



Detail of Raceway of S-S Series


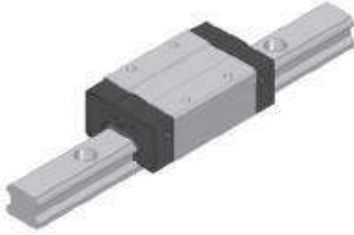
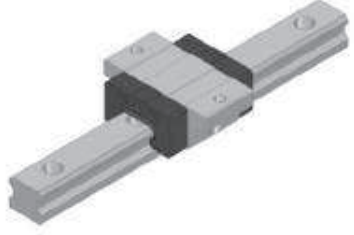
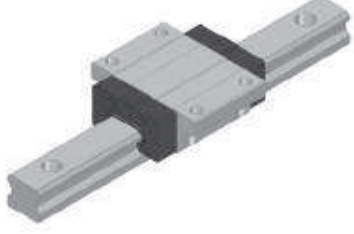


Moment Rigidity



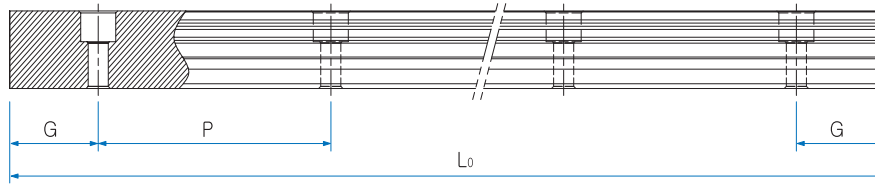
Radial Rigidity

Types and Features

Category	Type	Shape & Features	
Compact type	S-C S-SC		<ul style="list-style-type: none"> - With the tapped flange of a block, a slim compact that the width and length of Linear Motion guide block is minimized - A 4-direction equal load type with 45° contact angle <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer chain is applied.</p>
	S-R S-SR		<ul style="list-style-type: none"> - Having the cross section identical to that of S-C Series, a slim compact type that the width and length of Linear Motion guide block is minimized - A 4-direction equal load type with 45° contact angle <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer chain is applied.</p>
Flange type	S-CF S-SCF		<ul style="list-style-type: none"> - With the tapped flange of a block, a slim compact type that the width and length of Linear Motion guide block is minimized - A 4-direction equal load type with 45° contact angle <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer chain is applied.</p>
	S-F S-SF		<ul style="list-style-type: none"> - Having the cross section identical to that of S-CF Series, a slim compact type that the width and length of Linear Motion guide block is minimized - A 4-direction equal load type with 45° contact angle <p>S Series is a low-noise low-dust raise type with improved life due to zero friction between balls since a spacer chain is applied.</p>

Cartesian coordinated robot,
linear actuator,
automation system,
semiconductor/
display manufacturing system,
LED inspection equipment,
dispenser equipment,
medical Equipment,
high-speed transport system,
woodworking machine,
take-out robots,
small machine tool,
laser processor,
precision measurement equipment

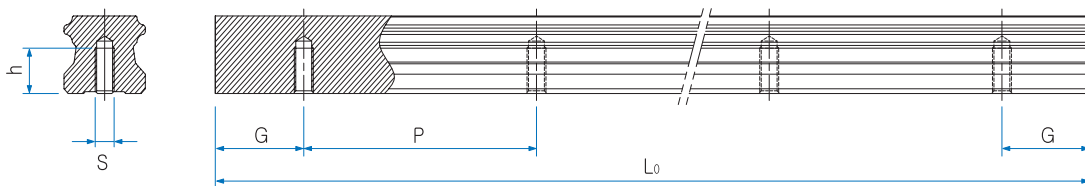
Standard tap hole type of a rail



Unit : mm

Model No.	S15	S20	S25
Standard length	160	160	220
	220	220	280
	280	280	340
	⋮	340	400
	1360	⋮	460
	1480	1960	⋮
	1600	2080	2200
		2200	2320
Standard pitch P	60	60	60
G	20	20	20
Max. length	4000		

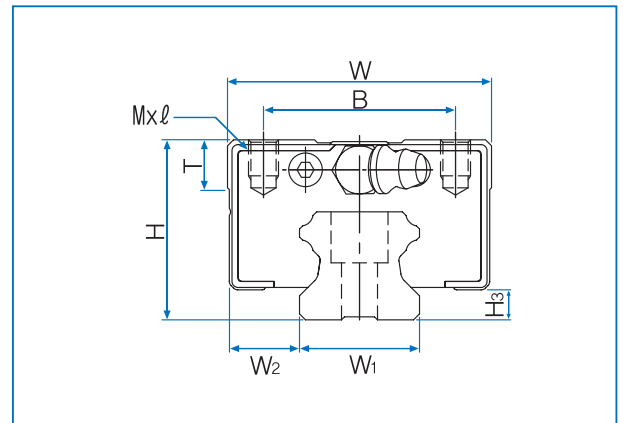
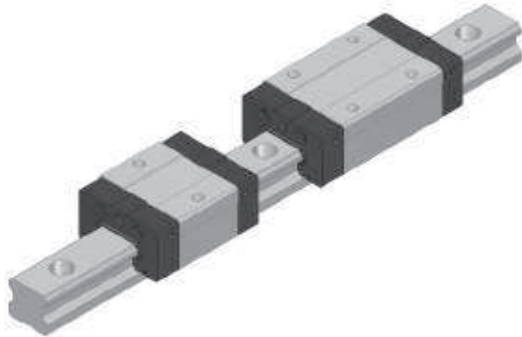
Standard tap hole type of a rail



Unit : mm

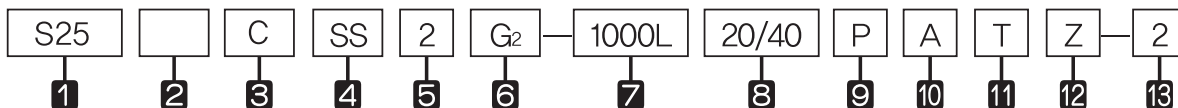
Model No.	S	h(mm)
H15	M5	8
H20	M6	10
H25	M6	12

S-C Series, S-R Series



Model No.	External dimensions			Dimensions of block								Grease nipple	H ₃
	Height H	Width W	Length L	B	C	M x l	L ₁	T	N	E			
S 15C	24	34	40,2	26	—	M4 x 6	24	6	6	6	A-M4	4,5	
S 15R			56,9		26		40,7						
S 20C	28	42	47,2	32	—	M5 x 7	27,6	7,5	5,5	12	B-M6F	6	
S 20R			66,3		32		46,7						
S 25C	33	48	59,1	35	—	M6 x 9	34,4	8	6	12	B-M6F	7	
S 25R			83		35		58,2						

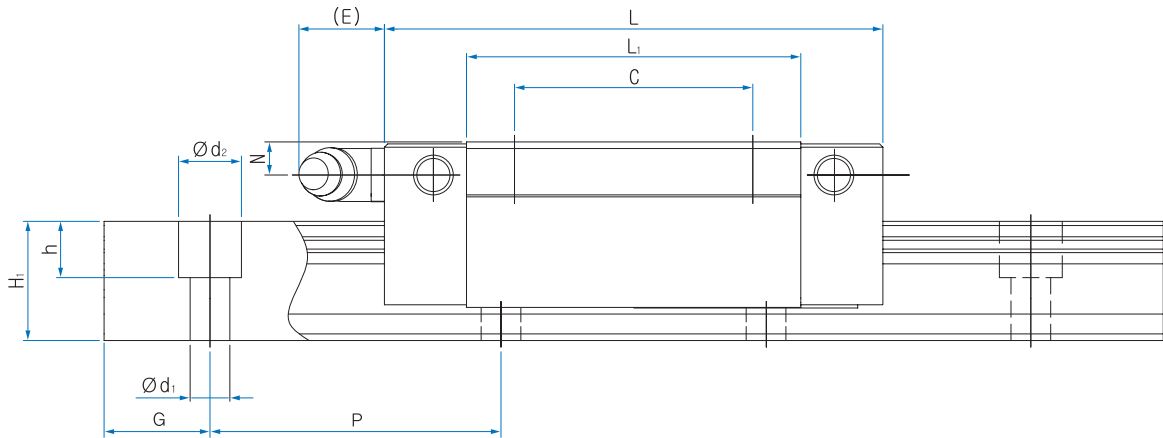
Composition of Model No.



- 1 Model No. of Linear Motion Guide
- 2 Type of block : No symbol—Full-ball type / S—Spacer Chain type
- 3 Form of block : C—Rectangular short type / R—Rectangular standard type / CF—Flange short type / F—Flange standard type
- 4 Type of seal : UU—End seal / SS—End seal + Inside seal / ZZ—End seal + Inside seal + metal scraper
UULF—End seal + LF seal / SSLF—End seal + Inside seal + LF seal / ZZLF—End seal + Inside seal + metal scraper + LF seal (*1)
- 5 Number of blocks combined in 1 rail
- 6 Symbol of clearance : No symbol—Normal preload / G₁—Light preload / G₂—Heavy preload / G_s—Special preload (*2)
- 7 Length of rail
- 8 Size of G value : standard G value has no symbol.
- 9 Symbol of precision : No symbol—Moderate precision / H—High precision / P—Precision / SP—Super Precision / UP—Ultra Precision (*3)
- 10 No symbol—Rail counter bore type (A topside assembly) / A—Rail tap hole type (an underside assembly)(*4)
- 11 Connection symbol
- 12 Special symbol
- 13 Number of axis used on the same surface

(*1) See P77 Symbol List of Optional Parts (*2) See P17 Radial Clearance

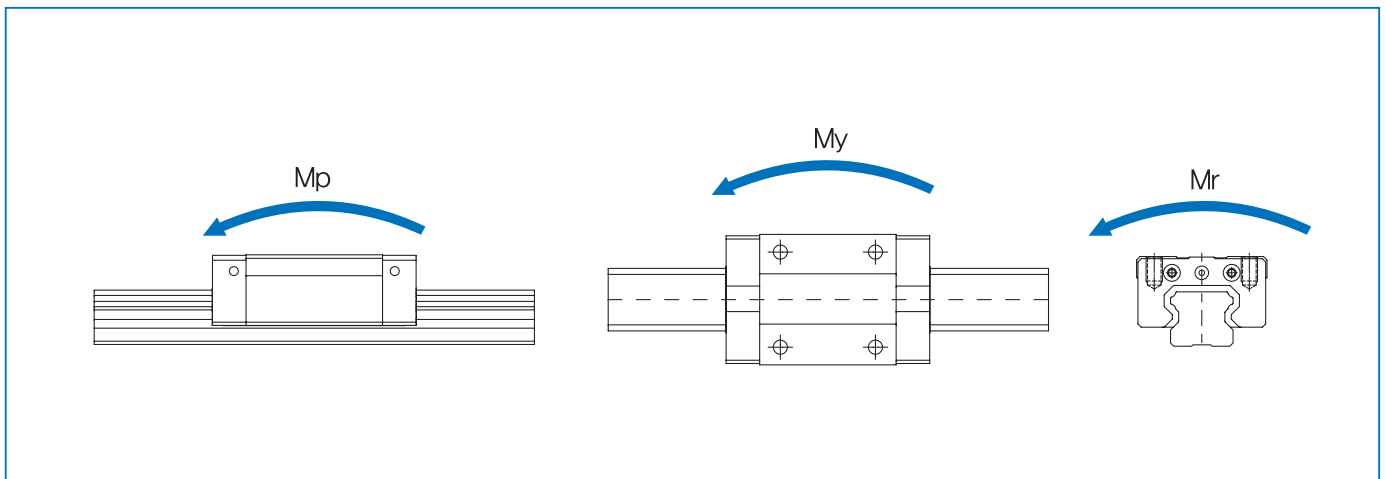
(*3) See P24 Selection of Precision Class (*4) See P59 The reference for standard tap hole type of a rail



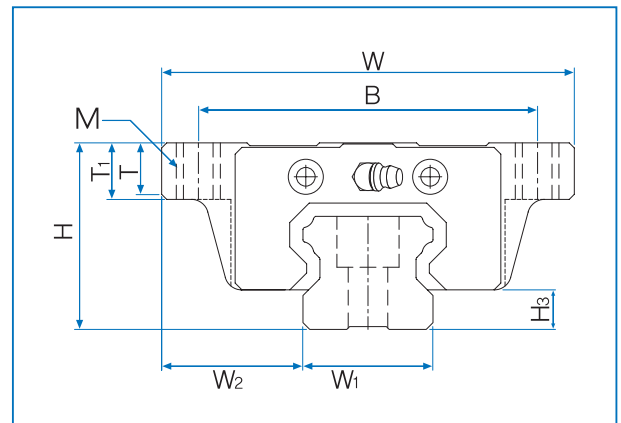
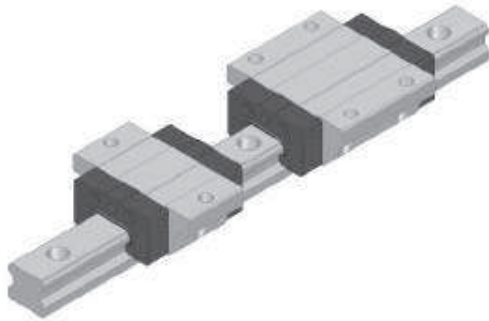
Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN·m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C ₀ kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(contact)	1	2(contact)	1		
15	9.5	13	20	60	4.5x7.5x5.3	7.0	10.0	0.042	0.224	0.042	0.224	0.079	0.096	1.3
						9.9	16.2	0.115	0.552	0.115	0.552	0.129	0.156	
20	11	16.5	20	60	6x9.5x8.5	9.8	13.1	0.063	0.342	0.063	0.342	0.137	0.153	2.2
						13.7	21.2	0.173	0.838	0.173	0.838	0.223	0.246	
23	12.5	20	20	60	7x11x9	15.7	20.4	0.123	0.670	0.123	0.670	0.246	0.254	3.0
						22.1	33.1	0.337	1.636	0.337	1.636	0.398	0.413	

1N≒0.102kgf

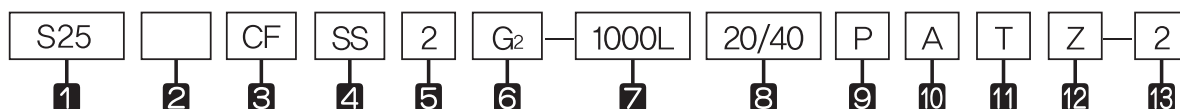


S-CF Series, S-F Series



Model No.	External dimensions			Dimensions of block									Grease nipple	H ₃
	Height H	Width W	Length L	B	C	M x ℓ	L ₁	T	T ₁	N	E			
S 15CF	24	52	40,2	41	—	M5	24	6	7	6	6	A-M4	4.5	
S 15F			56,9		26		40,7							
S 20CF	28	59	47,2	49	—	M6	27,6	8	9	5,5	12	B-M6F	6	
S 20F			66,3		32		46,7							
S 25CF	33	73	59,1	60	—	M8	34,4	9	10	6	12	B-M6F	7	
S 25F			83		35		58,2							

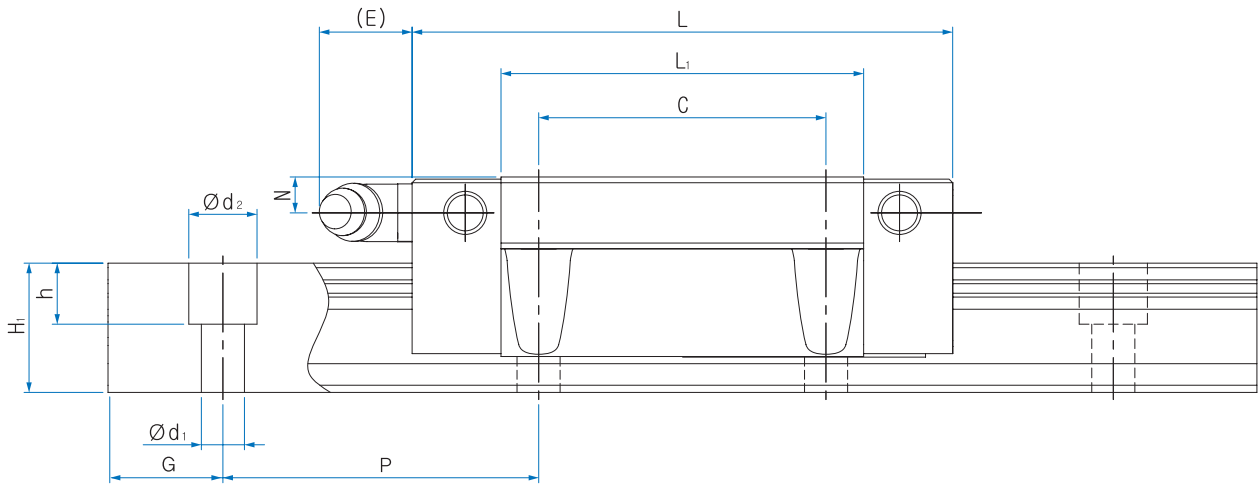
Composition of Model No.



- 1 Model No. of Linear Motion Guide
- 2 Type of block : No symbol—Full-ball type / S—Spacer Chain type
- 3 Form of block : C—Rectangular short type / R—Rectangular standard type / CF—Flange short type / F—Flange standard type
- 4 Type of seal : UU—End seal / SS—End seal + Inside seal / ZZ—End seal + Inside seal + metal scraper
UULF—End seal + LF seal / SSLF—End seal + Inside seal + LF seal / ZZLF—End seal + Inside seal + metal scraper + LF seal (*1)
- 5 Number of blocks combined in 1 rail
- 6 Symbol of clearance : No symbol—Normal preload / G₁—Light preload / G₂—Heavy preload / G_s—Special preload (*2)
- 7 Length of rail
- 8 Size of G value : standard G value has no symbol.
- 9 Symbol of precision : No symbol—Moderate precision / H—High precision / P—Precision / SP—Super Precision / UP—Ultra Precision (*3)
- 10 No symbol—Rail counter bore type (A topside assembly) / A—Rail tap hole type (an underside assembly) (*4)
- 11 Connection symbol
- 12 Special symbol
- 13 Number of axis used on the same surface

(*1) See P77 Symbol List of Optional Parts (*2) See P17 Radial Clearance

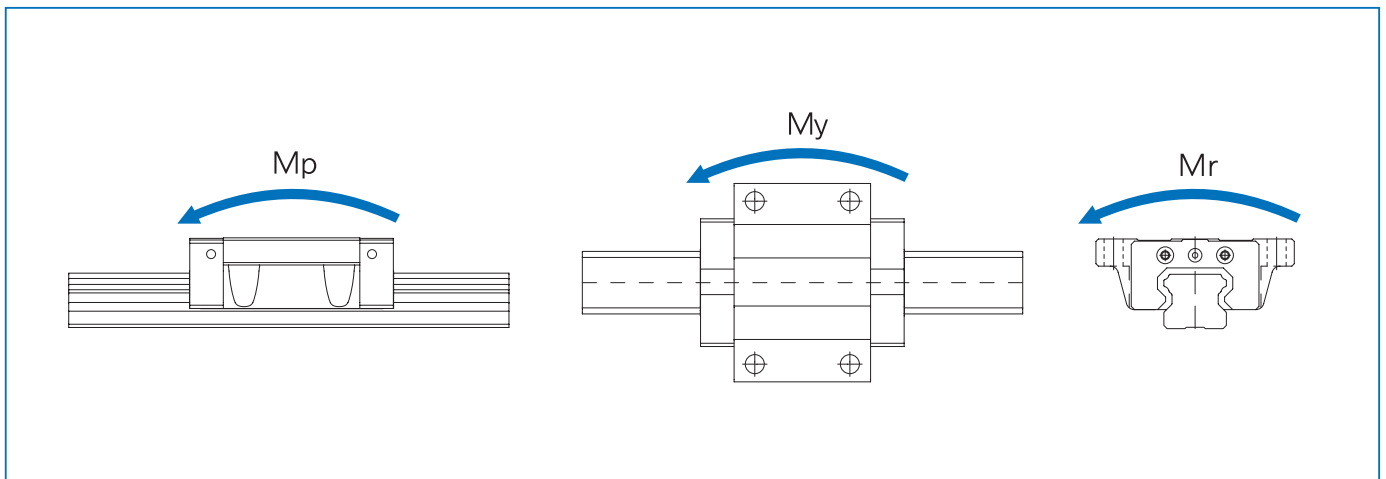
(*3) See P24 Selection of Precision Class (*4) See P59 The reference for standard tap hole type of a rail



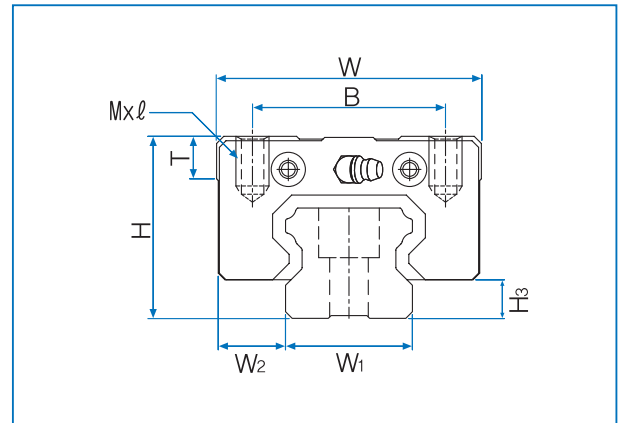
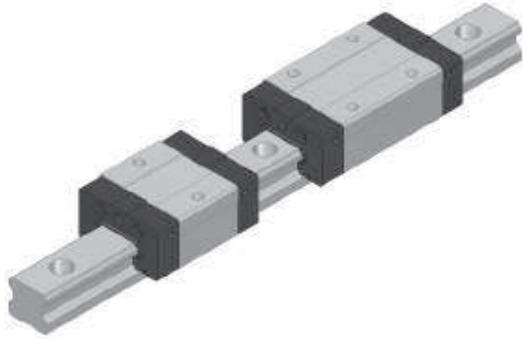
Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN·m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C _o kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(contact)	1	2(contact)	1		
15	18.5	13	20	60	4.5x7.5x5.3	7.0	10.0	0.042	0.224	0.042	0.224	0.079	0.125	1.3
						9.9	16.2	0.115	0.552	0.115	0.552	0.129	0.203	
20	19.5	16.5	20	60	6x9.5x8.5	9.8	13.1	0.063	0.342	0.063	0.342	0.137	0.187	2.2
						13.7	21.2	0.173	0.838	0.173	0.838	0.223	0.301	
23	25	20	20	60	7x11x9	15.7	20.4	0.123	0.670	0.123	0.670	0.246	0.320	3.0
						22.1	33.1	0.337	1.636	0.337	1.636	0.398	0.527	

1N≒0.102kgf

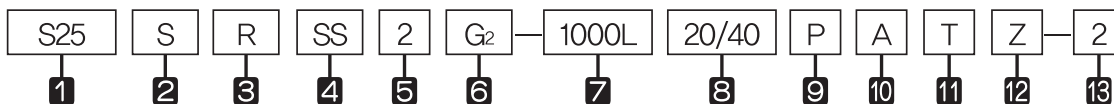


S-SC Series, S-SR Series



Model No.	External dimensions			Dimensions of block								H ₃
	Height H	Width W	Length L	B	C	M X l	L ₁	T	N	E	Grease nipple	
S 15SC	24	34	40.2	26	—	M4 x 6	24	6	6	6	A-M4	4.5
S 15SR			56.9		26		40.7					
S 20SC	28	42	47.2	32	—	M5 x 7	27.6	7.5	5.5	12	B-M6F	6
S 20SR			66.3		32		46.7					
S 25SC	33	48	59.1	35	—	M6 x 9	34.4	8	6	12	B-M6F	7
S 25SR			83		35		58.3					

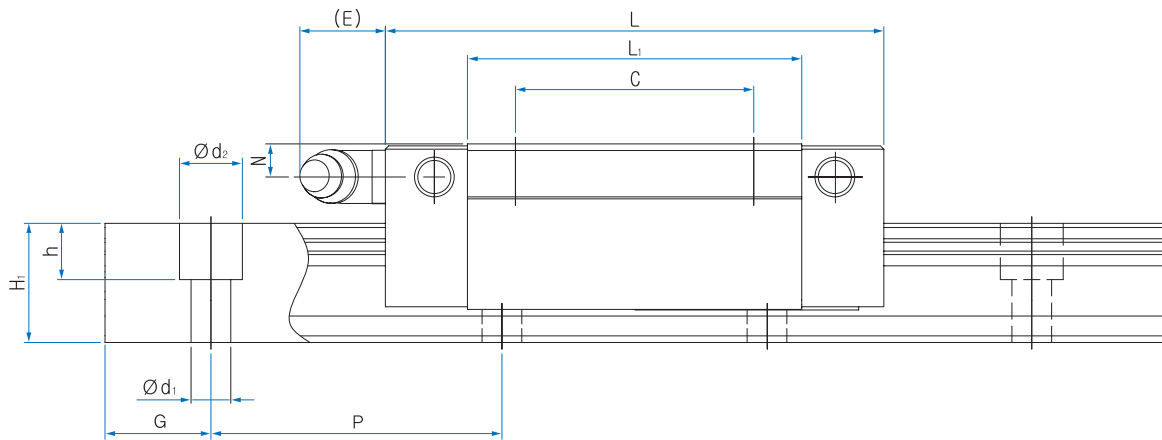
Composition of Model No.



- 1 Model No. of Linear Motion Guide
- 2 Type of block : No symbol—Full-ball type / S—Spacer Chain type
- 3 Form of block : C—Rectangular short type / R—Rectangular standard type / CF—Flange short type / F—Flange standard type
- 4 Type of seal : UU—End seal / SS—End seal + Inside seal / ZZ—End seal + Inside seal + metal scraper
UULF—End seal + LF seal / SSLF—End seal + Inside seal + LF seal / ZZLF—End seal + Inside seal + metal scraper + LF seal (*1)
- 5 Number of blocks combined in 1 rail
- 6 Symbol of clearance : No symbol—Normal preload / G₁—Light preload / G₂—Heavy preload / G_s—Special preload (*2)
- 7 Length of rail
- 8 Size of G value : standard G value has no symbol.
- 9 Symbol of precision : No symbol—Moderate precision / H—High precision / P—Precision / SP—Super Precision / UP—Ultra Precision (*3)
- 10 No symbol—Rail counter bore type (A topside assembly) / A—Rail tap hole type (an underside assembly) (*4)
- 11 Connection symbol
- 12 Special symbol
- 13 Number of axis used on the same surface

(*1) See P77 Symbol List of Optional Parts (*2) See P17 Radial Clearance

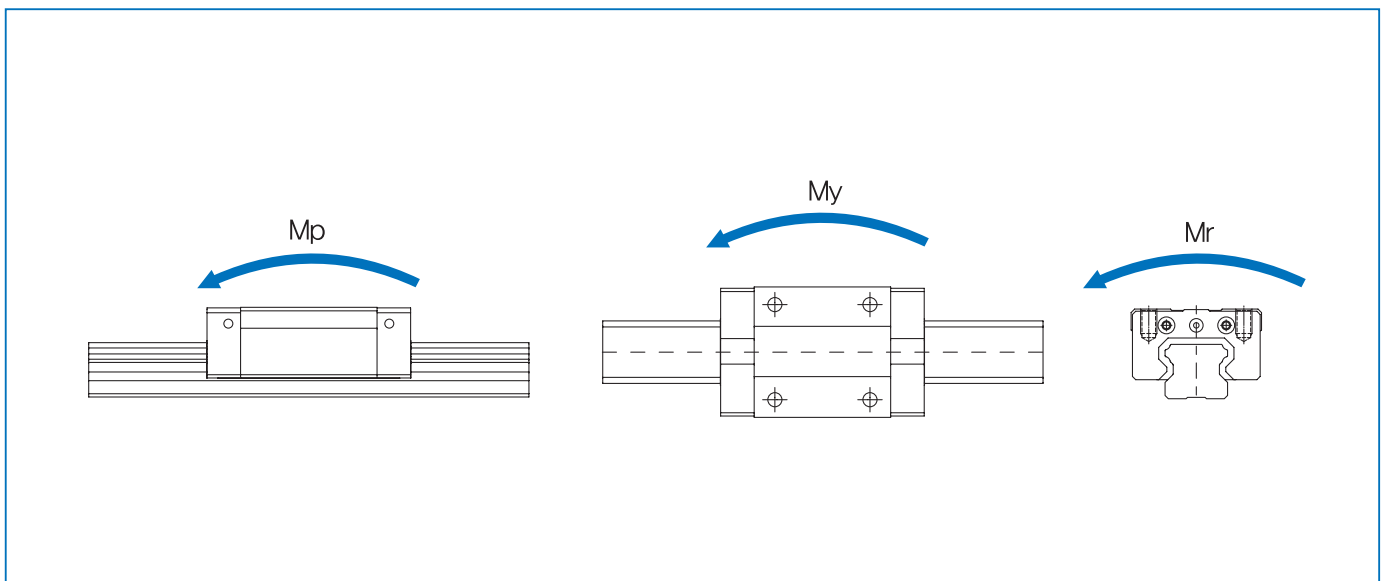
(*3) See P24 Selection of Precision Class (*4) See P59 The reference for standard tap hole type of a rail



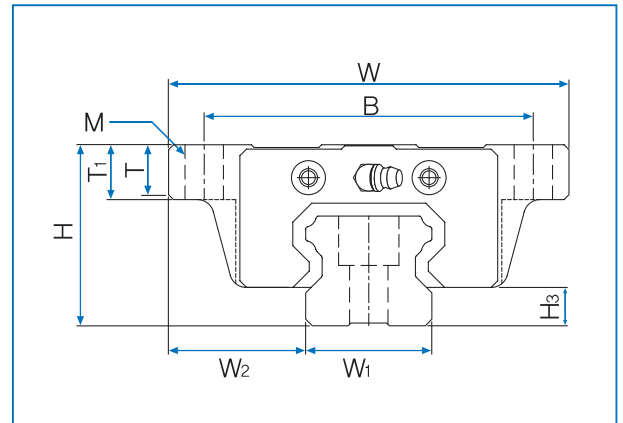
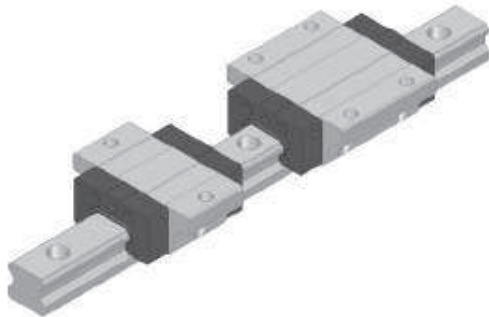
Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN · m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C _o kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(Contact)	1	2(Contact)	1		
15	9.5	13	20	60	4.5x7.5x5.3	8.3	10	0.042	0.224	0.042	0.224	0.079	0.096	1.3
						12.1	16.2	0.115	0.552	0.115	0.552	0.129	0.156	
20	11	16.5	20	60	6x9.5x8.5	11.1	13.1	0.063	0.342	0.063	0.342	0.137	0.153	2.2
						16.1	21.2	0.173	0.838	0.173	0.838	0.223	0.246	
23	12.5	20	20	60	7x11x9	17.9	20.4	0.123	0.670	0.123	0.670	0.246	0.254	3.0
						25.8	33.1	0.337	1.636	0.337	1.636	0.398	0.413	

1N≒0.102kgf

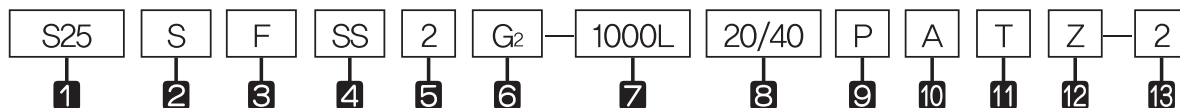


S-SCF Series, S-SF Series



Model No.	External dimensions			Dimensions of block									Grease nipple	H ₃
	Height H	Width W	Length L	B	C	M	L ₁	T	T ₁	N	E			
S 15SCF	24	52	40.2	41	–	M5	24	6	7	6	6	A–M4	4.5	
S 15SF			56.9		26		40.7							
S 20SCF	28	59	47.2	49	–	M6	27.6	8	9	5.5	12	B–M6F	6	
S 20SF			66.3		32		46.7							
S 25SCF	33	73	59.1	60	–	M8	34.4	9	10	6	12	B–M6F	7	
S 25SF			83		35		58.3							

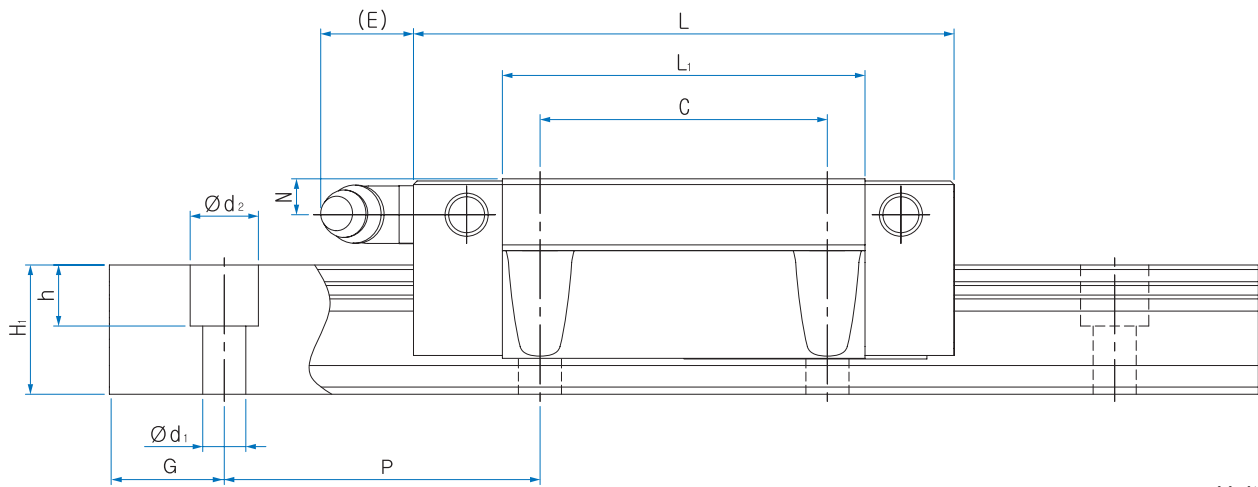
Composition of Model No.



- 1 Model No. of Linear Motion Guide
- 2 Type of block : No symbol–Full-ball type / S–Spacer Chain type
- 3 Form of block : C–Rectangular short type / R–Rectangular standard type / CF–Flange short type / F–Flange standard type
- 4 Type of seal : UU–End seal / SS–End seal + Inside seal / ZZ–End seal + Inside seal + metal scraper
UULF–End seal + LF seal / SSLF– End seal + Inside seal + LF seal / ZZLF - End seal + Inside seal + metal scraper + LF seal (*1)
- 5 Number of blocks combined in 1 rail
- 6 Symbol of clearance : No symbol–Normal preload / G₁–Light preload / G₂–Heavy preload / G_s–Special preload (*2)
- 7 Length of rail
- 8 Size of G value : standard G value has no symbol.
- 9 Symbol of precision : No symbol–Moderate precision / H–High precision / P–Precision / SP–Super Precision / UP–Ultra Precision (*3)
- 10 No symbol–Rail counter bore type (A topside assembly) / A– Rail tap hole type (an underside assembly) (*4)
- 11 Connection symbol
- 12 Special symbol
- 13 Number of axis used on the same surface

(*1) See P77 Symbol List of Optional Parts (*2) See P17 Radial Clearance

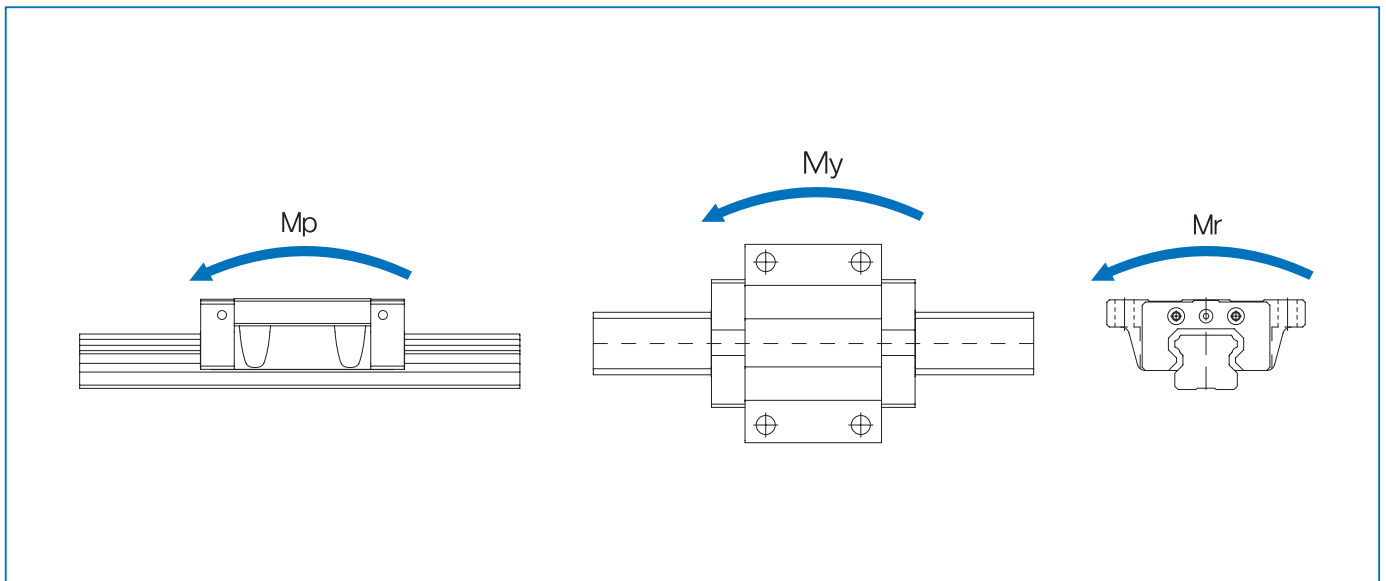
(*3) See P24 Selection of Precision Class (*4) See P59 The reference for standard tap hole type of a rail

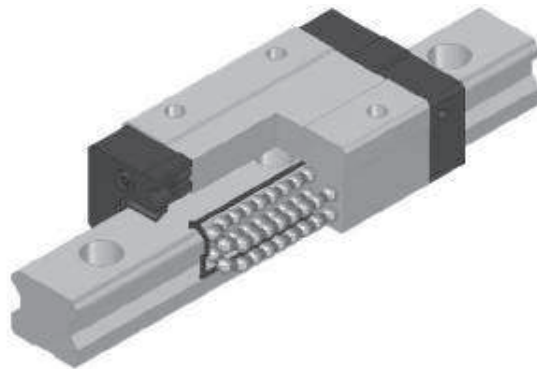


Unit : mm

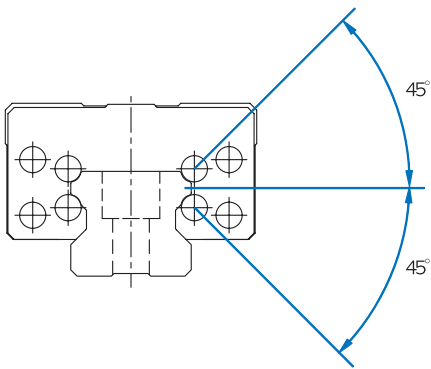
Dimensions of Rail						Basic load rating		Static allowance moment kN · m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C ₀ kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(Contact)	1	2(Contact)	1		
15	9.5	13	20	60	4.5x7.5x5.3	8.3	10	0.042	0.224	0.042	0.224	0.079	0.125	1.3
						12.1	16.2	0.115	0.552	0.115	0.552	0.129	0.203	
20	11	16.5	20	60	6x9.5x8.5	11.1	13.1	0.063	0.342	0.063	0.342	0.137	0.187	2.2
						16.1	21.2	0.173	0.838	0.173	0.838	0.223	0.301	
23	12.5	20	20	60	7x11x9	17.9	20.4	0.123	0.670	0.123	0.670	0.246	0.320	3.0
						25.8	33.1	0.337	1.636	0.337	1.636	0.398	0.527	

1N≒0.102kgf

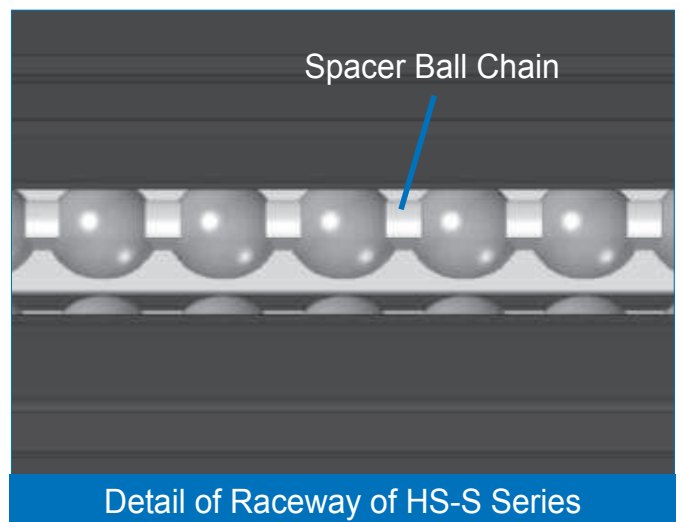




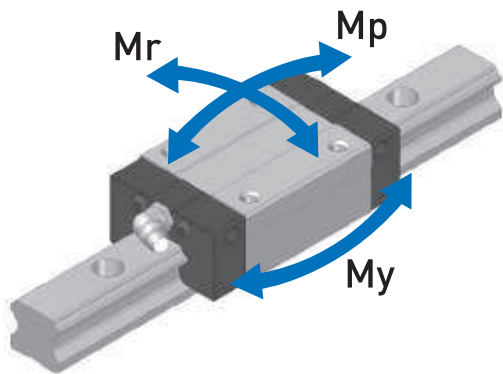
HS-S Series (Spacer Chain Type)



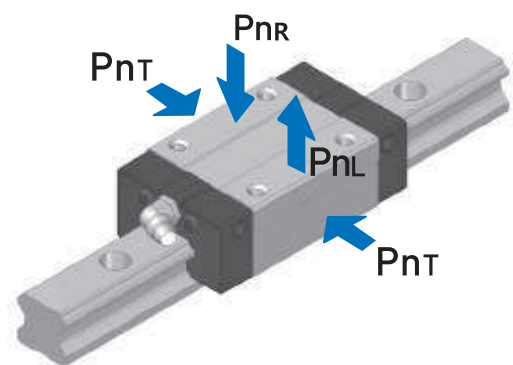
Cross Section



Detail of Raceway of HS-S Series

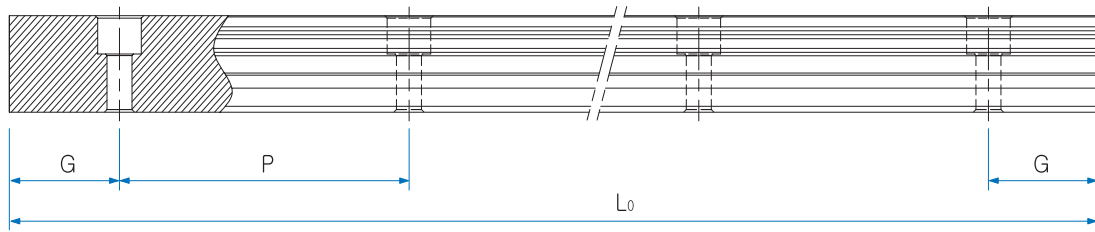


Moment Rigidity



Radial Rigidity

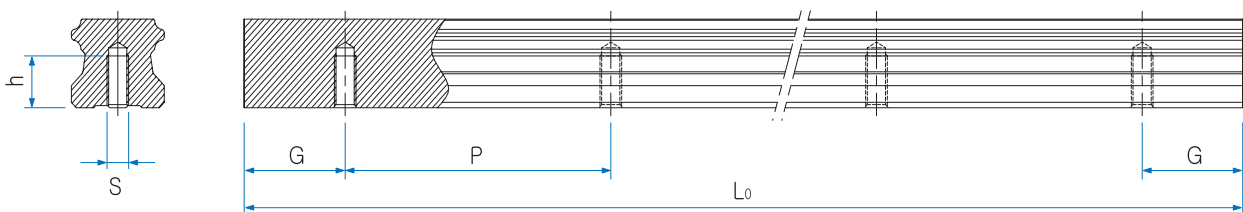
Standard and maximum length of a rail



Unit : mm

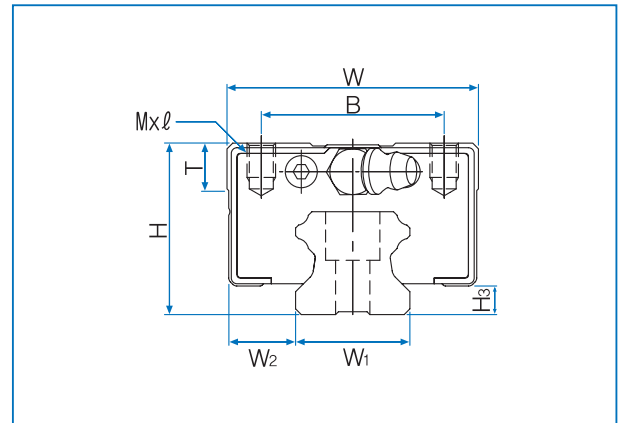
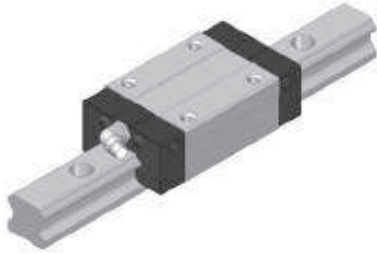
Model No.	HS25	HS30	HS35
Standard length	220	280	440
	340	360	520
	400	440	600
	⋮	520	760
	2200	⋮	⋮
	2320	2520	2680
	2440	2680	2840
		2840	3000
Standard pitch P	60	80	80
G	20	20	20
Max. length	4000		

Standard tap hole type of a rail



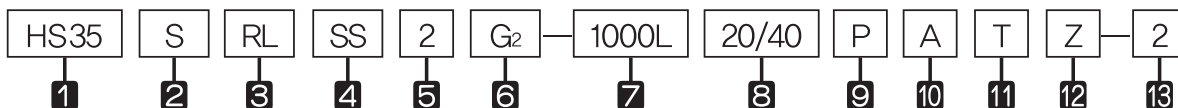
Model No.	S	h(mm)
HS25	M6	12
HS30	M8	15
HS35	M8	17

HS-SR Series, HS-SRL Series



Model No.	External dimensions			Dimensions of block								H ₃
	Height H	Width W	Length L	B	C	M X l	L ₁	T	N	E	Grease nipple	
HS 25SR	36	48	83	35	35	M6x6.5	58.3	8	9	12	B-M6F	7
HS 25SRL			102.9		50		78.2					
HS 30SR	42	60	97.8	40	40	M8x8	70.8	8	7.8	12	B-M6F	7
HS 30SRL			120		60		93					
HS 35SR	48	70	110	50	50	M8x10	80.8	15	10	12	B-M6F	7.5
HS 35SRL			135.4		72		106.2					

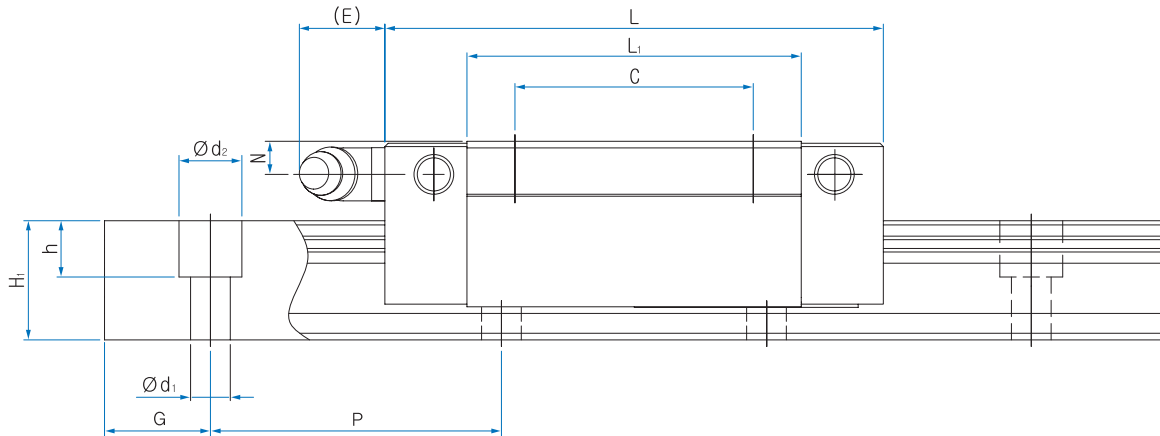
Composition of Model No.



- 1 Model No. of Linear Motion Guide
- 2 Type of block : S–Spacer Chain type
- 3 Form of block : R–Rectangular standard type / RL–Rectangular long type
- 4 Type of seal : UU–End seal / SS–End seal + Inside seal / ZZ–End seal + Inside seal + metal scraper
UULF–End seal + LF seal / SSLF– End seal + Inside seal + LF seal / ZZLF - End seal + Inside seal + metal scraper + LF seal (*1)
- 5 Number of blocks combined in 1 rail
- 6 Symbol of clearance : No symbol–Normal preload / G₁–Light preload / G₂–Heavy preload / G_s–Special preload (*2)
- 7 Length of rail
- 8 Size of G value : standard G value has no symbol.
- 9 Symbol of precision : No symbol–Moderate precision / H–High precision / P–Precision / SP–Super Precision / UP–Ultra Precision (*3)
- 10 No symbol–Rail counter bore type (A topside assembly) / A– Rail tap hole type (an underside assembly) (*4)
- 11 Connection symbol
- 12 Special symbol
- 13 Number of axis used on the same surface

(*1) See P77 Symbol List of Optional Parts (*2) See P17 Radial Clearance

(*3) See P24 Selection of Precision Class (*4) See P69 The reference for standard tap hole type of a rail



Unit : mm

Dimensions of Rail						Basic load rating		Static allowance moment kN · m					Mass	
Width W ₁ ±0.05	W ₂	Heigh H ₁	Value G	Pitch P	d ₁ x d ₂ x h	C kN	C ₀ kN	M _p		M _y		M _r	Block kg	Rail kg/m
								1	2(Contact)	1	2(Contact)	1		
23	12.5	20	20	60	7x11x9	25.8	33.1	0.337	1.636	0.337	1.636	0.398	0.53	3.0
						31.7	43.6	0.596	2.760	0.596	2.760	0.525	0.71	
28	16	25.1	20	80	9x14x14.1	48.0	57.1	0.711	3.384	0.711	3.384	0.828	0.9	4.85
						58.0	73.6	1.203	5.506	1.203	5.506	1.067	1.1	
34	18	27	20	80	9x14x13	63.7	74.6	1.062	5.012	1.062	5.012	1.298	1.5	6.58
						77.1	96.2	1.797	8.172	1.797	8.172	1.674	2.01	

1N≒0.102kgf

